Grammar Systems and Distributed Automata

With the need to solve different problems within a short time in an efficient manner, parallel and distributed computing have become essential. Study of such computations in the abstract sense, from the formal-language theory point of view, started with the development of grammar systems. In classical formal-language theory, a language is generated by a single grammar or accepted by a single automation. They model a single processor or we can say the devices are centralized. Though multi tape Turing machines (TMs) try to introduce parallelism in a small way, the finite control of the machine is only one.

The introduction of distributed computing useful in analyzing computation in computer networks, distributed databases etc., has led to the notions such as distributed parallelism, concurrency, and communication. The theory of grammar systems and the distributed automata are formal models for distributed computing, where these notions could be formally defined and analyzed.

CD Grammar Systems

Definition

A CD grammar system of degree $n \ge 1$, is a construct.:

$$GS = (N, T, S, P_1, \dots, P_n)$$

Where N and T are disjoint alphabets (non terminals and terminals);

 $S \in N$ is the start symbol and P_1, \dots, P_n are the finite sets of rewriting rules over $N \cup T$, P_1, \dots, P_n are called components of the system.

Another way of specifying a CD grammar system is:

$$GS = (N, T, S, G_1, ..., G_n)$$

where $G_i = (N, T, P_i, S), 1 \le i \le n$.

Definition

Let $GS = (N, T, S, P_1, \dots, P_n)$ be a CD grammar system. We now define different protocols of co-operation.

1. Normal mode (* mod e): \Rightarrow is defined by $, x \Rightarrow y$ without any restriction.

The student works on the blackboard as long as he wants.

2. Terminating mode $(t \mod e)$: for each $i \in \{1, ..., n\}$, the terminating derivation by the ith component, denoted by $\Rightarrow_{P_i}^t$, is defined by $x \Rightarrow_{P_i}^t y$ if and only if $x \Rightarrow_{P_i}^* y$ and there is no $z \in (N \cup T)^*$ with $z \in \mathbb{R}$.

3. = k mode: For each $i \in \{1, ..., n\}$ the k-steps derivation by the ith component, denoted by $\Longrightarrow_{P_i}^{=k}$, is defined by $x \Longrightarrow_{P_i}^{=k} y$ if and only if there are $x_1, ..., x_{k+1} \in (N \cup T)^*$ such that $x = x_i, y = x_{k+1}$ and for each $j, 1 \le j \le k$

$$X_j \Longrightarrow_{P_i} X_{j+1}$$
.

4. \leq k mode: For each component P_i , the \leq k – steps derivation by the ith component denoted by \Rightarrow_{P} , is defined by:

$$x \stackrel{\leq k}{\Longrightarrow} y \text{ if and only if } x \stackrel{=k'}{\Longrightarrow} y \text{ for some } k' \leq k.$$

5. \geq k mode: The \geq k steps of derivation by the ith component, denoted as $\Rightarrow_{P_i}^{\geq k}$, is defined by

 $x \underset{P_i}{\Longrightarrow} y \ if \ and \ only \ if \ x \underset{P_i}{\Longrightarrow} y \ for \ some \ k' \ge k.$

Let $D = \{*, t\} \cup \{\le k, \ge k, =k \mid k \ge 1\}.$

Definition

The language generated by a CD grammar system

$$GS = (N, T, S, P_1, \dots, P_n)$$
 in derivation mode $f \in D$ is:

$$L_{f}(GS) = \begin{cases} W \in T^{*} \mid S \underset{P_{i_{1}}}{\Longrightarrow} \alpha_{1} \underset{P_{i_{2}}}{\Longrightarrow} \alpha_{2} \dots \underset{P_{i_{m}}}{\Longrightarrow} \alpha_{m} = w, m \geq 1, \\ 1 \leq i_{j} \leq n, 1 \leq j \leq m \end{cases}$$

Example

1. Consider the following CD grammar system:

$$GS_{1} = \left(\left\{S, X, X', Y, Y'\right\}, \left\{a, b, c\right\}, S, P_{1}, P_{2}\right),$$

$$P_{1} = \left\{S \to S, S \to XY, X' \to X, Y' \to Y\right\}$$

$$P_{2} = \left\{X \to aX', Y \to bY'c, X \to a, Y \to bc\right\}$$

If f = * mode, the first component derives $S \Rightarrow XY$ the second component derives from Y,bY'c, it can switch to first component or derive aX' from X.

In the first component X' can be changed to X or Y' can be changed to Y or both. The derivation proceeds similarly.

