

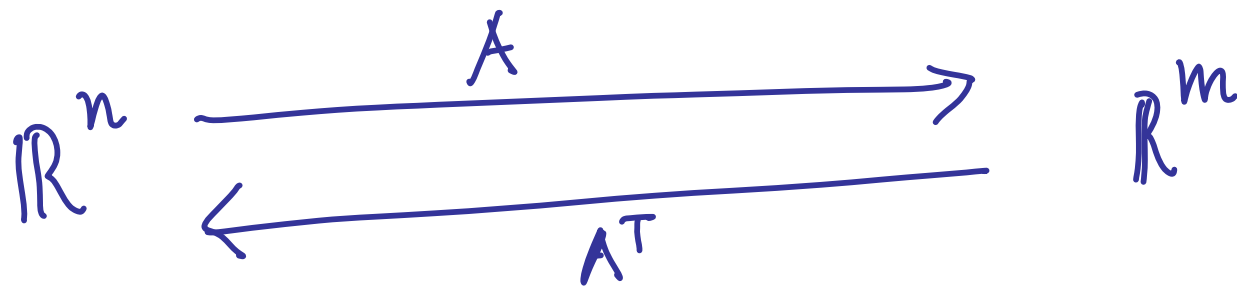
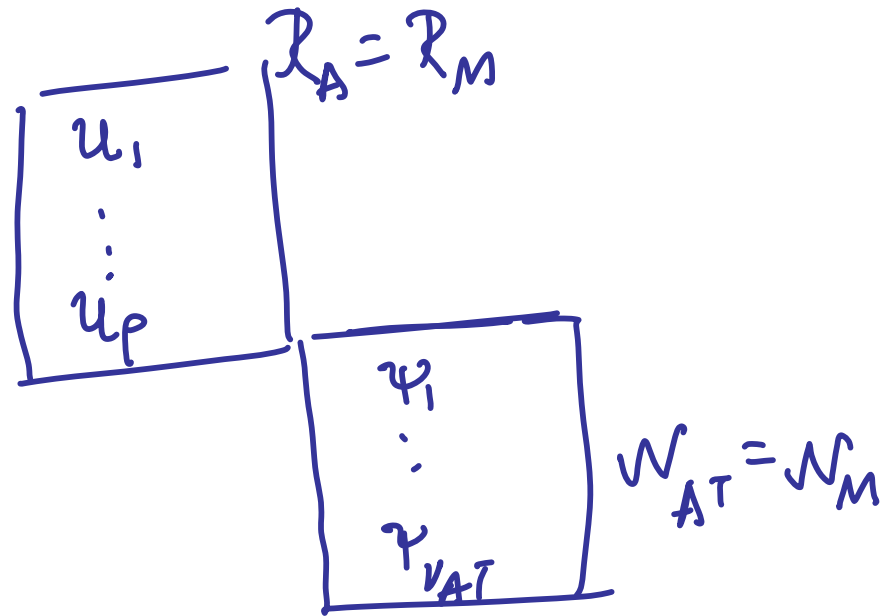
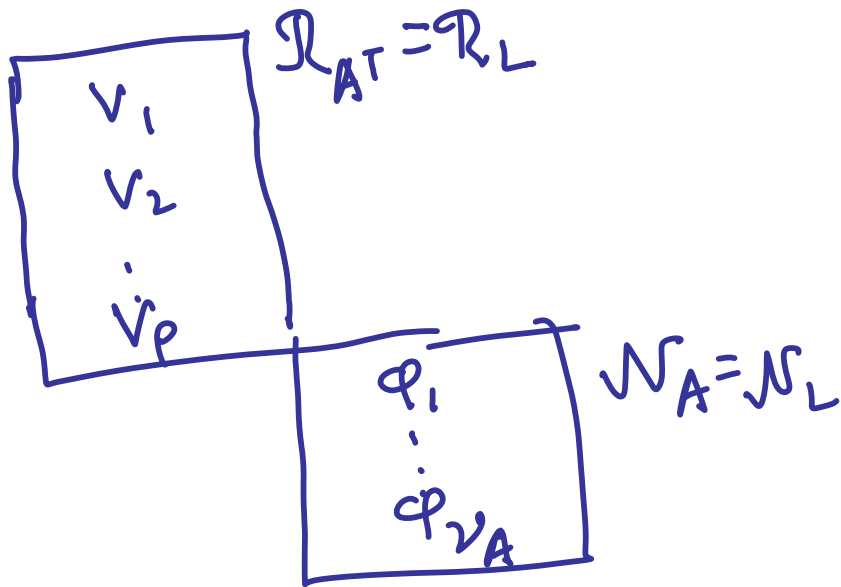
$$A \in \mathbb{R}^{m \times n}$$

