

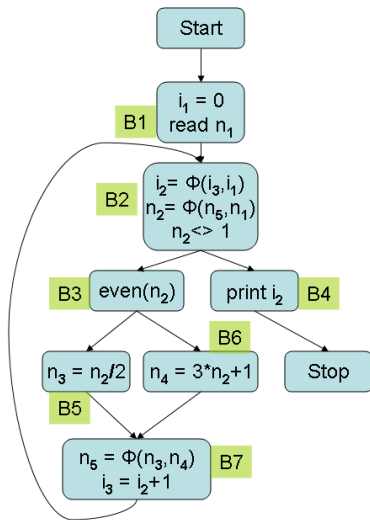
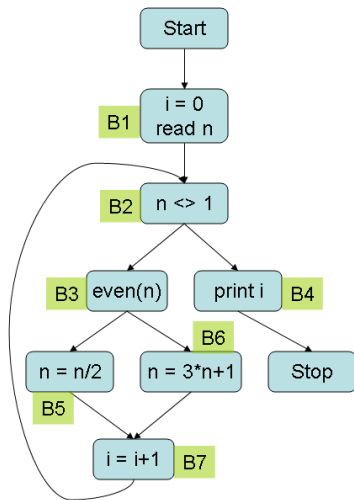
The Static Single Assignment Form: Construction and Application to Program Optimizations - Part 3

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Program 3 in non-SSA and SSA Form



Optimization Algorithms with SSA Forms

- Dead-code elimination
 - Very simple, since there is exactly one definition reaching each use
 - Examine the *du-chain* of each variable to see if its use list is empty
 - Remove such variables and their definition statements
 - If a statement such as $x = y + z$ or $x = \phi(y_1, y_2)$ is deleted, care must be taken to remove the deleted statement from the *du-chains* of y_1 and y_2
- Simple constant propagation
- Copy propagation
- Conditional constant propagation and constant folding
- Global value numbering

Simple Constant Propagation

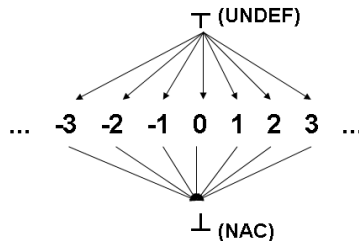
```
{ Stmtpile = {S|S is a statement in the program}
  while Stmtpile is not empty {
    S = remove(Stmtpile);
    if S is of the form  $x = \phi(c, c, \dots, c)$  for some constant  $c$ 
      replace S by  $x = c$ 
    if S is of the form  $x = c$  for some constant  $c$ 
      delete S from the program
      for all statements T in the du-chain of  $x$  do
        substitute  $c$  for  $x$  in T
      Stmtpile = Stmtpile  $\cup$  {T}
  }
```

Copy propagation is similar to constant propagation

- A single-argument ϕ -function, $x = \phi(y)$, or a copy statement, $x = y$ can be deleted and y substituted for every use of x

The Constant Propagation Framework - An Overview

$m(y)$	$m(z)$	$m'(x)$
UNDEF	UNDEF	UNDEF
	c_2	UNDEF
	NAC	NAC
c_1	UNDEF	UNDEF
	c_2	$c_1 + c_2$
	NAC	NAC
NAC	UNDEF	NAC
	c_2	NAC
	NAC	NAC



Conditional Constant Propagation - 1

- SSA forms along with extra edges corresponding to *d-u* information are used here
 - Edge from every definition to each of its uses in the SSA form (called henceforth as *SSA edges*)
- Uses both flow graph and SSA edges and maintains two different work-lists, one for each (*Flowpile* and *SSApile*, resp.)
- Flow graph edges are used to keep track of reachable code and SSA edges help in propagation of values
- Flow graph edges are added to *Flowpile*, whenever a branch node is symbolically executed or whenever an assignment node has a single successor

Conditional Constant Propagation - 2

- SSA edges coming out of a node are added to the SSA work-list whenever there is a change in the value of the assigned variable at the node
- This ensures that all *uses* of a definition are processed whenever a definition changes its lattice value.
- This algorithm needs only one lattice cell per *variable* (globally, not on a per node basis) and two lattice cells per node to store expression values
- Conditional expressions at branch nodes are evaluated and depending on the value, either one of outgoing edges (corresponding to *true* or *false*) or both edges (corresponding to \perp) are added to the worklist
- However, at any join node, the *meet* operation considers only those predecessors which are marked *executable*.

CCP Algorithm - Contd.

```
//  $\mathcal{G} = (\mathcal{N}, \mathcal{E}_f, \mathcal{E}_s)$  is the SSA graph,  
// with flow edges and SSA edges, and  
//  $\mathcal{V}$  is the set of variables used in the SSA graph  
begin  
   $Flowpile = \{(Start \rightarrow n) \mid (Start \rightarrow n) \in \mathcal{E}_f\}$ ;  
   $SSApile = \emptyset$ ;  
  for all  $e \in \mathcal{E}_f$  do  $e.executable = false$ ; end for  
   $v.cell$  is the lattice cell associated with the variable  $v$   
  for all  $v \in \mathcal{V}$  do  $v.cell = \top$ ; end for  
  //  $y.oldval$  and  $y.newval$  store the lattice values  
  // of expressions at node  $y$   
  for all  $y \in \mathcal{N}$  do  
     $y.oldval = \top$ ;  $y.newval = \top$ ;  
  end for
```


CCP Algorithm - Contd.

```
while (Flowpile  $\neq \emptyset$ ) or (SSApile  $\neq \emptyset$ ) do
begin
  if (Flowpile  $\neq \emptyset$ ) then
  begin
    (x, y) = remove(Flowpile);
    if (not (x, y).executable) then
    begin
      (x, y).executable = true;
      if ( $\phi$ -present(y)) then visit- $\phi$ (y)
      else if (first-time-visit(y)) then visit-expr(y);
      // visit-expr is called on y only on the first visit
      // to y through a flow edge; subsequently, it is called
      // on y on visits through SSA edges only
      if (flow-outdegree(y) == 1) then
      // Only one successor flow edge for y
      Flowpile = Flowpile  $\cup \{(y, z) \mid (y, z) \in \mathcal{E}_f\}$ ;
    end
  end
end
```

CCP Algorithm - Contd.

```
// if the edge is already marked, then do nothing
end
if ( $SSA_{pile} \neq \emptyset$ ) then
  begin
     $(x, y) = \text{remove}(SSA_{pile});$ 
    if ( $\phi\text{-present}(y)$ ) then  $\text{visit-}\phi(y)$ 
      else if ( $\text{already-visited}(y)$ ) then  $\text{visit-expr}(y);$ 
      // A false returned by already-visited implies
      // that  $y$  is not yet reachable through flow edges
    end
  end // Both piles are empty
end
function  $\phi\text{-present}(y)$  //  $y \in \mathcal{N}$ 
begin
  if  $y$  is a  $\phi$ -node then return true
  else return false
end
```