It is not difficult to see that the language generated is

$$\{a^mb^nc^n \setminus m, n \geq 1\}.$$

The same will be true for

 $t \mod e$,=1 $\mod e$, $\geq 1 \mod e$, $\leq k \mod e$ for $k \geq 1$.

But, if we consider = 2 mode, each component should execute two steps. In the first component $S \Rightarrow S \Rightarrow XY$. In the second component, $XY \Rightarrow aX'Y \Rightarrow aX'bY'c$.

Then control goes back to component one where X' and Y' are changed to X and Y in two steps. The derivation proceeds in the similar manner.

It is easy to see that the language generated by GS_1 in the = 2 mode is $\{a^nb^nc^n \mid n \ge 1\}$. A similar argument holds for ≥ 2 – mode also and the language generated is the same.

At most, two steps of derivation can be done in each component. Hence, in the case of = k or $\ge k$ mode where $k \ge 3$, the language generated is the empty set.

2.
$$GS_2 = (\{S, A\}, \{a\}, S, P_1, P_2, P_3)$$

 $P_1 = \{S \rightarrow AA\}$
 $P_2 = \{A \rightarrow S\}$
 $P_3 = \{A \rightarrow a\}$

In the * mode $\{a^n \mid n \ge 2\}$ is generated as the control can switch from component to component at any time.

A similar results holds for $\geq 1, \leq k (k \geq 1)$ modes. For = 1, = k, $\geq k (k \geq 2)$, the language generate is empty as $S \to AA$ can be used only once in P_1 and $A \to a$ can be used once in P_3 .

In the t mode in P_1 , $S \Rightarrow AA$ and if the control goes to P_3 from AA, aa is derived. If the control goes to P_2 from AA, SS is derived. Now the control has to go to P_1 to proceed with the derivation

 $SS \Rightarrow AAAA$, and if the control goes to P_2 , S^4 is derived; if it goes to P_3 , a^4 is derived. It is easy to see that the language generated in t mode is

$$\left\{a^{2^n} \mid n \ge 1\right\}.$$

3. $GS_3 = (\{S, X_1, X_2\}, \{a,b\}, S, P_1, P_2, P_3),$

where

$$P_{1} = \left\{ S \to S, S \to X_{1}X_{1}, X_{2} \to X_{1} \right\}$$

$$P_{2} = \left\{ X_{1} \to aX_{2}, X_{1} \to a \right\}$$

$$P_{3} = \left\{ X_{1} \to bX_{2}, X_{1} \to b \right\}$$

In * mode , = 1, \geq 1 mod e, \leq k mod e ($k \geq 2$), t mode the language generated will be $\{w \mid w \in \{a,b\}^*, |w| \geq 2\}$. In = 2 mode , each component has to execute two steps , so the language generated will be $\{ww \mid w \in \{a,b\}^+\}$.

A similar argument holds for ≥ 2 steps. For $= k \text{ or } \geq k \text{ mod } es(k \geq 3)$, the language generated is empty, as each component can use at most two steps before transferring the control.

We state some results about the generative power without giving proof. The proofs are fairly simple, and can be tried as exercise. It can be easily seen that for CD grammars systems working in any of the modes defined having regular, linear, context—sensitive, or type 0 components, respectively, the generative power does not change; i.e., they generate the families of regular, linear, context—sensitive, or recursively enumerable languages, respectively.

But by the example given , we find that CD grammar systems with context – free components can generate context – sensitive languages. Let $CD_n(f)$ denote the family of languages generated by CD grammar systems with ε – free context free components , the number of components being at most n . When the number of components is not limited , the family is denoted by $CD_{\infty}(f)$ if ε – rules are allowed the corresponding families are denoted by

 $CD_n^{\varepsilon}(f)$ and $CD_{\infty}^{\varepsilon}(f)$, respectively.

PC Grammar systems

Definition

A PC grammar system of degree n, $n \ge 1$, is an (n + 3) – tuple : $GP = (N, K, T, (S_1, P_1), \dots, (S_n, P_n)),$

Where N is a non - terminal alphabet, T is a terminal alphabet,

 $K = \{Q_1, Q_2, \dots, Q_n\}$ are query symbols. N,T,K are mutually disjoint. P_i is a finite set of rewriting rules over $N \cup K \cup T$, and $S_i \in N$ for all $1 \le i \le n$.

Let
$$V_{GP} = N \bigcup K \bigcup T$$

The sets P_i are called components of the system. The index i of Q_i points to the ith component P_i of GP.

An equivalent representation for GP is $(N, K, T, G_1, ..., G_n)$, where $G_1 = (N \cup K, T, S_i, P_i), 1 \le i \le n$.

