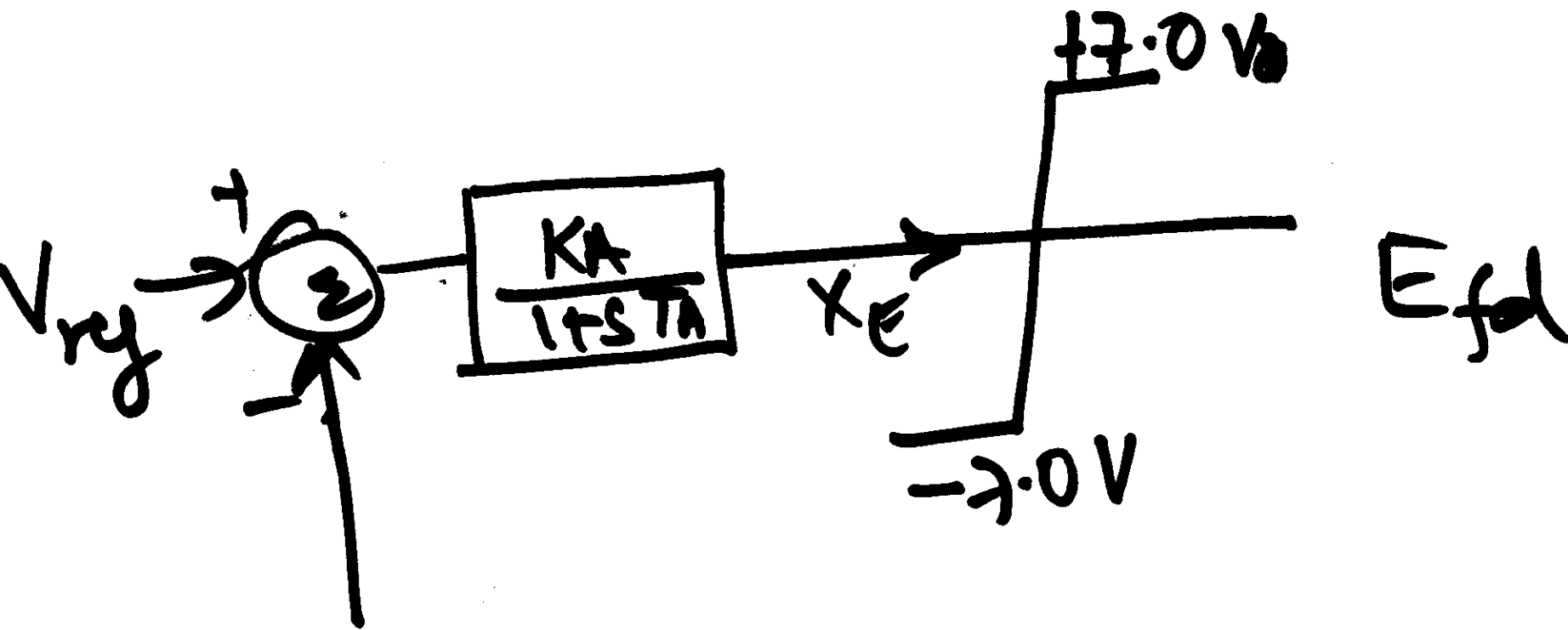


$$\frac{d\psi_d}{dt} = -\omega\psi_q - \omega_B R_a i_d - \omega_B \cdot V_d$$

$$\frac{dx_{di}}{dt} = -\omega x_{iq} + \omega_B (V_d - E_d)$$

$$\frac{d(\psi_d + x_{di})}{dt} = -\omega(\psi_q + x_{iq}) - \omega_B R_a i_d - \omega_B E_d.$$