CCP Algorithm - Contd.

```
function visit- $\phi$ ( $y$ ) //  $y \in \mathcal{N}$ 
begin
   $y.newval = \top$ ; //  $\|y.instruction.inputs\|$  is the number of
  // parameters of the  $\phi$ -instruction at node  $y$ 
  for  $i = 1$  to  $\|y.instruction.inputs\|$  do
    Let  $p_i$  be the  $i^{th}$  predecessor of  $y$  ;
    if ( $(p_i, y).executable$ ) then
      begin
        Let  $a_i = y.instruction.inputs[i]$ ;
        //  $a_i$  is the  $i^{th}$  input and  $a_i.cell$  is the lattice cell
        // associated with that variable
         $y.newval = y.newval \sqcap a_i.cell$ ;
      end
    end for
end for
```

CCP Algorithm - Contd.

```
if ( $y.newval < y.instruction.output.cell$ ) then
begin
   $y.instruction.output.cell = y.newval$ ;
   $SSApile = SSApile \cup \{(y, z) \mid (y, z) \in \mathcal{E}_s\}$ ;
end
end
```

```
function already-visited( $y$ ) //  $y \in \mathcal{N}$ 
// This function is called when processing an SSA edge
begin // Check in-coming flow graph edges of  $y$ 
  for all  $e \in \{(x, y) \mid (x, y) \in \mathcal{E}_f\}$ 
    if  $e.executable$  is true for at least one edge  $e$ 
      then return true else return false
    end for
  end
end
```

CCP Algorithm - Contd.

```
function first-time-visit( $y$ ) //  $y \in \mathcal{N}$ 
// This function is called when processing a flow graph edge
begin // Check in-coming flow graph edges of  $y$ 
  for all  $e \in \{(x, y) \mid (x, y) \in \mathcal{E}_f\}$ 
    if  $e.executable$  is true for more than one edge  $e$ 
      then return false else return true
  end for
// At least one in-coming edge will have executable true
// because the edge through which node  $y$  is entered is
// marked as executable before calling this function
end
```

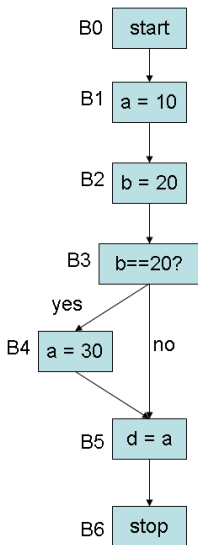
CCP Algorithm - Contd.

```
function visit-expr(y) //  $y \in \mathcal{N}$ 
begin
  Let  $input_1 = y.instruction.inputs[1]$ ;
  Let  $input_2 = y.instruction.inputs[2]$ ;
  if ( $input_1.cell == \perp$  or  $input_2.cell == \perp$ ) then
     $y.newval = \perp$ 
  else if ( $input_1.cell == \top$  or  $input_2.cell == \top$ ) then
     $y.newval = \top$ 
    else // evaluate expression at y as per lattice evaluation rules
       $y.newval = evaluate(y)$ ;
    It is easy to handle instructions with one operand
  if y is an assignment node then
    if ( $y.newval < y.instruction.output.cell$ ) then
      begin
         $y.instruction.output.cell = y.newval$ ;
         $SSApile = SSApile \cup \{(y, z) \mid (y, z) \in \mathcal{E}_s\}$ ;
      end
```

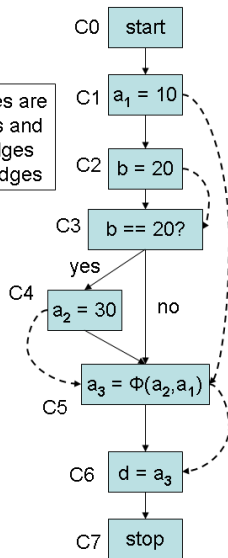
CCP Algorithm - Contd.

```
else if  $y$  is a branch node then
  begin
    if ( $y.newval < y.oldval$ ) then
      begin
         $y.oldval = y.newval$ ;
        switch( $y.newval$ )
          case  $\perp$ : // Both true and false branches are equally likely
             $Flowpile = Flowpile \cup \{(y, z) \mid (y, z) \in \mathcal{E}_f\}$ ;
          case true:  $Flowpile = Flowpile \cup \{(y, z) \mid (y, z) \in \mathcal{E}_f$  and
              ( $y, z$ ) is the true branch edge at  $y$  };
          case false:  $Flowpile = Flowpile \cup \{(y, z) \mid (y, z) \in \mathcal{E}_f$  and
              ( $y, z$ ) is the false branch edge at  $y$  };
        end switch
      end
    end
  end
end
```

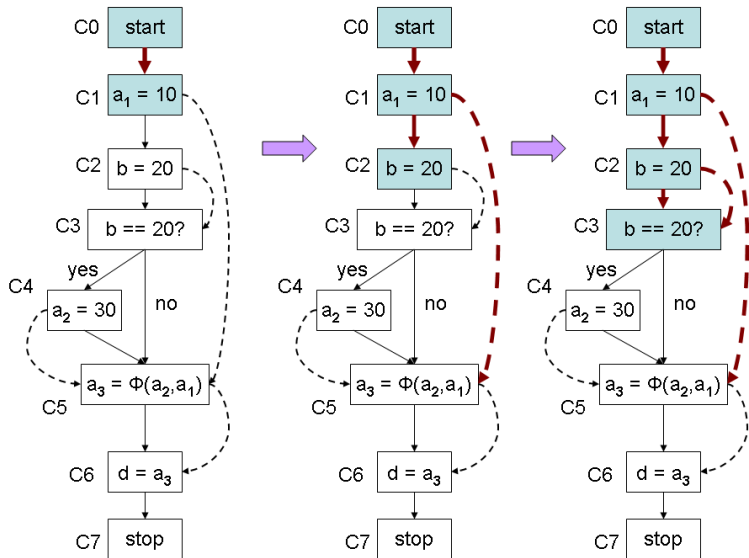
CCP Algorithm - Example - 1



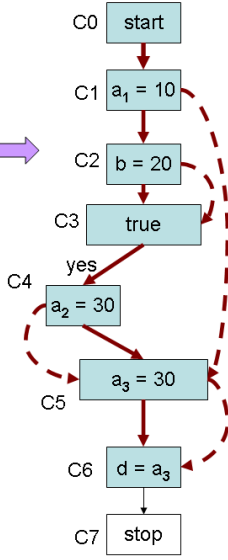
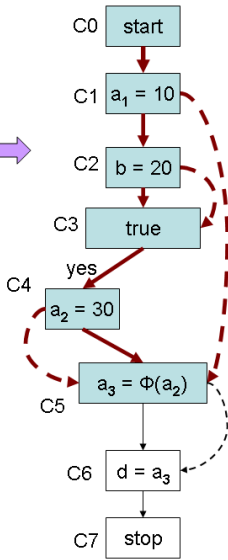
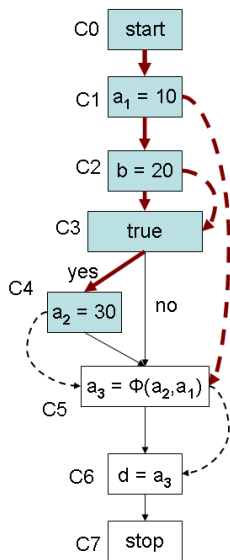
Solid edges are flow edges and dashed edges are SSA edges