Definition

Given a PC grammar system

$$GP = (N, K, T, (S_1, P_1)....(S_n, P_n)),$$

as above for two n – tuples $(x_1, x_2, ..., x_n)$, $(y_1, ..., y_n)$, with $x_i, y_i \in V_{GP}^*$, $1 \le i \le n$, where $x_1 \not\in T^*$, we write $(x_1, ..., x_n) \Rightarrow (y_1, ..., y_n)$

if one of the two following two cases holds.

- 1. For each i $1 \le i \le n$, $|x_i|_K = 0$ (i.e., no query symbol in x_i), and either $x_i \Rightarrow y_i$ by a rule in P_i or $x_i = y_i \in T^*$.
- 2. There is i, $1 \le i \le n$, such that $|x_i|_K > 0$. (i.e., x_i has query symbols). Let for each such i, $x_i = z_1 Q_{i_1} z_2 Q_{i_2} z_t Q_{i_t} z_{t+1}$, $t \ge 1$ for

$$z_i \in (N \cup T)^*, 1 \le j \le t+1.$$

If $|x_{i_j}|_K=0$, for all j, $1 \leq j \leq t$, then $y_i=z_ix_{i_1}z_2x_{i_2}....z_tx_{i_t}z_{t+1}$ and $y_{i_j}=S_j$

(in returning mode) and $y_{i_j} = x_{i_j}$ (in non returning mode) $1 \le j \le t$. if for some j, $1 \le j \le t$, $|x_{i_j}|_k \ne 0$, then $y_i = x_i$. For all i, $1 \le i \le n$, such that y_i is not specified above, we have $y_i = x_i$.

An n-tuple $(x_1,...,x_n)$ with $x_i \in V_{GP}^*$ is called an instantaneous description (ID) (of GP).

- Thus an ID $(x_1, ..., x_n)$ directly gives rise to an ID $(y_1, ..., y_n)$, if either
- (a) Component wise derivation: No query symbol appears in x_1, \ldots, x_n ; then we have $x_i \Rightarrow y_i$ using a rule in P_i , if x_i has a non terminal. If $x_i \in T^*$, $y_i = x_i$
- (b) Communication step: Query symbols occur in some x_i . Then, a communication step is performed. Each occurrence of Q_j in x_i is replaced by x_j , provided x_j does not contain query symbols. In essence a component x_i containing query symbols is modified only when all occurrences of query symbols in it refer to strings without occurrences of query symbols.

In this communication step x_i replaces the query symbol Q_i . After that, GS resumes starting from axiom (this is called returning mode) or continues from where it was (this is called non-returning mode). Communication has priority over rewriting. No rewriting is possible as long as one query symbol is present in any component. If some query symbols in a component cannot be replaced in a given communication step, it may be possible that they can be replaced in the next step. When the first component (master) has a terminal string derivation stops . \Rightarrow is used to represent both rewriting and communication steps. $\stackrel{*}{\Rightarrow}$ is the reflexive transitive closure of \Rightarrow . We write \Rightarrow for returning mode \Rightarrow for non returning mode.

Definition

The language generated by a PC grammar system GP

1. In returning mode is:

$$L_r(GP)\left\{x \in T^* \mid \left(S_1, ..., S_n\right) \stackrel{*}{\underset{r}{\Longrightarrow}} \left(x, \alpha_2,, \alpha_n\right), \alpha_i, V_{GP}^*, 2 \le i \le n\right\}$$

2. In non - returning mode is:

$$L_{nr}(GP)\left\{x \in T^* \mid (S_1, ..., S_n) \stackrel{*}{\Longrightarrow} (x, \alpha_2,, \alpha_n), \alpha_i \in V_{GP}^*, 2 \le i \le n\right\}$$

If a query symbol is present, rewriting is not possible in any component. If circular query occurs, communication will not be possible and the derivation halts without producing a string for the language.

Circular query means something like the following: component i has query symbol \mathcal{Q}_j : component j has query symbol \mathcal{Q}_k : and component k has query symbol \mathcal{Q}_i : this is an example of a cycle query

The first component is called the master and the language consists of terminal strings derived there.

Generally, any component can introduce the query symbols. This is called non centralized system. If only the first component is allowed to introduce query symbols, it is called a centralized system.

A PC grammar system is said to be regular, linear, context free, and context sensitive, depending on the type of rules used in components.

There are a number of results on the hierarchy of PC grammar systems. Csuhaj Varju et al..,(1997) gave a detailed description of these systems.