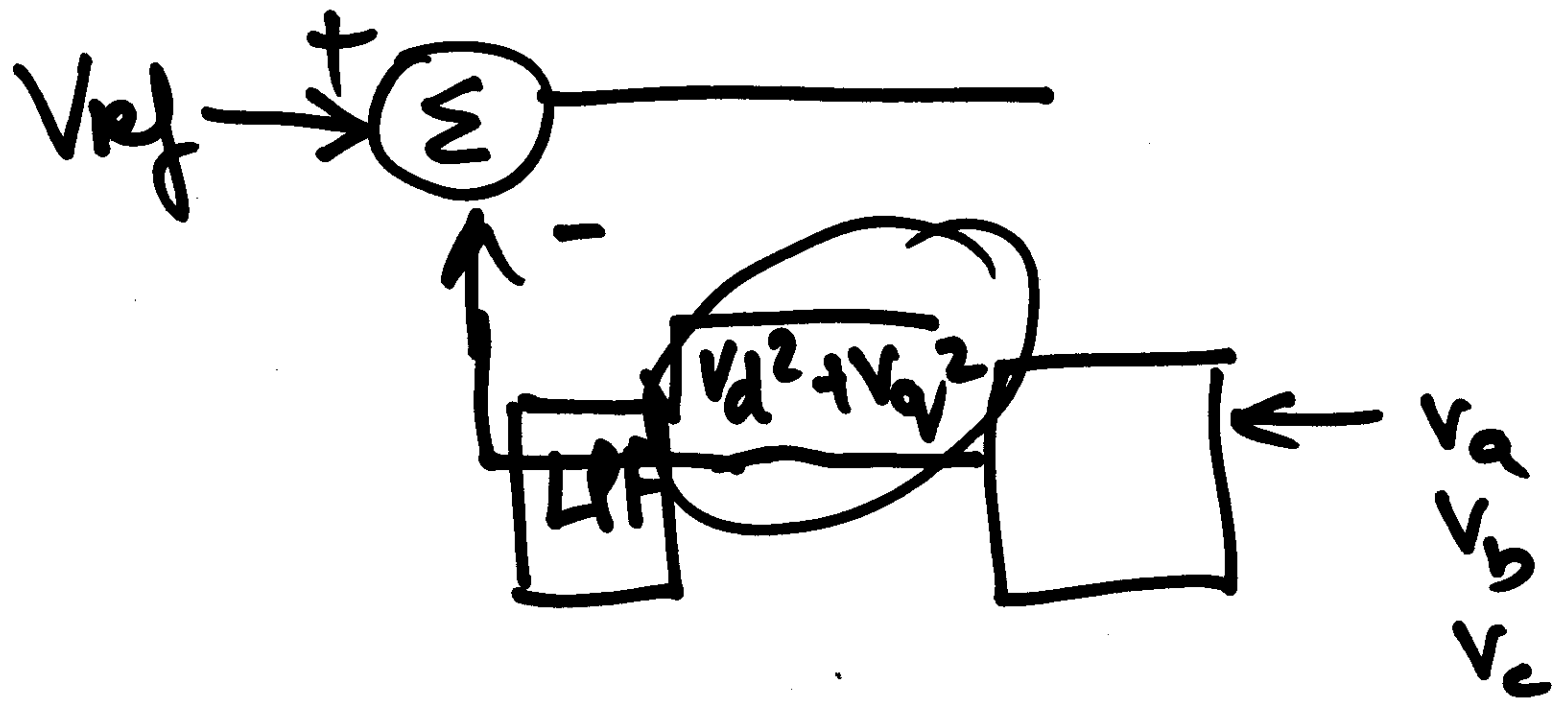


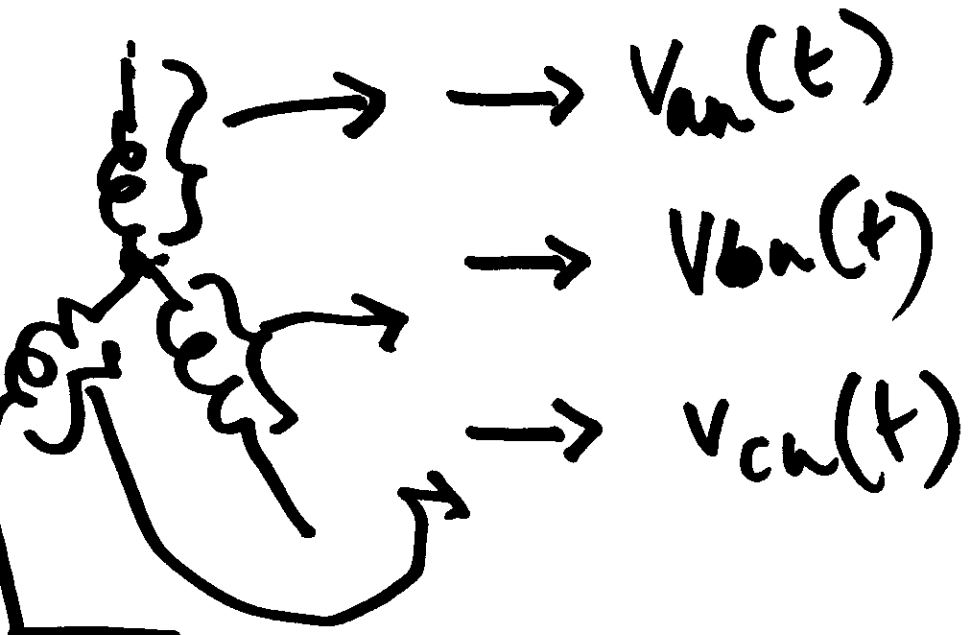
$$X_E \neq E_{fed}$$

$$X_E = E_{fed} \}$$

$$-7V < X_E < +7V$$

$$\underline{V} = \sqrt{V_d^2 + V_q^2}$$





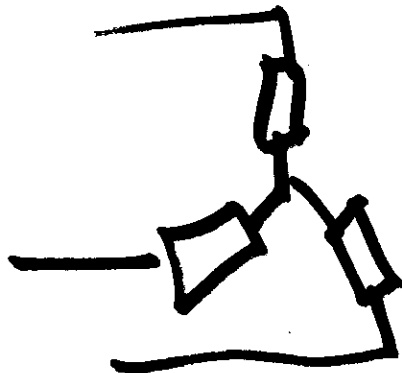
$\sqrt{V_{as}^2 + V_{ae}^2}$

$$V_{as} = \frac{1}{T} \int_{t-T}^t v_{an}(t) \sin \omega_0 t \, dt.$$

$$V_{ae} = \frac{1}{T} \int_{t-T}^t v_{an}(t) \cos \omega_0 t \, dt$$

$$\begin{aligned}
 P(t) &= v_a i_a + v_b i_b + v_c i_c. \\
 &= v_d i_d + v_q i_q + v_o i_o.
 \end{aligned}$$

$$Q(t) \triangleq \frac{v_d i_q - v_q i_d}{} !$$



