11.9

Convergence of Taylor Series; Error Estimates

This section addresses the two questions left unanswered by Section 11.8:

- 1. When does a Taylor series converge to its generating function?
- **2.** How accurately do a function's Taylor polynomials approximate the function on a given interval?

Taylor's Theorem

We answer these questions with the following theorem.

THEOREM 22 Taylor's Theorem

If f and its first n derivatives f', f'', ..., $f^{(n)}$ are continuous on the closed interval between a and b, and $f^{(n)}$ is differentiable on the open interval between a and b, then there exists a number c between a and b such that

$$f(b) = f(a) + f'(a)(b - a) + \frac{f''(a)}{2!}(b - a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(b - a)^n + \frac{f^{(n+1)}(c)}{(n+1)!}(b - a)^{n+1}.$$

Taylor's Theorem is a generalization of the Mean Value Theorem (Exercise 39). There is a proof of Taylor's Theorem at the end of this section.

When we apply Taylor's Theorem, we usually want to hold a fixed and treat b as an independent variable. Taylor's formula is easier to use in circumstances like these if we change b to x. Here is a version of the theorem with this change.

Taylor's Formula

If f has derivatives of all orders in an open interval I containing a, then for each positive integer n and for each x in I,

$$f(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \cdots + \frac{f^{(n)}(a)}{n!}(x - a)^n + R_n(x),$$
(1)

where

$$R_n(x) = \frac{f^{(n+1)}(c)}{(n+1)!} (x-a)^{n+1}$$
 for some c between a and x. (2)

When we state Taylor's theorem this way, it says that for each $x \in I$,

$$f(x) = P_n(x) + R_n(x).$$

The function $R_n(x)$ is determined by the value of the (n + 1)st derivative $f^{(n+1)}$ at a point c that depends on both a and x, and which lies somewhere between them. For any value of n we want, the equation gives both a polynomial approximation of f of that order and a formula for the error involved in using that approximation over the interval I.

Equation (1) is called **Taylor's formula**. The function $R_n(x)$ is called the **remainder of order** n or the **error term** for the approximation of f by $P_n(x)$ over I. If $R_n(x) \to 0$ as $n \to \infty$ for all $x \in I$, we say that the Taylor series generated by f at x = a **converges** to f on I, and we write

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x - a)^k.$$

Often we can estimate R_n without knowing the value of c, as the following example illustrates.

EXAMPLE 1 The Taylor Series for e^x Revisited

Show that the Taylor series generated by $f(x) = e^x$ at x = 0 converges to f(x) for every real value of x.

Solution The function has derivatives of all orders throughout the interval $I = (-\infty, \infty)$. Equations (1) and (2) with $f(x) = e^x$ and a = 0 give

$$e^x = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^n}{n!} + R_n(x)$$
 Polynomial from Section 11.8, Example 2

and

$$R_n(x) = \frac{e^c}{(n+1)!} x^{n+1}$$
 for some c between 0 and x.

Since e^x is an increasing function of x, e^c lies between $e^0 = 1$ and e^x . When x is negative, so is c, and $e^c < 1$. When x is zero, $e^x = 1$ and $R_n(x) = 0$. When x is positive, so is c, and $e^c < e^x$. Thus,

$$|R_n(x)| \le \frac{|x|^{n+1}}{(n+1)!}$$
 when $x \le 0$,

and

$$|R_n(x)| < e^x \frac{x^{n+1}}{(n+1)!}$$
 when $x > 0$.

Finally, because

$$\lim_{n \to \infty} \frac{x^{n+1}}{(n+1)!} = 0 \qquad \text{for every } x, \qquad \text{Section 11.1}$$

 $\lim_{n\to\infty} R_n(x) = 0$, and the series converges to e^x for every x. Thus,

$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!} = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^k}{k!} + \dots$$
 (3)

Estimating the Remainder

It is often possible to estimate $R_n(x)$ as we did in Example 1. This method of estimation is so convenient that we state it as a theorem for future reference.

THEOREM 23 The Remainder Estimation Theorem

If there is a positive constant M such that $|f^{(n+1)}(t)| \le M$ for all t between x and a, inclusive, then the remainder term $R_n(x)$ in Taylor's Theorem satisfies the inequality

$$|R_n(x)| \le M \frac{|x-a|^{n+1}}{(n+1)!}.$$

If this condition holds for every n and the other conditions of Taylor's Theorem are satisfied by f, then the series converges to f(x).