Example

1. Let

$$GP_{1} = \begin{pmatrix} \{S_{1}, S_{1}', S_{2}, S_{3}\}, \{Q_{1}, Q_{2}, Q_{3}\}, \{a, b\}, (S_{1}, P_{1}), (S_{2}, P_{2}), \\ (S_{3}, P_{3}) \end{pmatrix}$$

 P_1 Consists of rules :

- 1. $S_1 \rightarrow abc$
- 2. $S_1 \rightarrow a^2b^2c^2$
- 3. $S_1 \rightarrow aS_1$
- 4. $S_1 \rightarrow a^3 Q_2$
- 5. $S_1' \rightarrow aS$

6.
$$S_1' \to a^3 Q_2$$

7.
$$S_2 \rightarrow b^2 Q_3$$

8.
$$S_3 \rightarrow c$$

$$P_2 = \left\{ S_2 \to b S_2 \right\}$$

$$P_3 = \left\{ S_3 \to cS_3 \right\}$$

$$L_r(GP_1) = L_{nr}(GP_1) = \{a^n b^n c^n \mid n \ge 1\}$$

This can be seen as follows

$$\frac{G_1}{S_1}$$

$$\frac{G_2}{S_2}$$

$$\frac{G_3}{S_3}$$

$$bS_2$$

$$cS_3$$

derivation stops $abc \in L_r(GP_1), L_{nr}(GP_1)$

$$S_{\scriptscriptstyle 1}$$

$$S_2$$

$$S_3$$

$$a^2b^2c^2$$

$$bS_2$$

$$cS_3$$

$$a^2b^2c^2 \in L_r(GP_1), L_{nr}(GP_1)$$

| $\underline{G_1}$ | $\underline{G_2}$ | $\underline{G_3}$ | |
|-------------------|-------------------|---------------------|------|
| $\frac{G_1}{S_1}$ | \overline{S}_2 | S_3 | |
| a^3Q_2 | bS_2 | cS_3 | |
| a^3bS_2 | S_2 | cS_3 | |
| $a^3bb^2Q_3$ | bS_2 | c^2S_3 | |
| $a^3b^3c^2S_3$ | bS_2 | S_3 | |
| $a^3b^3c^3$ | b^2S_2 | cS_3 in returning | mode |

| S_{1} | S |
|----------------|---|
| a^3Q_2 | b |
| a^3bS_2 | b |
| $a^3bb^2Q_3$ | b |
| $a^3b^3c^2S_3$ | b |
| | |

 $a^3b^3c^3$

 c^3S_3 in non returning mode

$$a^3b^3c^3 \in L_r(GP_1), L_{nr}(GP_1)$$

| $rac{G_1}{S_1}$ | $rac{G_2}{S_2}$ | $\frac{G_3}{S_3}$ |
|------------------|------------------|-------------------|
| aS_1 | bS_2 | cS_3 |
| aa^3Q_3 | b^2S_2 | c^2S_3 |
| $a^4b^2S_2$ | $S^{}_2$ | c^2S_3 |
| $a^4b^2b^2Q_3$ | bS_2 | c^3S_3 |
| $a^4b^2c^3c_3$ | bS_2 | S_3 |
| $a^4b^4c^4$ | b^2S_2 | cS_3 |

in returning mode

 $a^4b^4c^4 \in L_1(GP_1), L_{nr}(GP_1).$

2. Let
$$GP_2 = (\{S_1, S_2\}, \{Q_1, Q_2\}, \{a, b\}, (S_1, P_1)(S_2, P_2)),$$

where

$$P_1 = \{S_1 \rightarrow S_1, S_1 \rightarrow Q_1 Q_2\}$$

$$P_2 = \{S_2 \to aS_2, S_2 \to bS_2, S_2 \to a, S_2 \to b\}$$

$$L_r(GP_2) = L_{nr}(GP_2) = \{ww \mid w \in \{a,b\}^+\}$$

We see how abbabb is derived.

| $\underline{G_1}$ | G_2 | | | |
|---|---------|-----------------------|--|--|
| S_1 | S_2 | | | |
| S_{1} | aS_2 | | | |
| $S_{_1}$ | abS_2 | | | |
| Q_2Q_2 | abb | | | |
| abbabb | S_2 | in returning mode | | |
| abbabb | abb | in non returning mode | | |
| However $abbabb\in L_{r}ig(GP_{1}ig), L_{nr}ig(GP_{1}ig)$ | | | | |

This type of communication is called communication by request. There is also another way of communication known as communication by command. (Dassow and Paun, 1997). A restricted version of this communication by command is found useful in characterizing the workload in computer networks (Arthi et al., 2001).