Data-flow Analysis: Theoretical Foundations - Part 2

Y.N. Srikant

Department of Computer Science Indian Institute of Science Bangalore 560 012

NPTEL Course on Compiler Design

Foundations of Data-flow Analysis

- Basic questions to be answered
 - Under what situations is the iterative DFA algorithm correct?
 - How precise is the solution produced by it?
 - Will the algorithm converge?
 - What is the meaning of a "solution"?
- The above questions can be answered accurately by a DFA framework
- Further, reusable components of the DFA algorithm can be identified once a framework is defined
- A DFA framework (D, V, ∧, F) consists of
 - D: A direction of the dataflow, either forward or backward
 - V : A domain of values
 - \land : A meet operator (V, \land) form a semi-lattice
 - F: A family of transfer functions, $V \longrightarrow V$
 - F includes constant transfer functions for the ENTRY/EXIT nodes as well



Properties of the Iterative DFA Algorithm

 If the iterative algorithm converges, the result is a solution to the DF equations

Proof: If the equations are not satisfied by the time the loop ends, atleast one of the *OUT* sets changes and we iterate again

 If the framework is monotone, then the solution found is the maximum fixpoint (MFP) of the DF equations
 An MFP solution is such that in any other solution, values of IN[B] and OUT[B] are ≤ the corresponding values of the MFP (i.e., less precise)

Proof: We can show by induction that the values of IN[B] and OUT[B] only decrease (in the sense of \leq relation) as the algorithm iterates



Properties of the Iterative DFA Algorithm (2)

 If the semi-lattice of the framework is monotone and is of finite height, then the algorithm is guaranteed to converge

Proof: Dataflow values decrease with each iteration Max no. of iterations = height of the lattice \times no. of nodes in the flow graph

Meaning of the Ideal Data-flow Solution

- Find all possible execution paths from the start node to the beginning of B
- (Assuming forward flow) Compute the data-flow value at the end of each path (using composition of transfer functions) and apply the ∧ operator to these values to find their glb
- No execution of the program can produce a smaller value for that program point

$$IDEAL[B] = \bigwedge_{P, \text{ a possible execution path from start node to } f_P(v_{init})$$

- Answers greater (in the sense of ≤) than IDEAL are incorrect (one or more execution paths have been ignored)
- Any value smaller than or equal to IDEAL is conservative,
 i.e., safe (one or more infeasible paths have been included)
- Closer the value to IDEAL, more precise it is



Meaning of the Meet-Over-Paths Data-flow Solution

 Since finding all execution paths is an undecidable problem, we approximate this set to include all paths in the flow graph

$$MOP[B] = \bigwedge_{P, \text{ a path from start node to } B} f_P(v_{init})$$

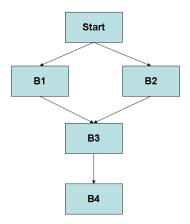
 MOP[B] ≤ IDEAL[B], since we consider a superset of the set of execution paths

Meaning of the Maximum Fixpoint Data-flow Solution

- Finding all paths in a flow graph may still be impossible, if it has cycles
- The iterative algorithm does not try this
 - It visits all basic blocks, not necessarily in execution order
 - \bullet It applies the \land operator at each join point in the flow graph
 - The solution obtained is the Maximum Fixpoint solution (MFP)
- If the framework is distributive, then the MOP and MFP solutions will be identical
- Otherwise, with just monotonicity, MFP ≤ MOP ≤ IDEAL, and the solution provided by the iterative algorithm is safe



Example to show *MFP* \leq *MOP*



Example to show $MFP \leq MOP$ (2)

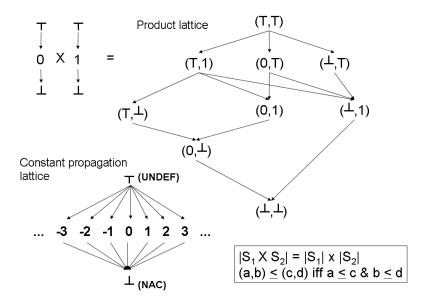
- There are two paths from Start to B4:
 Start → B1 → B3 → B4 and Start → B2 → B3 → B4
- $MOP[B4] = ((f_{B3} \cdot f_{B1}) \wedge (f_{B3} \cdot f_{B2}))(v_{init})$
- In the iterative algorithm, if we chose to visit the nodes in the order (Start, B1, B2, B3, B4), then IN[B4] = f_{B3}(f_{B1}(v_{init}) \(\times\) f_{B2}(v_{init}))
- Note that the ∧ operator is being applied differently here than in the MOP equation
- The two values above will be equal only if the framework is distributive
- With just monotonicity, we would have IN[B4] ≤ MOP[B4]