814

We are now ready to look at some examples of how the Remainder Estimation Theorem and Taylor's Theorem can be used together to settle questions of convergence. As you will see, they can also be used to determine the accuracy with which a function is approximated by one of its Taylor polynomials.

EXAMPLE 2 The Taylor Series for $\sin x$ at x = 0

Show that the Taylor series for $\sin x$ at x = 0 converges for all x.

Solution The function and its derivatives are

$$f(x) = \sin x,$$
 $f'(x) = \cos x,$
 $f''(x) = -\sin x,$ $f'''(x) = -\cos x,$
 \vdots \vdots

$$f^{(2k)}(x) = (-1)^k \sin x,$$
 $f^{(2k+1)}(x) = (-1)^k \cos x,$

so

$$f^{(2k)}(0) = 0$$
 and $f^{(2k+1)}(0) = (-1)^k$.

The series has only odd-powered terms and, for n = 2k + 1, Taylor's Theorem gives

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + \frac{(-1)^k x^{2k+1}}{(2k+1)!} + R_{2k+1}(x).$$

All the derivatives of $\sin x$ have absolute values less than or equal to 1, so we can apply the Remainder Estimation Theorem with M=1 to obtain

$$|R_{2k+1}(x)| \le 1 \cdot \frac{|x|^{2k+2}}{(2k+2)!}.$$

Since $(|x|^{2k+2}/(2k+2)!) \to 0$ as $k \to \infty$, whatever the value of x, $R_{2k+1}(x) \to 0$, and the Maclaurin series for $\sin x$ converges to $\sin x$ for every x. Thus,

$$\sin x = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k+1}}{(2k+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots.$$
 (4)

EXAMPLE 3 The Taylor Series for $\cos x$ at x = 0 Revisited

Show that the Taylor series for $\cos x$ at x = 0 converges to $\cos x$ for every value of x.

Solution We add the remainder term to the Taylor polynomial for $\cos x$ (Section 11.8, Example 3) to obtain Taylor's formula for $\cos x$ with n = 2k:

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^k \frac{x^{2k}}{(2k)!} + R_{2k}(x).$$

Because the derivatives of the cosine have absolute value less than or equal to 1, the Remainder Estimation Theorem with M=1 gives

$$|R_{2k}(x)| \le 1 \cdot \frac{|x|^{2k+1}}{(2k+1)!}.$$

For every value of x, $R_{2k} \to 0$ as $k \to \infty$. Therefore, the series converges to $\cos x$ for every value of x. Thus,

$$\cos x = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k}}{(2k)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots.$$
 (5)

EXAMPLE 4 Finding a Taylor Series by Substitution

Find the Taylor series for $\cos 2x$ at x = 0.

Solution We can find the Taylor series for $\cos 2x$ by substituting 2x for x in the Taylor series for $\cos x$:

$$\cos 2x = \sum_{k=0}^{\infty} \frac{(-1)^k (2x)^{2k}}{(2k)!} = 1 - \frac{(2x)^2}{2!} + \frac{(2x)^4}{4!} - \frac{(2x)^6}{6!} + \cdots$$

$$= 1 - \frac{2^2 x^2}{2!} + \frac{2^4 x^4}{4!} - \frac{2^6 x^6}{6!} + \cdots$$

$$= \sum_{k=0}^{\infty} (-1)^k \frac{2^{2k} x^{2k}}{(2k)!}.$$
Equation (5) with 2x for x

Equation (5) holds for $-\infty < x < \infty$, implying that it holds for $-\infty < 2x < \infty$, so the newly created series converges for all x. Exercise 45 explains why the series is in fact the Taylor series for $\cos 2x$.

EXAMPLE 5 Finding a Taylor Series by Multiplication

Find the Taylor series for $x \sin x$ at x = 0.

Solution We can find the Taylor series for $x \sin x$ by multiplying the Taylor series for $\sin x$ (Equation 4) by x:

$$x \sin x = x \left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \cdots \right)$$
$$= x^2 - \frac{x^4}{3!} + \frac{x^6}{5!} - \frac{x^8}{7!} + \cdots$$

The new series converges for all x because the series for $\sin x$ converges for all x. Exercise 45 explains why the series is the Taylor series for $x \sin x$.

Truncation Error

The Taylor series for e^x at x = 0 converges to e^x for all x. But we still need to decide how many terms to use to approximate e^x to a given degree of accuracy. We get this information from the Remainder Estimation Theorem.