Rank  $A = p$ , Nullity of  $A$  is  $\nu_A$

$$L = A^T A \in \mathbb{R}^{n \times n}$$

$$M = A A^T \in \mathbb{R}^{m \times m}$$

PSD



Chose

$v_1, v_2, \dots, v_p$  as the o.n. eigenvectors  
corr to the positive eigenvalues  
of  $L$  arranged as  
 $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_p > 0$

$\varphi_1, \varphi_2, \dots, \varphi_{2A}$  as the o.n. eigenvectors  
corr to the 0 eigenvalue  
of  $L$

$\psi_1, \psi_2, \dots, \psi_{2A^T}$  as the o.n. eigenvectors  
corr. to the 0 eigenvalue  
of  $M$

$u_1, u_2, \dots, u_p$  as  $u_j = \frac{1}{s_j} A v_j$  }  $1 \leq j \leq p$   
where  $s_j = \sqrt{\lambda_j}$

( $\delta_j$  are called singular values of  $A$ )

$$A v_j = \delta_j u_j \quad 1 \leq j \leq p$$

$$A^T u_j = \delta_j v_j \quad 1 \leq j \leq p$$

We used these to get

(I) SVD - Product form:

$$A = U S_A V^T$$

where

$$U = [u_1 \dots u_p \quad \psi_1 \dots \psi_{\nu_{A^T}}] \in \mathbb{R}^{m \times m} \text{ orthogonal matrix}$$

$V = [v_1 \dots v_p \ \varphi_1 \dots \varphi_{n-p}] \in \mathbb{R}^{n \times n}$  orthogonal matrix

$$S_A = \left( \begin{array}{cc|c} s_1 & 0 & \bigcirc \\ 0 & s_p & \bigcirc \\ \hline \bigcirc & \bigcirc & \bigcirc \end{array} \right)_{m \times n}$$

II SVD — Sum form

$$A = \sum_{j=1}^p s_j v_j \otimes u_j$$

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where

$$v_j \otimes u_j = u_j v_j^T \in \mathbb{R}^{m \times n}$$

$m \times n$     $1 \times n$

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Use of these four o.n.-bases to  
analyse the system

$$Ax = b \quad \dots \quad (\underline{I})$$

$$A \in \mathbb{R}^{m \times n}$$

Given  $b \in \mathbb{R}^m$    To find  $x \in \mathbb{R}^n$

s.t.  $Ax = b$  i.e.  $(\underline{I})$  is satisfied

The given  $b \in \mathbb{R}^m$

$u_1, \dots, u_p, \psi_1, \dots, \psi_{v_{A^T}}$  is an onb for  $\mathbb{R}^m$

We can expand  $b$  in terms of this

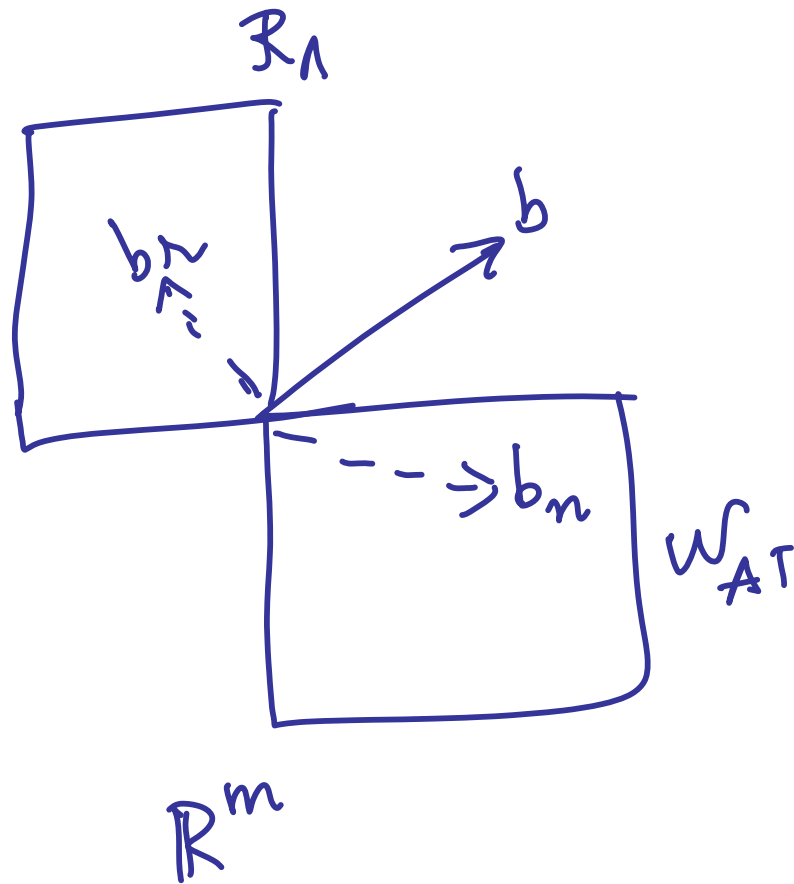
o.n. basis as

$$b = \underbrace{\sum_{j=1}^p (b, u_j) u_j}_{b_R} + \underbrace{\sum_{r=1}^{v_{A^T}} (b, \psi_r) \psi_r}_{b_N}$$