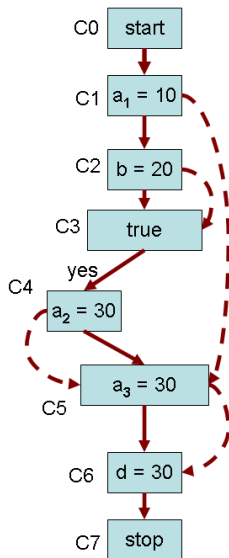
CCP Algorithm - Example 1 - Trace 1



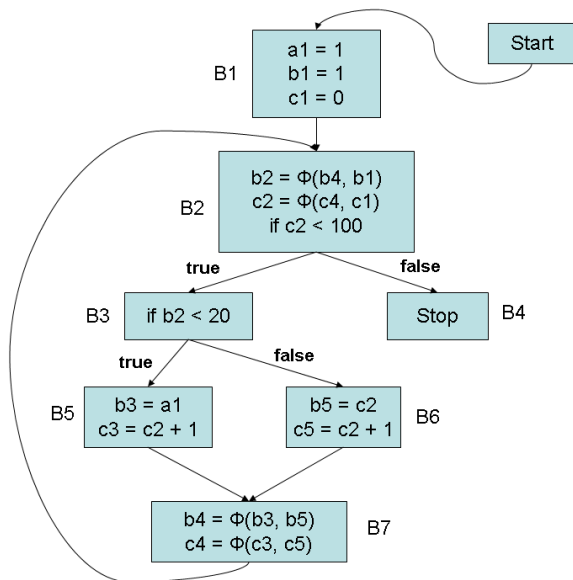
CCP Algorithm - Example 1 - Trace 2



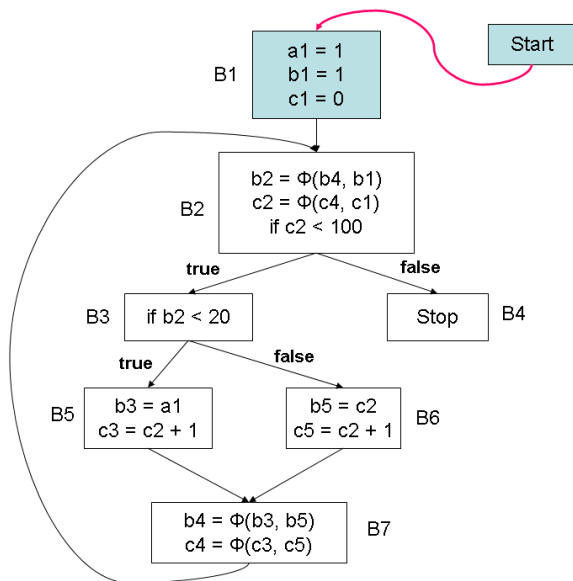
CCP Algorithm - Example 1 - Trace 3



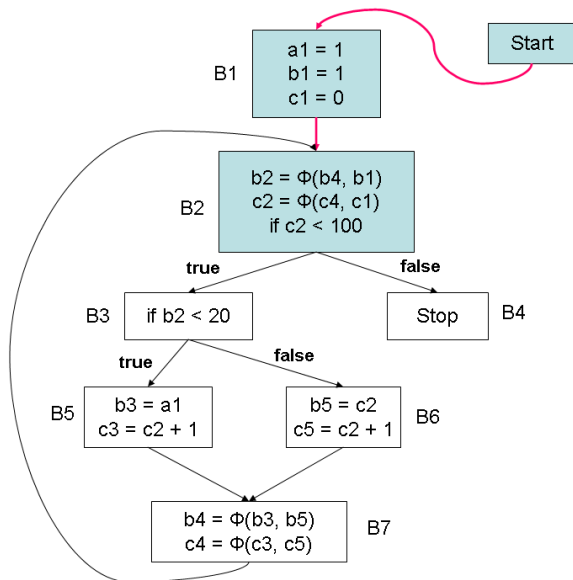
CCP Algorithm - Example 2



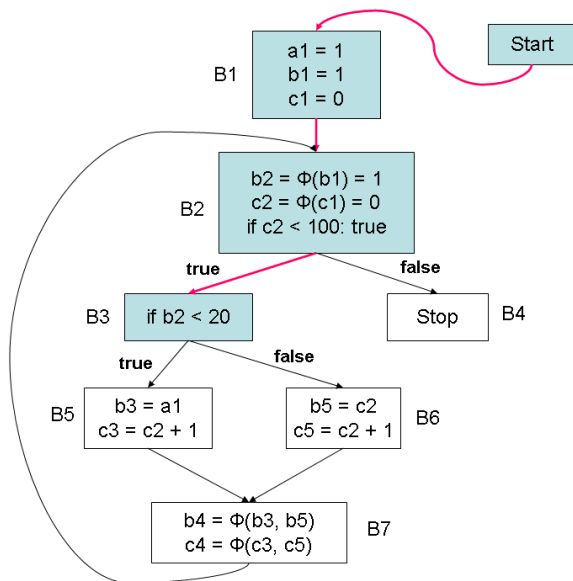
CCP Algorithm - Example 2 - Trace 1



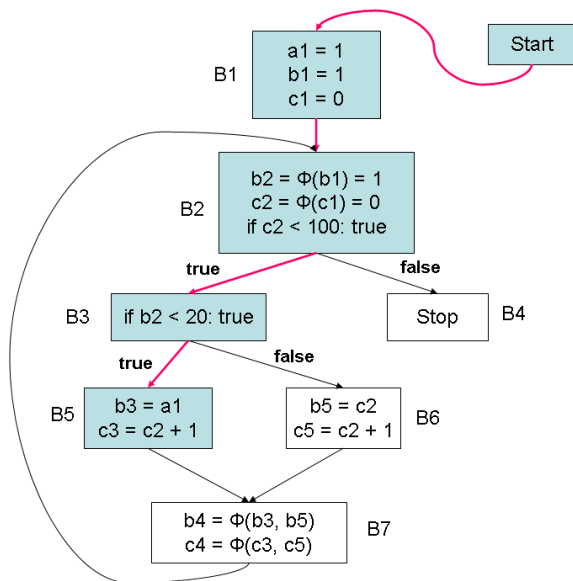
CCP Algorithm - Example 2 - Trace 2



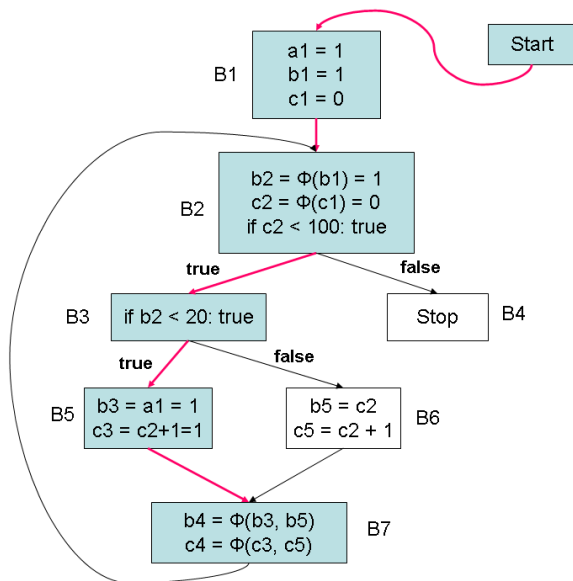
CCP Algorithm - Example 2 - Trace 3



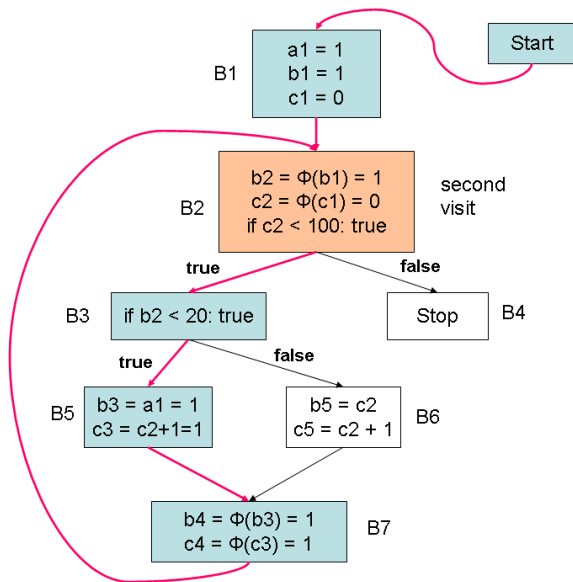
CCP Algorithm - Example 2 - Trace 4



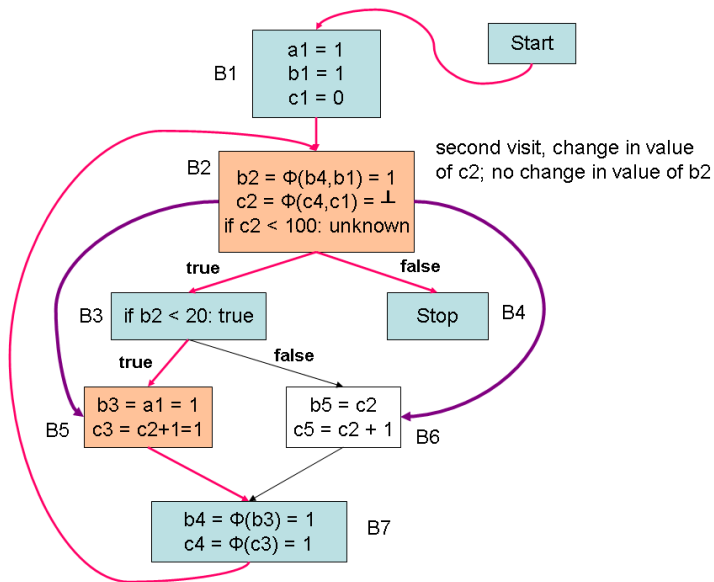
CCP Algorithm - Example 2 - Trace 5



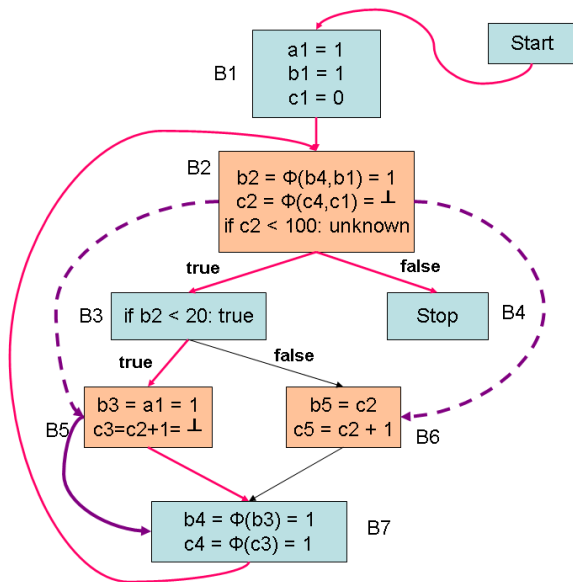
CCP Algorithm - Example 2 - Trace 6



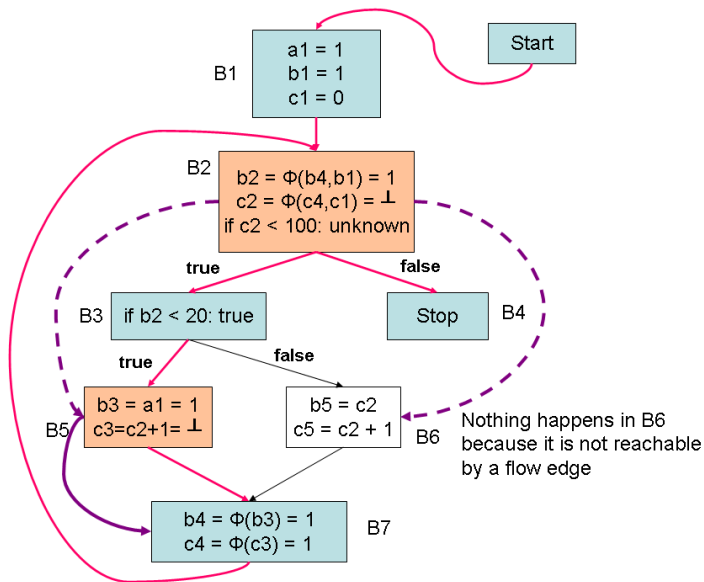
CCP Algorithm - Example 2 - Trace 7



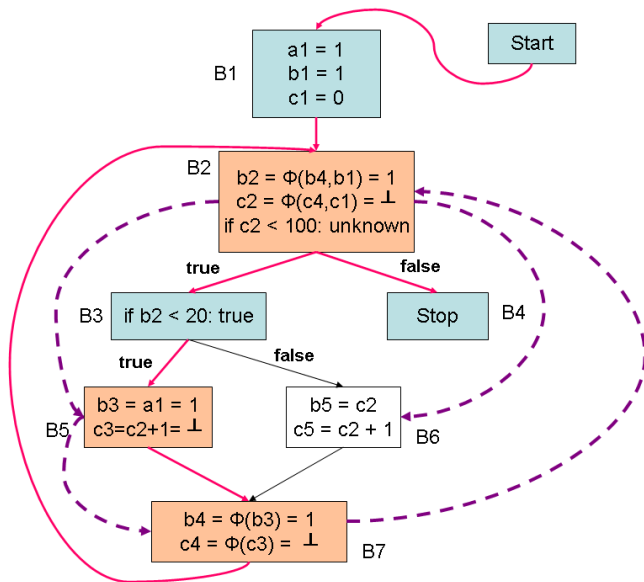
CCP Algorithm - Example 2 - Trace 8



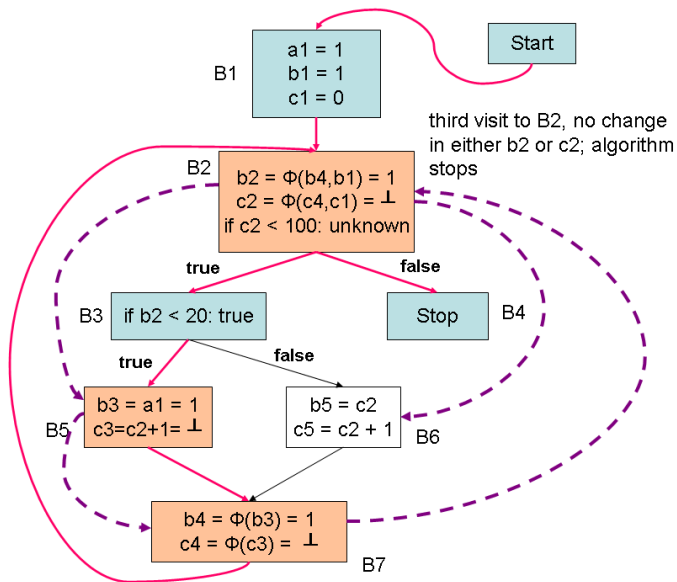
CCP Algorithm - Example 2 - Trace 9



CCP Algorithm - Example 2 - Trace 10

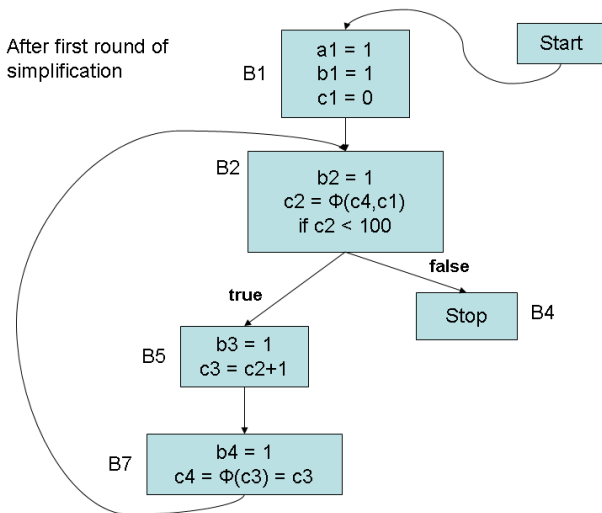


CCP Algorithm - Example 2 - Trace 11

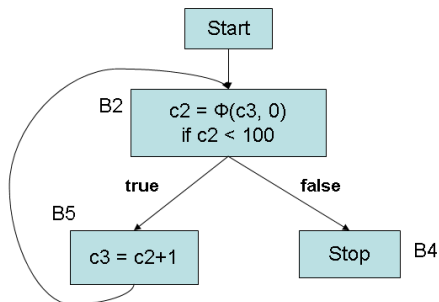


CCP Algorithm - Example 2 - Trace 12

After first round of simplification



CCP Algorithm - Example 2 - Trace 13



After second round of simplification –
elimination of dead code, elimination
