Run-time Environments - Part 1

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NPTEL Course on Compiler Design

Outline of the Lecture – Part 1

- What is run-time support?
- Parameter passing methods
- Storage allocation
- Activation records
- Static scope and dynamic scope
- Passing functions as parameters
- Heap memory management

Garbage Collection



What is Run-time Support?

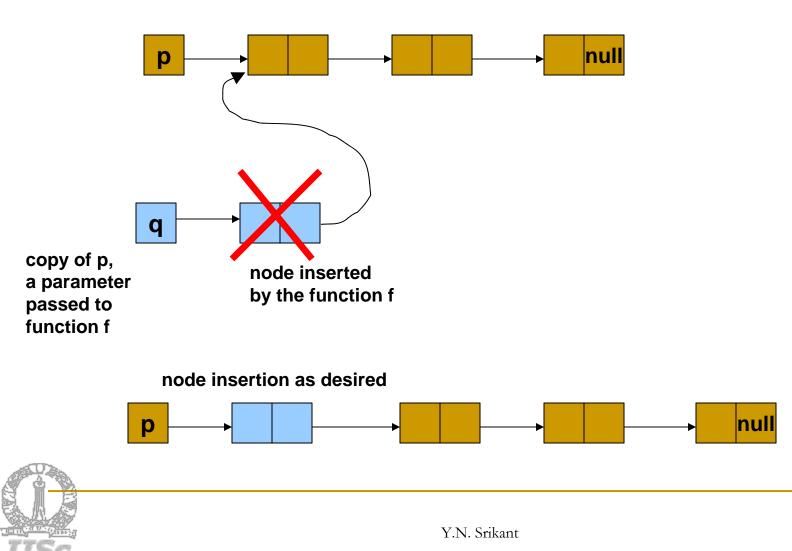
- It is not enough if we generate machine code from intermediate code
- Interfaces between the program and computer system resources are needed
 - □ There is a need to manage memory when a program is running
 - This memory management must connect to the data objects of programs
 - Programs request for memory blocks and release memory blocks
 - Passing parameters to fucntions needs attention
 - Other resources such as printers, file systems, etc., also need to be accessed
- These are the main tasks of run-time support
- In this lecture, we focus on memory management



- Call-by-value
- At runtime, prior to the call, the parameter is evaluated, and its actual value is put in a location private to the called procedure
 - Thus, there is no way to change the actual parameters.
 - Found in C and C++
 - C has only call-by-value method available
 - Passing pointers does not constitute call-by-reference
 - Pointers are also copied to another location
 - Hence in C, there is no way to write a function to insert a node at the front of a linked list (just after the header) without using pointers to pointers



Problem with Call-by-Value



- Call-by-Reference
- At runtime, prior to the call, the parameter is evaluated and put in a temporary location, if it is not a variable
- The address of the variable (or the temporary) is passed to the called procedure
- Thus, the actual parameter may get changed due to changes to the parameter in the called procedure



Found in C++ and Java

Call-by-Value-Result

 Call-by-value-result is a hybrid of Call-by-value and Call-byreference

- Actual parameter is calculated by the calling procedure and is copied to a local location of the called procedure
- Actual parameter's value is not affected during execution of the called procedure
- At return, the value of the formal parameter is copied to the actual parameter, if the actual parameter is a variable
- Becomes different from call-by-reference method
 - when global variables are passed as parameters to the called procedure and
 - the same global variables are also updated in another procedure invoked by the called procedure
 - Found in Ada



Difference between Call-by-Value, Call-by-Reference, and Call-by-Value-Result

program <i>RTST</i> ;	call-by-	Ca	all-by-	call-by-		
var a: integer;	value	re	ference	value-result		
procedure Q;	2	12		11		
begin a:= a+1; end	Value of a printed					
procedure R(x:integer);			Note: In Call-by-V-R, value of x is copied			
begin				into a, when proc R		
begin a:= 1; R <i>(a</i>); print(a);	returns. Hence a=11.					



- Call-by-Name

- Use of a call-by-name parameter implies a textual substitution of the formal parameter name by the actual parameter
- For example, if the procedure

procedure R (X,I : integer);

begin *I* := 2; *X* := 5; *I* := 3; *X* := 1; **end**;

is called by *R(B[J*2], J)*

this would result in (effectively) changing the body to

just before executing it



- Call by Name
- Note that the actual parameter corresponding to X changes whenever J changes
 - Hence, we cannot evaluate the address of the actual parameter just once and use it
 - It must be recomputed every time we reference the formal parameter within the procedure
- A separate routine (called *thunk*) is used to evaluate the parameters whenever they are used
- Found in Algol and functional languages



Example of Using the Four Parameter Passing Methods

- procedure swap (x, y : integer);
- 2. var temp : integer;
- 3. begin
- 4. temp := x;
- **5.** x := y;
- 6. y := temp;
- end (*swap*);
- 8. ..
- 9. i := 1;
- 10. a[i]:=10; (* a: array[1..5] of integer *)
- **11.** print(i,a[i]);
- 12. swap(i,a[i]);
- **13.** print(i,a[1]);

 Results from the 4 parameter passing methods (print statements)

cal	-by-	call-	by-	call-by-		cal	l-by-
val	ue	refe	rence	val-result		name	
1	10	1	10	1	10	1	10
1	10	10	1	10	1	err	or!

Reason for the error in the Call-by-name Example The problem is in the swap routine

```
temp := i; (* => temp:=1 *)
i := a[i]; (* => i:=10 since a[i]=10 *)
a[i] := temp; (* => a[10]:=1 => index out of bounds *)
```



Code and Data Area in Memory

- Most programming languages distinguish between code and data
- Code consists of only machine instructions and normally does not have embedded data
 - Code area normally does not grow or shrink in size as execution proceeds
 - Unless code is loaded dynamically or code is produced dynamically
 - As in Java dynamic loading of classes or producing classes and instantiating them dynamically through reflection
 - Memory area can be allocated to code statically
 - We will not consider Java further in this lecture
- Data area of a program may grow or shrink in size during execution



Static Versus Dynamic Storage Allocation

Static allocation

 Compiler makes the decision regarding storage allocation by looking only at the program text

Dynamic allocation

- Storage allocation decisions are made only while the program is running
- Stack allocation
 - Names local to a procedure are allocated space on a stack
- Heap allocation
 - Used for data that may live even after a procedure call returns
 - Ex: dynamic data structures such as symbol tables
 - Requires memory manager with garbage collection



Static Data Storage Allocation

- Compiler allocates space for all variables (local and global) of all procedures at compile time
 - No stack/heap allocation; no overheads
 - Ex: Fortran IV and Fortran 77
 - Variable access is fast since addresses are known at compile time
 - No recursion



Main program variables
Procedure P1 variables
Procedure P2 variables
Procedure P4 variables
Main memory

Dynamic Data Storage Allocation

- Compiler allocates space only for golbal variables at compile time
- Space for variables of procedures will be allocated at run-time
 - Stack/heap allocation
 - Ex: C, C++, Java, Fortran 8/9
 - Variable access is slow (compared to static allocation) since addresses are accessed through the stack/heap pointer
 - Recursion can be implemented



Activation Record Structure

Return address

Static and Dynamic links (also called Access and Control link resp.)

(Address of) function result

Actual parameters

Local variables

Temporaries

Saved machine status

Space for local arrays

Note:

The position of the fields of the act. record as shown are only notional.

Implementations can choose different orders; e.g., function result could be at the top of the act. record.