$b_R \in \mathcal{R}_A$ ,  $b_N \in \mathcal{N}_{A^T}$   
orthogonal } orthogonal projection  
proj of  $b$  onto  $\mathcal{R}_A$  } of  $b$  onto  $\mathcal{N}_{A^T}$

Pythagoras Theorem

$$\|b\|^2 = \|b_R\|^2 + \|b_N\|^2$$



$$b = \sum_{j=1}^p (b, u_j) u_j + \sum_{\lambda=1}^{r_{AT}} (b, \psi_\lambda) \psi_\lambda \quad \dots \quad (\text{---})$$

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To find  $x \in \mathbb{R}^n$

for  $\mathbb{R}^n$  we have onb

$v_1, v_2, \dots, v_p, \varphi_1, \dots, \varphi_{n-p}$

The  $x$  we are looking for must be  
a l.c. of these basis vectors.

Hence  $x$  must be of the form

$$x = \sum_{j=1}^p \alpha_j v_j + \sum_{r=1}^{n-p} \beta_r \varphi_r$$

The vector  $x$  is known the moment  
we know  $\alpha_1, \dots, \alpha_p, \beta_1, \dots, \beta_{n-p}$



We have to find these scalars in  
such a way that  $Ax = b$

$Ax$  is of the form

$$Ax = A \left( \sum_{j=1}^p \alpha_j v_j + \sum_{\ell=1}^{v_\ell} \beta_\ell \varphi_\ell \right)$$

$$= \sum_{j=1}^p \alpha_j Av_j + \underbrace{\sum_{\ell=1}^{v_\ell} \beta_\ell A\varphi_\ell}$$

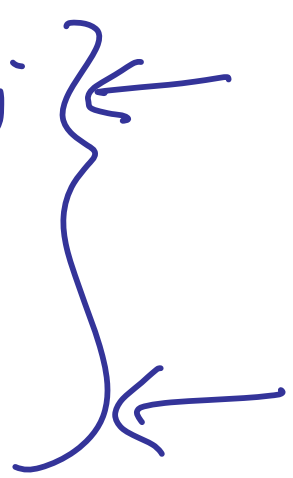
$$= \sum_{j=1}^p \alpha_j \beta_j u_j$$



We have

$$b = \sum_{j=1}^p (b, u_j) u_j + \sum_{\lambda=1}^{v_{AT}} (b, \psi_\lambda) \psi_\lambda$$

and

$$Ax = \sum_{j=1}^p \alpha_j s_j u_j$$


To find  $x$  s.t.

$$Ax = b$$

We need

$$\sum_{j=1}^p \alpha_j s_j u_j = \sum_{j=1}^p (b, u_j) u_j + \sum_{\lambda=1}^{v_{AT}} (b, \psi_\lambda) \psi_\lambda$$

$$\Rightarrow \underbrace{\sum_{j=1}^p \left\{ \alpha_j s_j - (b, u_j) \right\} u_j}_{\in \mathcal{R}_A} = \underbrace{\sum_{\lambda=1}^{v_{AT}} (b, \psi_\lambda) \psi_\lambda}_{\in \mathcal{N}_{AT}}$$

$\in \mathcal{R}_A \because u_1, \dots, u_p$   
 is an o.n.-basis  
 for  $\mathcal{R}_A$

$\in \mathcal{N}_{AT} \because \psi_1, \dots, \psi_{v_{AT}}$   
 is an o.n.-basis  
 for  $\mathcal{N}_{AT}$

$$\Rightarrow \left\{ \begin{array}{l} \sum_{\lambda=1}^{v_{AT}} (b, \psi_\lambda) \psi_\lambda = \mathbf{0}_m \text{ and } \dots \text{ (1)} \\ \sum_{j=1}^p \left( \alpha_j s_j - (b, u_j) \right) u_j = \mathbf{0}_m \text{ } \dots \text{ (2)} \end{array} \right.$$

From all (1) tells that we can  
get  $Ax = b$  only if  $b$  satisfies

$$\sum_{\lambda=1}^{v_{AT}} (b, \psi_{\lambda}) \psi_{\lambda} = 0_m$$

$$\Leftrightarrow (b, \psi_{\lambda}) = 0, \quad 1 \leq \lambda \leq v_{AT}$$

(only if  $b \in \mathcal{R}A$ )