$$\overset{\text{CP}}{\overset{\text{CP}}{\overset{\text{CP}}{\text{CP}}}} V = \left\{ [v_a \quad v_b \quad v_c] \begin{bmatrix} v_a \\ v_b \\ v_c \end{bmatrix} \right\}^{1/2}$$

$$\left\{ [v_a \quad v_b \quad v_c] I \begin{bmatrix} v_a \\ v_b \\ v_c \end{bmatrix} \right\}^{1/2}$$

$$V = \sqrt{V_a^2 + V_b^2 + V_c^2}$$

$$= \sqrt{V_d^2 + V_q^2 + V_0^2}.$$

$$V = \sqrt{V_d^2 + V_q^2} \}.$$

→ V_a

→ V_b

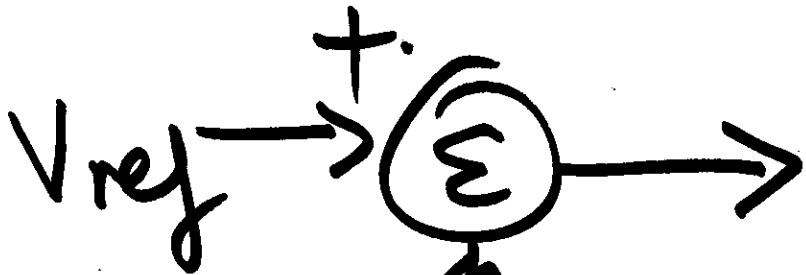
→ V_c

$V =$

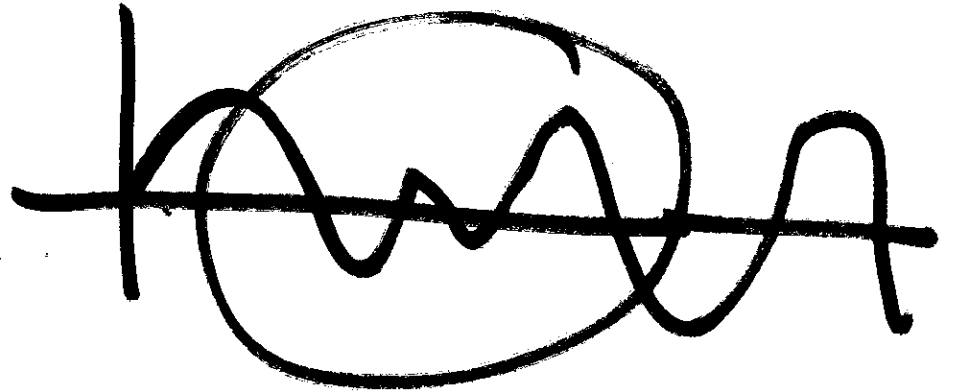
$$\left(\sqrt{V_a^2(t) + V_b^2(t) + V_c^2(t)} \right)$$