of trivial Φ -functions, copy propagation etc.

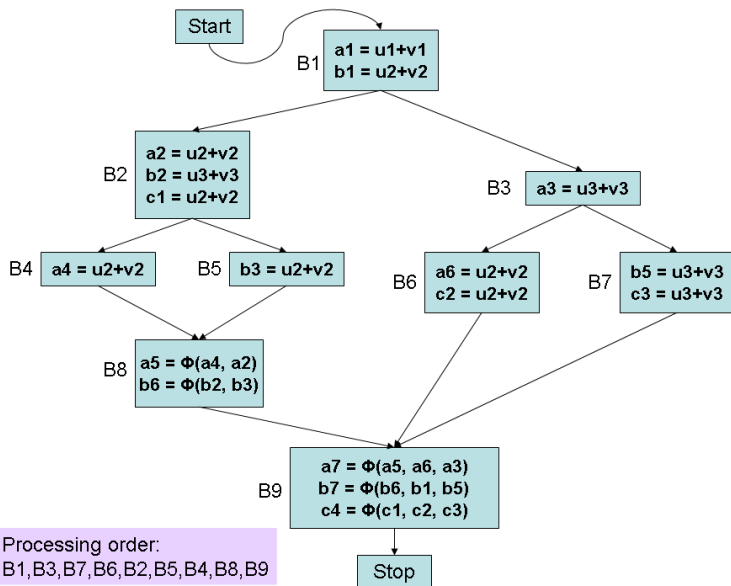
Value Numbering with SSA Forms

- Global value numbering scheme
 - Similar to the scheme with extended basic blocks
 - Scope of the tables is over the dominator tree
 - Therefore more redundancies can be caught (e.g., expressions in block $B8$, such as $d_1 = u_1 + v_1$, which are equivalent to a_1 in block $B1$)
- No $d-u$ or $u-d$ edges needed
- Uses *reverse post order* on the DFS tree of the SSA graph to process the dominator tree
 - This ensures that definitions are processed before use
- Back edges make the algorithm find *fewer* equivalences (more on this later)
- Scoped *HashTable* (scope over the dominator tree)
 - For example, an assignment $a_{10} = u_1 + v_1$ in block $B9$ (if present) can use the value of the expression $u_1 + v_1$ of block $B1$, since $B1$ is a dominator of $B9$

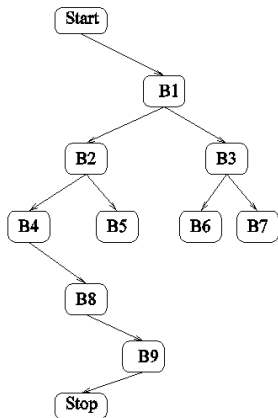
Value Numbering with SSA Forms

- Variable names are not reused in SSA forms
 - Hence, no need to restore old entries in the scoped *HashTable* when the processing of a block is completed
 - Just deleting new entries will be sufficient
- Any copies generated because of common subexpressions can be deleted immediately
- Copy propagation is carried out during value-numbering
- Ex: Copy statements generated due to value numbering in blocks B2, B4, B5, B6, B7, and B8 can be deleted