Constant Propagation Framework - Data-flow Values

- The lattice for a single variable in the CP framework is shown in the next slide
- An example of product of two lattices is in the next slide
- DF values in the RD framework can also be considered as
 - values in a product of lattices of definitions
 - one lattice for each definition, with ϕ as \top and {d} as the only other element
- The lattice of the DF values in the CP framework
 - Product of the semi-lattices of the variables (one lattice for each variable)

Product of Two Lattices and Lattice of Constants



CP Framework - The ∧ (meet) Operator

- In a product lattice, $(a_1, b_1) \le (a_2, b_2)$ iff $a_1 \le_A a_2$ and $b_1 \le_B b_2$ assuming $a_1, a_2 \in A$ and $b_1, b_2 \in B$
- Each variable is associated with a map m
- m(v) is the abstract value (as in the lattice) of the variable v in a map m
- Each element of the product lattice is a similar, but "larger" map m
 - which is defined for all variables, and
 - where m(v) is the abstract value of the variable v
- Thus, $m \le m'$ (in the product lattice), iff for all variables v, $m(v) \le m'(v)$, OR, $m \land m' = m''$, if $m''(v) = m(v) \land m'(v)$, for all variables v



Transfer Functions for the CP Framework

- Assume one statement per basic block
- Transfer functions for basic blocks containing many statements may be obtained by composition
- m(v) is the abstract value of the variable v in a map m.
- The set F of the framework contains transfer functions which accept maps and produce maps as outputs
- F contains an identity map
- Map for the *Start* block is $m_0(v) = UNDEF$, for all variables v
- This is reasonable since all variables are undefined before a program begins



Transfer Functions for the CP Framework

- Let f_s be the transfer function of the statement s
- If $m' = f_s(m)$, then f_s is defined as follows
 - \bullet If s is not an assignment, f_s is the identity function
 - If s is an assignment to a variable x, then m'(v) = m(v), for all $v \neq x$, provided, one of the following conditions holds
 - (a) If the RHS of s is a constant c, then m'(x) = c
 - (b) If the RHS is of the form y + z, then

$$m'(x) = m(y) + m(z)$$
, if $m(y)$ and $m(z)$ are constants
= NAC, if either $m(y)$ or $m(z)$ is NAC
= UNDEF, otherwise

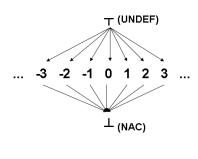
(c) If the RHS is any other expression, then m'(x) = NAC



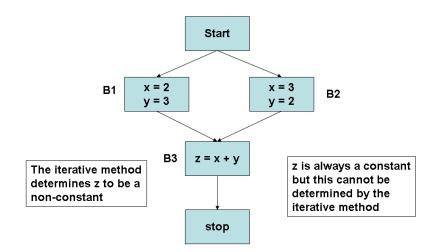
Monotonicity of the CP Framework

It must be noted that the transfer function $(m' = f_s(m))$ always produces a "lower" or same level value in the CP lattice, whenever there is a change in inputs

m(y)	m(z)	m'(x)	
UNDEF	UNDEF	UNDEF	
	<i>c</i> ₂	UNDEF	
	NAC	NAC	
<i>c</i> ₁	UNDEF	UNDEF	
	<i>c</i> ₂	$c_1 + c_2$	
	NAC	NAC	
NAC	UNDEF	NAC	
	<i>c</i> ₂	NAC	
	NAC	NAC	



Non-distributivity of the CP Framework



Non-distributivity of the CF Framework - Example

• If f_1 , f_2 , f_3 are transfer functions of B1, B2, B3 (resp.), then $f_3(f_1(m_0) \wedge f_2(m_0)) < f_3(f_1(m_0)) \wedge f_3(f_2(m_0))$ as shown in the table, and therefore the CF framework is non-distributive

т	m(x)	m(y)	m(z)
m_0	UNDEF	UNDEF	UNDEF
$f_1(m_0)$	2	3	UNDEF
$f_2(m_0)$	3	2	UNDEF
$f_1(m_0) \wedge f_2(m_0)$	NAC	NAC	UNDEF
$f_3(f_1(m_0) \wedge f_2(m_0))$	NAC	NAC	NAC
$f_3(f_1(m_0))$	2	3	5
$f_3(f_2(m_0))$	3	2	5
$f_3(f_1(m_0)) \wedge f_3(f_2(m_0))$	NAC	NAC	5