EXAMPLE 6 Calculate e with an error of less than 10^{-6} .

Solution We can use the result of Example 1 with x = 1 to write

$$e = 1 + 1 + \frac{1}{2!} + \cdots + \frac{1}{n!} + R_n(1),$$

with

$$R_n(1) = e^c \frac{1}{(n+1)!}$$
 for some c between 0 and 1.

For the purposes of this example, we assume that we know that e < 3. Hence, we are certain that

$$\frac{1}{(n+1)!} < R_n(1) < \frac{3}{(n+1)!}$$

because $1 < e^c < 3$ for 0 < c < 1.

By experiment we find that $1/9! > 10^{-6}$, while $3/10! < 10^{-6}$. Thus we should take (n + 1) to be at least 10, or n to be at least 9. With an error of less than 10^{-6} ,

$$e = 1 + 1 + \frac{1}{2} + \frac{1}{3!} + \dots + \frac{1}{9!} \approx 2.718282.$$

EXAMPLE 7 For what values of x can we replace $\sin x$ by $x - (x^3/3!)$ with an error of magnitude no greater than 3×10^{-4} ?

Solution Here we can take advantage of the fact that the Taylor series for $\sin x$ is an alternating series for every nonzero value of x. According to the Alternating Series Estimation Theorem (Section 11.6), the error in truncating

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

after $(x^3/3!)$ is no greater than

$$\left|\frac{x^5}{5!}\right| = \frac{|x|^5}{120}.$$

Therefore the error will be less than or equal to 3×10^{-4} if

$$\frac{|x|^5}{120} < 3 \times 10^{-4}$$
 or $|x| < \sqrt[5]{360 \times 10^{-4}} \approx 0.514$. Rounded down, to be safe

The Alternating Series Estimation Theorem tells us something that the Remainder Estimation Theorem does not: namely, that the estimate $x - (x^3/3!)$ for $\sin x$ is an underestimate when x is positive because then $x^5/120$ is positive.

Figure 11.15 shows the graph of $\sin x$, along with the graphs of a number of its approximating Taylor polynomials. The graph of $P_3(x) = x - (x^3/3!)$ is almost indistinguishable from the sine curve when $-1 \le x \le 1$.

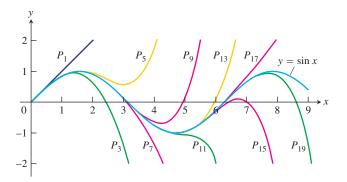


FIGURE 11.15 The polynomials

$$P_{2n+1}(x) = \sum_{k=0}^{n} \frac{(-1)^k x^{2k+1}}{(2k+1)!}$$

converge to $\sin x$ as $n \to \infty$. Notice how closely $P_3(x)$ approximates the sine curve for x < 1 (Example 7).

You might wonder how the estimate given by the Remainder Estimation Theorem compares with the one just obtained from the Alternating Series Estimation Theorem. If we write

$$\sin x = x - \frac{x^3}{3!} + R_3,$$

then the Remainder Estimation Theorem gives

$$|R_3| \le 1 \cdot \frac{|x|^4}{4!} = \frac{|x|^4}{24},$$

which is not as good. But if we recognize that $x - (x^3/3!) = 0 + x + 0x^2 - (x^3/3!) + 0x^4$ is the Taylor polynomial of order 4 as well as of order 3, then

$$\sin x = x - \frac{x^3}{3!} + 0 + R_4,$$

and the Remainder Estimation Theorem with M = 1 gives

$$|R_4| \le 1 \cdot \frac{|x|^5}{5!} = \frac{|x|^5}{120}.$$

This is what we had from the Alternating Series Estimation Theorem.

Combining Taylor Series

On the intersection of their intervals of convergence, Taylor series can be added, subtracted, and multiplied by constants, and the results are once again Taylor series. The Taylor series for f(x) + g(x) is the sum of the Taylor series for f(x) and g(x) because the *n*th derivative of f + g is $f^{(n)} + g^{(n)}$, and so on. Thus we obtain the Taylor series for $(1 + \cos 2x)/2$ by adding 1 to the Taylor series for $\cos 2x$ and dividing the combined results by 2, and the Taylor series for $\sin x + \cos x$ is the term-by-term sum of the Taylor series for $\sin x$ and $\cos x$.