- The *ValnumTable* stores the SSA name and its value number and is global; it is not scoped over the dominator tree (reasons next slide)
- Value numbering transformation retains the *dominance property* of the SSA form
 - Every definition dominates all its uses or predecessors of uses (in case of *phi*-functions)

Example: An SSA Form

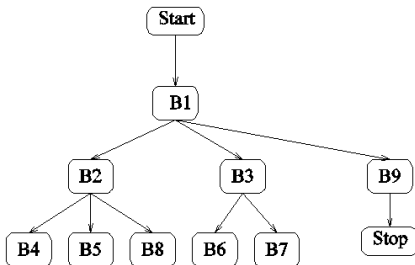


Dominator Tree and Reverse Post order



Postorder on the DFS tree:

Stop, B9, B8, B4, B5, B2, B6, B7, B3, B1, Start



Reverse postorder on the SSA graph that is used with the dominator tree above:

Start, B1, B3, B7, B6, B2, B5, B4, B8, B9, Stop

Global Unscoped *ValnumTable*

- Needed for ϕ -instructions
- A ϕ -instruction receives inputs from several variables along different predecessors of a block
- These inputs are defined in the immediate predecessors or dominators of the predecessors of the current block
- They may be defined in any block that has a control path to the current block
- For example, while processing block B_9 , we need definitions of a_5 , a_6 , and a_3
 - a_5, a_6 : defined in the predecessor block, B_6 , and
 - a_3 : defined in the dominator of the predecessor of B_9 , i.e., B_3
- However, each incoming arc corresponds to exactly one parameter of the ϕ -instruction
- Hence we need an *unscoped ValnumTable*