$V = \text{const}$

$= \underline{\underline{LL \text{ rms}}}$

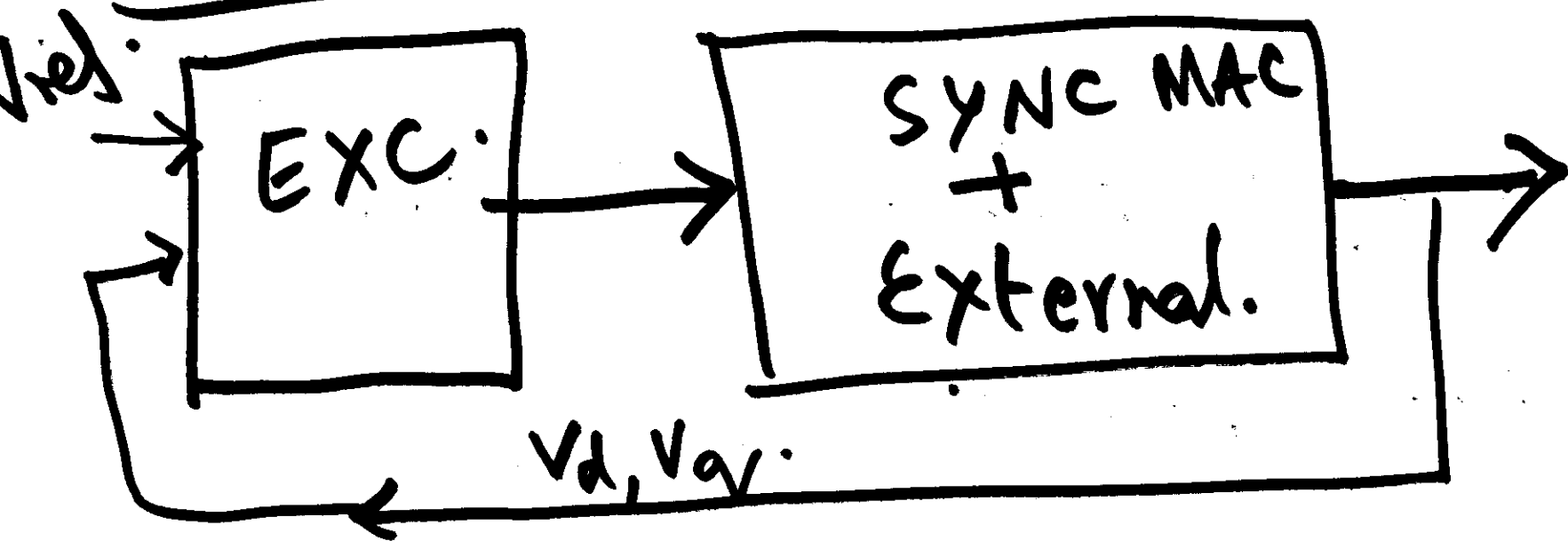


$V = ?$



$$v(t) = \underbrace{V}_{=} \sin \omega t$$

$$\frac{d(\psi_q + x_q i_q)}{dt} = \omega(\psi_d + x_d i_d) - \omega_B R_a i_q - \omega_B E_q$$




