# **Chapter 13 Additional and Advanced Exercises**

## **Applications**

**1.** A straight river is 100 m wide. A rowboat leaves the far shore at time  $t = 0$ . The person in the boat rows at a rate of 20 m/min, always toward the near shore. The velocity of the river at  $(x, y)$  is

$$
\mathbf{v} = \left(-\frac{1}{250}(y - 50)^2 + 10\right) \mathbf{i} \, \text{m/min}, \quad 0 < y < 100.
$$

- **a.** Given that  $\mathbf{r}(0) = 0\mathbf{i} + 100\mathbf{j}$ , what is the position of the boat at time *t*?
- **b.** How far downstream will the boat land on the near shore?



**2.** A straight river is 20 m wide. The velocity of the river at  $(x, y)$  is

$$
\mathbf{v} = -\frac{3x(20-x)}{100} \mathbf{j} \text{ m/min}, \quad 0 \le x \le 20.
$$

A boat leaves the shore at (0, 0) and travels through the water with a constant velocity. It arrives at the opposite shore at (20, 0). The speed of the boat is always  $\sqrt{20}$  m/min.



- **a.** Find the velocity of the boat.
- **b.** Find the location of the boat at time *t*.
- **c.** Sketch the path of the boat.

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**3.** A frictionless particle *P*, starting from rest at time  $t = 0$  at the point (*a*, 0, 0), slides down the helix

$$
\mathbf{r}(\theta) = (a\cos\theta)\mathbf{i} + (a\sin\theta)\mathbf{j} + b\theta\mathbf{k} \quad (a, b > 0)
$$

under the influence of gravity, as in the accompanying figure. The  $\theta$  in this equation is the cylindrical coordinate  $\theta$  and the helix is the curve  $r = a$ ,  $z = b\theta$ ,  $\theta \ge 0$ , in cylindrical coordinates. We assume  $\theta$  to be a differentiable function of  $t$  for the motion. The law of conservation of energy tells us that the particle's speed after it has fallen straight down a distance *z* is  $\sqrt{2gz}$ , where *g* is the constant acceleration of gravity.

- **a.** Find the angular velocity  $d\theta/dt$  when  $\theta = 2\pi$ .
- **b.** Express the particle's  $\theta$  and *z*-coordinates as functions of *t*.
- **c.** Express the tangential and normal components of the velocity  $d\mathbf{r}/dt$  and acceleration  $d^2\mathbf{r}/dt^2$  as functions of *t*. Does the acceleration have any nonzero component in the direction of the binormal vector **B**?



- **4.** Suppose the curve in Exercise 3 is replaced by the conical helix  $r = a\theta$ ,  $z = b\theta$  shown in the accompanying figure.
	- **a.** Express the angular velocity  $d\theta/dt$  as a function of  $\theta$ .
	- **b.** Express the distance the particle travels along the helix as a function of  $\theta$ .



### **Polar Coordinate Systems and Motion in Space**

**5.** Deduce from the orbit equation

**T**

$$
r = \frac{(1+e)r_0}{1+e\cos\theta}
$$

that a planet is closest to its sun when  $\theta = 0$  and show that  $r = r_0$ at that time.

**6. A Kepler equation** The problem of locating a planet in its orbit at a given time and date eventually leads to solving "Kepler" equations of the form

$$
f(x) = x - 1 - \frac{1}{2}\sin x = 0.
$$

- **a.** Show that this particular equation has a solution between  $x = 0$  and  $x = 2$ .
- **b.** With your computer or calculator in radian mode, use Newton's method to find the solution to as many places as you can.
- **7.** In Section 13.6, we found the velocity of a particle moving in the plane to be

$$
\mathbf{v} = \dot{x} \mathbf{i} + \dot{y} \mathbf{j} = \dot{r} \mathbf{u}_r + r \dot{\theta} \mathbf{u}_\theta.
$$