HashTable and ValnumTable

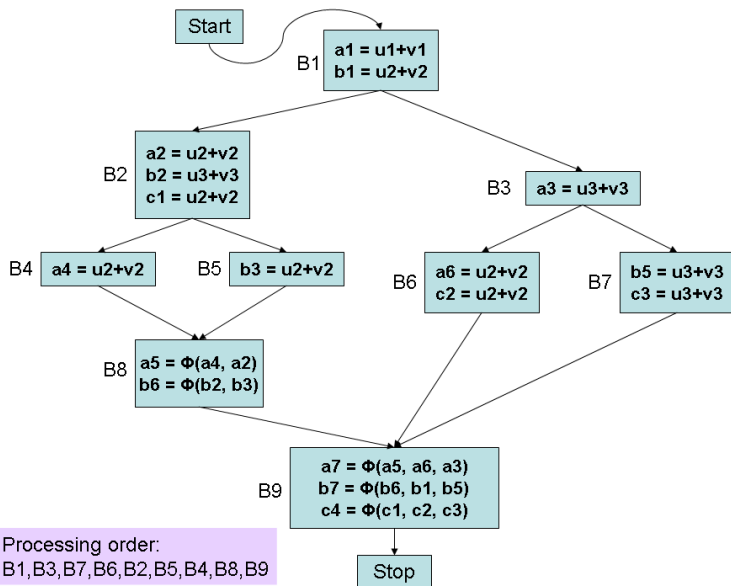
HashTable entry
(indexed by expression hash value)

Expression	Value number	Parameters for ϕ-function	Defining variable
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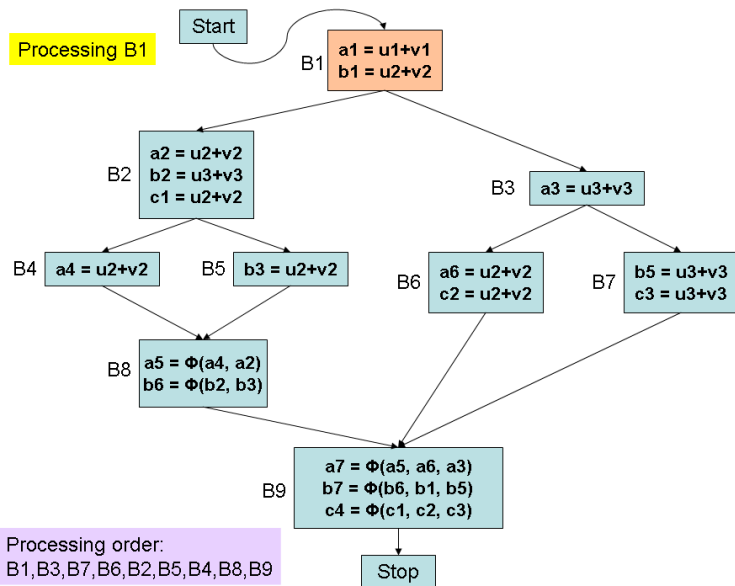
ValnumTable
(indexed by name hash value)

Variable name	Value number	Constant value	Replacing variable
----------------------	---------------------	-----------------------	---------------------------