Euler's Identity

As you may recall, a complex number is a number of the form a+bi, where a and b are real numbers and $i=\sqrt{-1}$. If we substitute $x=i\theta$ (θ real) in the Taylor series for e^x and use the relations

$$i^2 = -1$$
, $i^3 = i^2i = -i$, $i^4 = i^2i^2 = 1$, $i^5 = i^4i = i$,

and so on, to simplify the result, we obtain

$$e^{i\theta} = 1 + \frac{i\theta}{1!} + \frac{i^2\theta^2}{2!} + \frac{i^3\theta^3}{3!} + \frac{i^4\theta^4}{4!} + \frac{i^5\theta^5}{5!} + \frac{i^6\theta^6}{6!} + \cdots$$

$$= \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \cdots\right) + i\left(\theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \cdots\right) = \cos\theta + i\sin\theta.$$

This does not *prove* that $e^{i\theta} = \cos \theta + i \sin \theta$ because we have not yet defined what it means to raise e to an imaginary power. Rather, it says how to define $e^{i\theta}$ to be consistent with other things we know.

DEFINITION

For any real number
$$\theta$$
, $e^{i\theta} = \cos \theta + i \sin \theta$. (6)

Equation (6), called **Euler's identity**, enables us to define e^{a+bi} to be $e^a \cdot e^{bi}$ for any complex number a + bi. One consequence of the identity is the equation

$$e^{i\pi} = -1$$
.

When written in the form $e^{i\pi} + 1 = 0$, this equation combines five of the most important constants in mathematics.

A Proof of Taylor's Theorem

We prove Taylor's theorem assuming a < b. The proof for a > b is nearly the same. The Taylor polynomial

$$P_n(x) = f(a) + f'(a)(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x - a)^n$$

and its first n derivatives match the function f and its first n derivatives at x = a. We do not disturb that matching if we add another term of the form $K(x - a)^{n+1}$, where K is any constant, because such a term and its first n derivatives are all equal to zero at x = a. The new function

$$\phi_n(x) = P_n(x) + K(x - a)^{n+1}$$

and its first n derivatives still agree with f and its first n derivatives at x = a.

We now choose the particular value of K that makes the curve $y = \phi_n(x)$ agree with the original curve y = f(x) at x = b. In symbols,

$$f(b) = P_n(b) + K(b-a)^{n+1}, \quad \text{or} \quad K = \frac{f(b) - P_n(b)}{(b-a)^{n+1}}.$$
 (7)

With K defined by Equation (7), the function

$$F(x) = f(x) - \phi_n(x)$$

measures the difference between the original function f and the approximating function ϕ_n for each x in [a, b].

We now use Rolle's Theorem (Section 4.2). First, because F(a) = F(b) = 0 and both F and F' are continuous on [a, b], we know that

$$F'(c_1) = 0$$
 for some c_1 in (a, b) .

Next, because $F'(a) = F'(c_1) = 0$ and both F' and F'' are continuous on $[a, c_1]$, we know that

$$F''(c_2) = 0$$
 for some c_2 in (a, c_1) .

Rolle's Theorem, applied successively to $F'', F''', \dots, F^{(n-1)}$ implies the existence of

$$c_3$$
 in (a, c_2) such that $F'''(c_3) = 0$,
 c_4 in (a, c_3) such that $F^{(4)}(c_4) = 0$,
 \vdots
 c_n in (a, c_{n-1}) such that $F^{(n)}(c_n) = 0$.

Finally, because $F^{(n)}$ is continuous on $[a, c_n]$ and differentiable on (a, c_n) , and $F^{(n)}(a) = F^{(n)}(c_n) = 0$, Rolle's Theorem implies that there is a number c_{n+1} in (a, c_n) such that

$$F^{(n+1)}(c_{n+1}) = 0. (8)$$

If we differentiate $F(x) = f(x) - P_n(x) - K(x-a)^{n+1}$ a total of n+1 times, we get

$$F^{(n+1)}(x) = f^{(n+1)}(x) - 0 - (n+1)!K.$$
(9)

Equations (8) and (9) together give

$$K = \frac{f^{(n+1)}(c)}{(n+1)!} \quad \text{for some number } c = c_{n+1} \text{ in } (a,b).$$
 (10)

Equations (7) and (10) give

$$f(b) = P_n(b) + \frac{f^{(n+1)}(c)}{(n+1)!}(b-a)^{n+1}.$$

This concludes the proof.