- **a.** Express  $\dot{x}$  and  $\dot{y}$  in terms of  $\dot{r}$  and  $r\dot{\theta}$  by evaluating the dot  $\text{Express } x \text{ and } y \text{ in } \text{teri}$ <br>products  $\mathbf{v} \cdot \mathbf{i}$  and  $\mathbf{v} \cdot \mathbf{j}$ . #
- **b.** Express  $\dot{r}$  and  $r\dot{\theta}$  in terms of  $\dot{x}$  and  $\dot{y}$  by evaluating the dot Express *r* and *r*  $\theta$  in terms<br>products  $\mathbf{v} \cdot \mathbf{u}_r$  and  $\mathbf{v} \cdot \mathbf{u}_\theta$ . #
- **8.** Express the curvature of a twice-differentiable curve  $r = f(\theta)$  in the polar coordinate plane in terms of *ƒ* and its derivatives.
- **9.** A slender rod through the origin of the polar coordinate plane rotates (in the plane) about the origin at the rate of  $3 \text{ rad/min}$ . A beetle starting from the point (2, 0) crawls along the rod toward the origin at the rate of  $1$  in./min.
	- **a.** Find the beetle's acceleration and velocity in polar form when it is halfway to (1 in. from) the origin.
- **b.** To the nearest tenth of an inch, what will be the length of the path the beetle has traveled by the time it reaches the origin?
- **10. Conservation of angular momentum** Let **r**(*t*) denote the position in space of a moving object at time *t*. Suppose the force acting on the object at time *t* is

$$
\mathbf{F}(t) = -\frac{c}{|\mathbf{r}(t)|^3} \mathbf{r}(t),
$$

where *c* is a constant. In physics the **angular momentum** of an object at time *t* is defined to be  $L(t) = r(t) \times mv(t)$ , where *m* is the mass of the object and  $\mathbf{v}(t)$  is the velocity. Prove that angular momentum is a conserved quantity; i.e., prove that **L**(*t*) is a constant vector, independent of time. Remember Newton's law  $\mathbf{F} = m\mathbf{a}$ . (This is a calculus problem, not a physics problem.)

### **Cylindrical Coordinate Systems**

**11. Unit vectors for position and motion in cylindrical coordinates** When the position of a particle moving in space is given in cylindrical coordinates, the unit vectors we use to describe its position and motion are

$$
\mathbf{u}_r = (\cos \theta)\mathbf{i} + (\sin \theta)\mathbf{j}, \qquad \mathbf{u}_\theta = -(\sin \theta)\mathbf{i} + (\cos \theta)\mathbf{j},
$$

and **k** (see accompanying figure). The particle's position vector is then  $\mathbf{r} = r \mathbf{u}_r + z \mathbf{k}$ , where *r* is the positive polar distance coordinate of the particle's position.



- **a.** Show that  $\mathbf{u}_r$ ,  $\mathbf{u}_\theta$ , and **k**, in this order, form a right-handed frame of unit vectors.
- **b.** Show that

$$
\frac{d\mathbf{u}_r}{d\theta} = \mathbf{u}_\theta \quad \text{and} \quad \frac{d\mathbf{u}_\theta}{d\theta} = -\mathbf{u}_r.
$$

**c.** Assuming that the necessary derivatives with respect to *t* Assuming that the necessary derivatives with respect to *t* exist, express  $\mathbf{v} = \dot{\mathbf{r}}$  and  $\mathbf{a} = \ddot{\mathbf{r}}$  in terms of  $\mathbf{u}_r$ ,  $\mathbf{u}_\theta$ ,  $\mathbf{k}$ ,  $\dot{r}$ , and  $\dot{\theta}$ . (The dots indicate derivatives with respect to  $t$ :  $\dot{\mathbf{r}}$  means (The dots indicate derivatives with respect to *t*: **r** means  $d\mathbf{r}/dt$ , **r** means  $d^2\mathbf{r}/dt^2$ , and so on.) Section 13.6 derives these formulas and shows how the vectors mentioned here are used in describing planetary motion. #

#### **12. Arc length in cylindrical coordinates**

- **a.** Show that when you express  $ds^2 = dx^2 + dy^2 + dz^2$  in terms of cylindrical coordinates, you get  $ds^2 = dr^2 +$  $r^2 d\theta^2 + dz^2$ .
- **b.** Interpret this result geometrically in terms of the edges and a diagonal of a box. Sketch the box.
- **c.** Use the result in part (a) to find the length of the curve  $r = e^{\theta}, z = e^{\theta}, 0 \le \theta \le \theta \ln 8.$