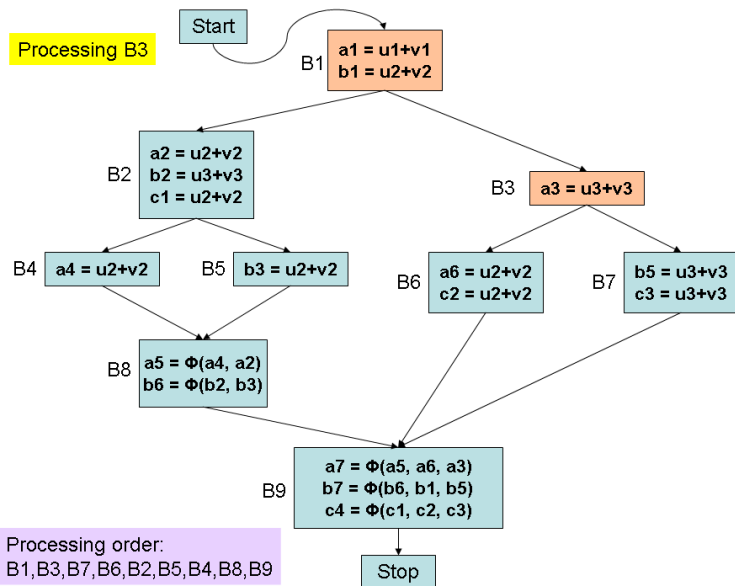
SSA Value-numbering Example - 1.0



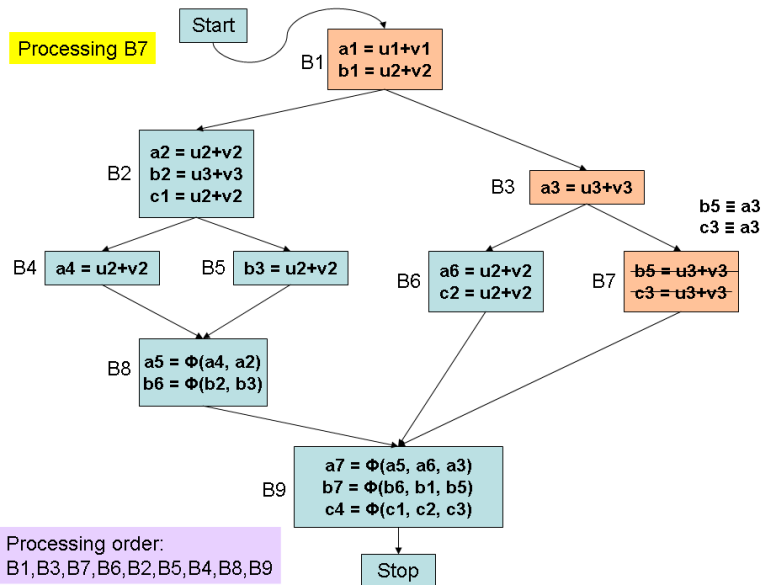
SSA Value-numbering Example - 1.1



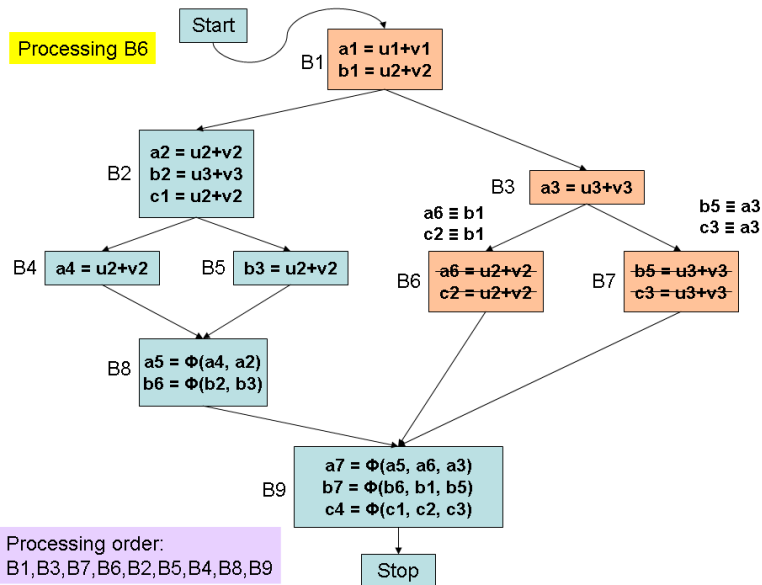
SSA Value-numbering Example - 1.2



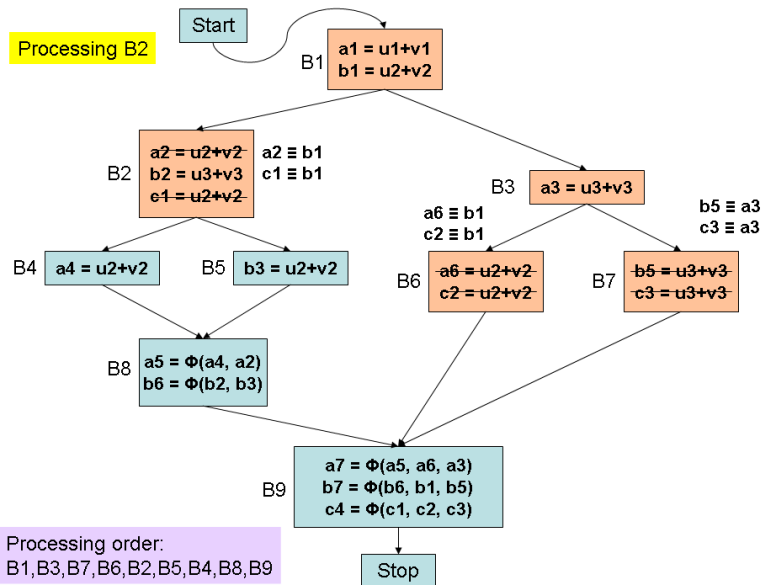
SSA Value-numbering Example - 1.3



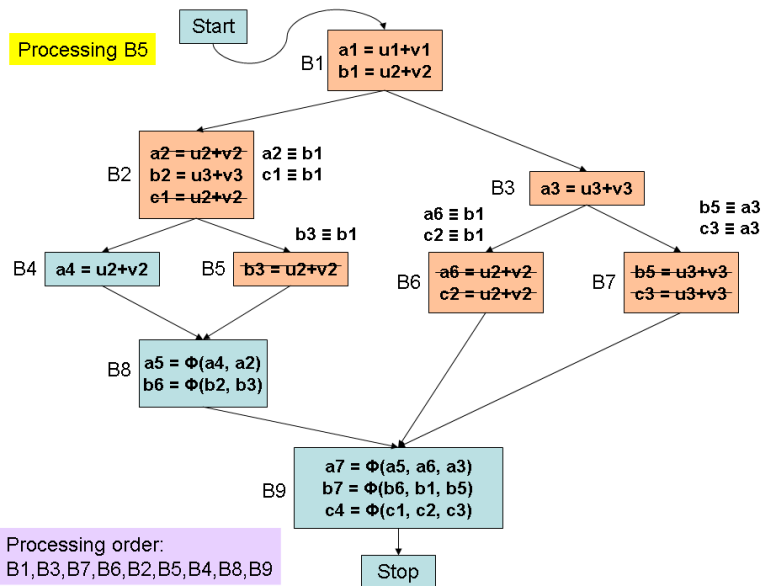
SSA Value-numbering Example - 1.4



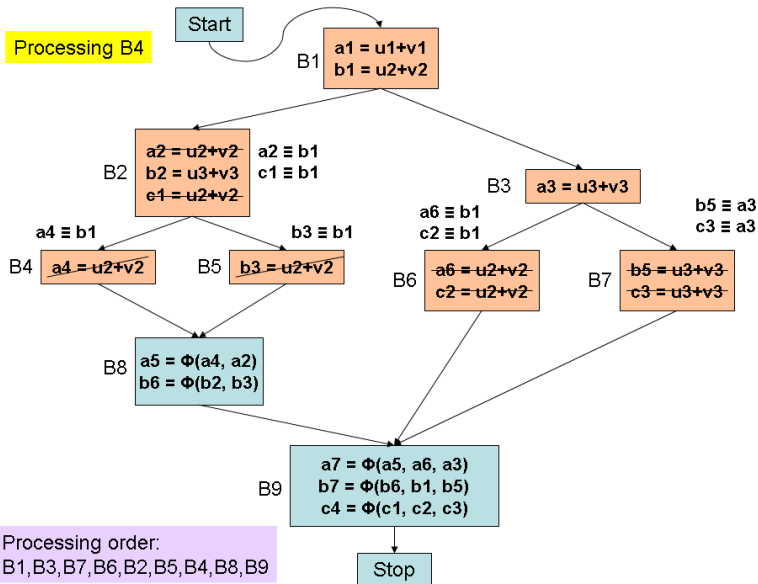
SSA Value-numbering Example - 1.5



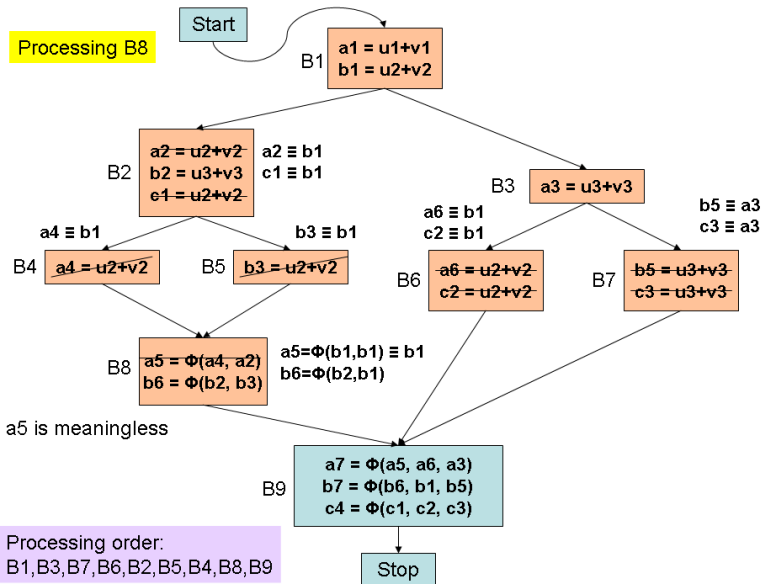
SSA Value-numbering Example - 1.6



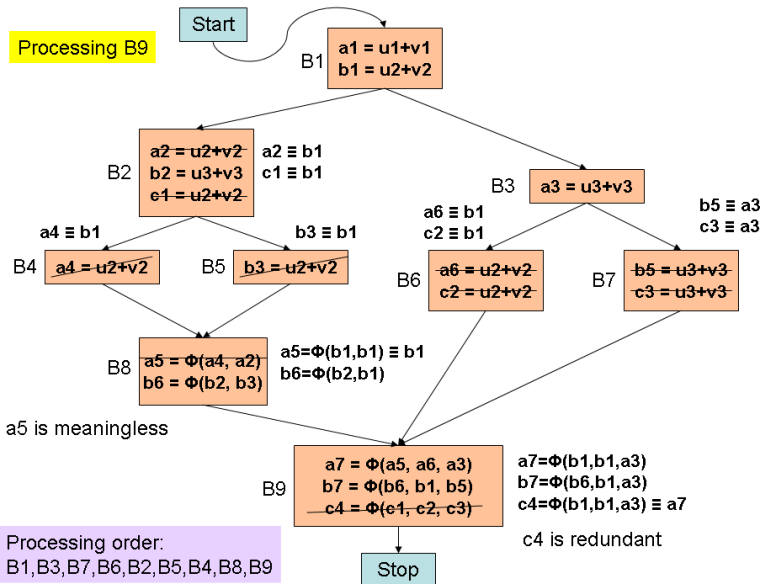
SSA Value-numbering Example - 1.7



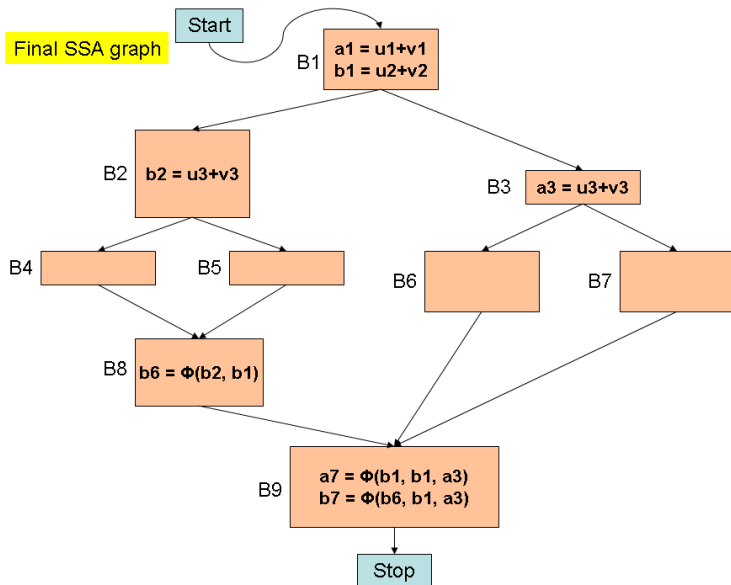
SSA Value-numbering Example - 1.8



SSA Value-numbering Example - 1.9



SSA Value-numbering Example - 1.10



SSA Value-Numbering Algorithm

```
function SSA-Value-Numbering (Block  $B$ ) {  
  Mark the beginning of a new scope;  
  For each  $\phi$ -function  $f$  of the form  $x = \phi(y_1, \dots, y_n)$  in  $B$  do {  
    search for  $f$  in HashTable;  
    //This involves getting the value numbers of the parameters also  
    if  $f$  is meaningless //all  $y_i$  are equivalent to some  $w$   
      replace value number of  $x$  by that of  $w$  in ValnumTable;  
      delete  $f$ ;  
    else if  $f$  is redundant and is equivalent to  $z = \phi(u_1, \dots, u_n)$   
      replace value number of  $x$  by that of  $z$  in ValnumTable;  
      delete  $f$ ;  
    else insert simplified  $f$  into HashTable and ValnumTable;  
  }  
}
```

SSA Value-Numbering Algorithm - Contd.

```
For each assignment  $a$  of the form  $x = y + z$  in  $B$  do {  
    search for  $y + z$  in HashTable;  
    //This involved getting value numbers of  $y$  and  $z$  also  
    If present with value number  $n$   
        replace value number of  $x$  by  $n$  in ValnumTable;  
        delete  $a$ ;  
    else add simplified  $y + z$  to HashTable and  $x$  to ValnumTable;  
}
```

```
For each child  $c$  of  $B$  in the dominator tree do  
//in reverse postorder of DFS over the SSA graph  
    SSA-Value-Numbering( $c$ );  
clean up HashTable after leaving this scope;
```

```
}
```

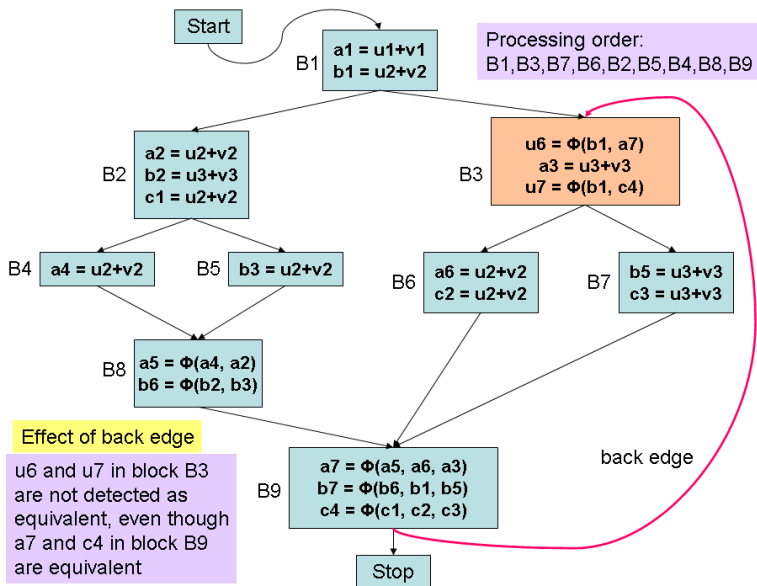
```
//Calling program
```

```
SSA-Value-Numbering(Start);
```

Processing ϕ -instructions

- Some times, one or more of the inputs of a ϕ -instruction may not yet be defined
 - They may reach through the back edge of a loop