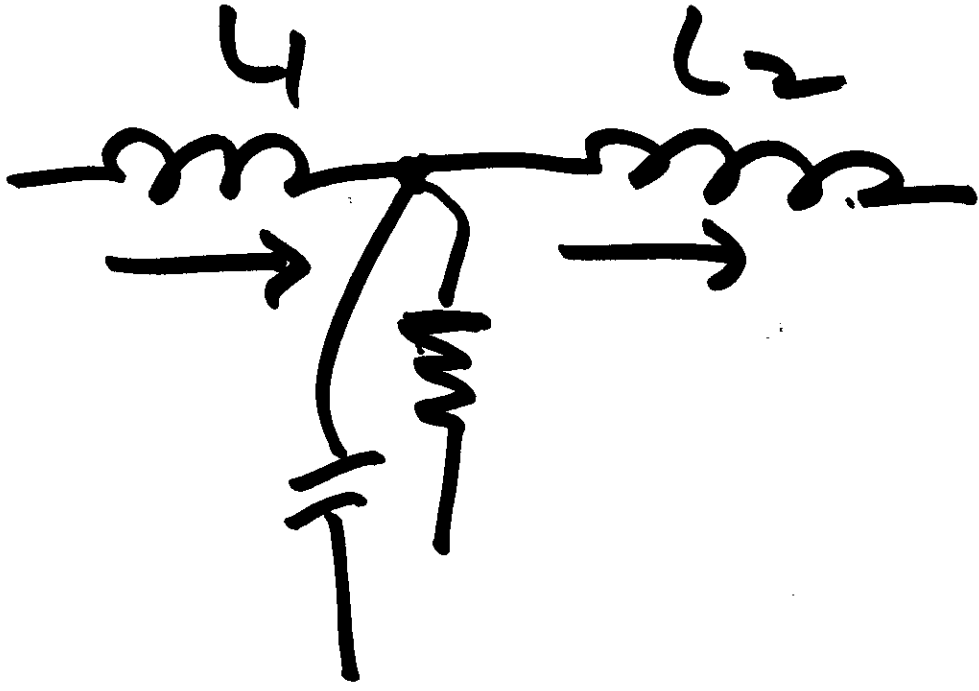
$$\frac{d\theta}{dt} = \omega = \omega_0 + \frac{d\phi}{dt}$$

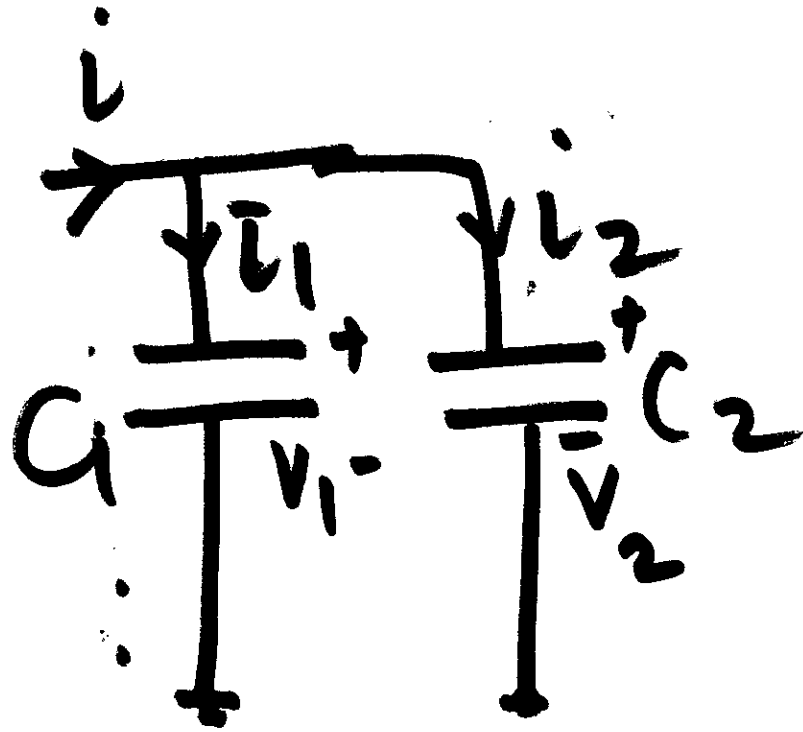
$$E_a = \sqrt{\frac{2}{3}} \cancel{E} \sin(\omega t)$$

$$E_b = \sqrt{\frac{2}{3}} E \sin\left(\omega t - \frac{2\pi}{3}\right)$$

$$E_c = \sqrt{\frac{2}{3}} E \sin\left(\omega t + \frac{2\pi}{3}\right)$$

$$\theta = \omega t + \delta$$






$$\left\{ \begin{array}{l} C_1 \frac{dV_1}{dt} = i_1, \quad C_2 \frac{dV_2}{dt} = i_2 \\ V_1 = V_2 \quad i_1 + i_2 = i \end{array} \right.$$