 - Such entries will not be found in the *ValnumTable*
 - For example, see *a7* and *c4* in the ϕ -functions in block B3 (next slide); their equivalence would not have been decided by the time B3 is processed
 - Simply assign a new value number to the ϕ -instruction and record it in the *ValnumTable* and the *HashTable* along with the new value number and the defining variable
- If all the inputs are found in the *ValnumTable*
 - Replace the inputs by the respective entries in the *ValnumTable*
 - Now, check whether the ϕ -instruction is either *meaningless* or *redundant*
 - If neither, enter the simplified expression into the tables as before

Example: Effect of Back Edge on Value Numbering



Processing ϕ -instructions

Meaningless ϕ -instruction

- All inputs are identical. For example, see block B8
- It can be deleted and all occurrences of the defining variable can be replaced by the input parameter. *ValnumTable* is updated

Redundant ϕ -instruction

- There is another ϕ -instruction in the *same basic block* with exactly the same parameters
- Block B9 has a redundant ϕ -instruction
- Another ϕ -instruction from a dominating block cannot be used because the control conditions may be different for the two blocks and hence the two ϕ -instructions may yield different values at runtime
- *HashTable* can be used to check redundancy
- A redundant ϕ -instruction can be deleted and all occurrences of the defining variable in the redundant instruction can be replaced by the earlier non-redundant one. Tables are updated

Liveness Analysis with SSA Forms

- For each variable v , walk backwards from each use of v , stopping when the walk reaches the definition of v
- Collect the block numbers on the way, and the variable v is *live* at the entry/exit (one or both, as the case may be) of each of these blocks
- In the example (next slide), consider uses of the variable i_2 in B7 and B4. Traversing upwards till B2, we get: B7, B5, B6, B3, B4(IN and OUT points), and OUT[B2], as blocks where i_2 is live
- This procedure works because the SSA forms and the transformations we have discussed satisfy (preserve) the *dominance property*
 - the definition of a variable dominates each use or the predecessor of the use (when the use is in a ϕ -function)
 - Otherwise, the whole SSA graph may have to be searched for the corresponding definition

Liveness Analysis with SSA Forms - Example