[c] (Consistency Condition)

i)  $b \in \mathcal{R}A$  or same as

ii)  $b \perp$  all the vectors in  $\mathcal{N}_{AT}$  or same as

iii)  $b \perp$  any basis in  $N_{AT}$  or same as

$$iv) (b, \psi_r) = 0, \quad 1 \leq r \leq \nu_{AT}$$

SUPPOSE  $b$  satisfies the above  
Consistency condition:

Then (2) gives us

$$\sum_{j=1}^p (\alpha_j s_j - (b, u_j)) u_j = 0_m$$

$u_1, \dots, u_p$  are o.n & hence l.i.

$$\Rightarrow (\alpha_j s_j - (b, u_j)) = 0 \quad 1 \leq j \leq P$$

$$\Rightarrow \alpha_j = \frac{(b, u_j)}{s_j} \quad 1 \leq j \leq P$$

&  $\beta_r$  can be chosen arbitrarily

Therefore the sol.  $x$  must be

of the form

$$x = \sum_{j=1}^P \frac{(b, u_j)}{s_j} v_j + \sum_{r=1}^{v_A} \beta_r \phi_r$$

where  $\beta_1, \dots, \beta_{v_A}$  can be chosen

arbitrarily in  $\mathbb{R}$

Therefore summarizing we get

When  $b \in \mathbb{R}^m$  satisfies

$$(b, \psi_r) = 0, \quad 1 \leq r \leq \nu_{AT} \quad \text{--- (C)}$$

then

$$Ax = b$$

has a sol and any solution  
must be of the form

$$x = \sum_{j=1}^p \frac{(b, u_j)}{\Delta_j} v_j + \sum_{r=1}^{v_A} \beta_r \varphi_r$$

where  $\beta_r \in \mathbb{R}$ ,  $1 \leq r \leq v_A$  can be chosen arbitrarily

The arbitrariness in the sol. is due to the  $\beta_1, \dots, \beta_{v_A}$

Hence if  $v_A = 0$  i.e.  $\rho = n$

then there is no arbitrariness  
and we have UNIQUE sol given by



$$\boxed{x = \sum_{j=1}^{p(=n)} \frac{(b, u_j)}{\lambda_j} v_j}$$

If  $v_A \neq 0$  then  $p < n$  and we have INFINITE-y sol.  $\therefore \beta_1, \dots, \beta_{v_A}$  can be chosen arbitrary

All these inf. sol are of the form  $x_A$

$$x = \underbrace{\sum_{j=1}^p \frac{(b, u_j)}{\lambda_j} v_j}_{\in \mathcal{R}_A} + \underbrace{\sum_{r=1}^{v_A} \beta_r \varphi_r}_{\in \mathcal{N}_A}$$

$x_p \qquad \qquad \qquad x_n$

$$x_R = \sum_{j=1}^p \frac{(b, u_j)}{\Delta_j} v_j \in \mathcal{R}_{AT}$$

$$x_n = \sum_{r=1}^{r_A} \beta_r \Phi_r \in \mathcal{N}_A$$

Pythagoras theorem

$$\|x\|^2 = \|x_R\|^2 + \|x_n\|^2$$

Hence the sol. with the least length  
is obtained when  $x_n = \theta_n$  i.e. when

$$\beta_1 = \dots = \beta_{r_A} = 0$$

This sol is called the OPTIMAL sol.

$$x_{OPT} = \sum_{j=1}^p \frac{(b, u_j)}{\Delta_j} v_j$$

Summarize :  $A \in \mathbb{R}^{m \times n}$

If  $b \in \mathbb{R}^m$  satisfies

$$(b, \psi_{\Omega}) = 0, \quad 1 \leq \Omega \leq \nu_{AT} \quad \text{--- (G)}$$

then the system

$$Ax = b$$

HAS A SOLUTION

i) The solution is unique if

$$p = n$$

UNIQUE

And the unique sol is given by

$$x = \sum_{j=1}^{p(=n)} \frac{(b, u_j)}{\Delta_j} v_j$$

ii)

If  $p < n$  then there are infinite number of solutions

And they are all of the form

Inf  
sol

$$x = \sum_{j=1}^p \frac{(b, u_j)}{\Delta_j} v_j + \sum_{r=1}^{n-p} \beta_r \phi_r$$

where  $\beta_r \in \mathbb{R}$ ,  $1 \leq r \leq r_A$ .

Among these solutions the solution having least length is called the OPTIMAL sol & is denoted by  $x_{OPT}$

and we have

$$x_{OPT} = \sum_{j=1}^{P(<n)} \frac{(b, u_j)}{s_j} v_j$$

Thus we have a complete analysis of the system

$$Ax = b$$

In terms of the bases we  
have chosen in the case when  
 $b$  satisfies the consistency  
conditions

We next look at the case

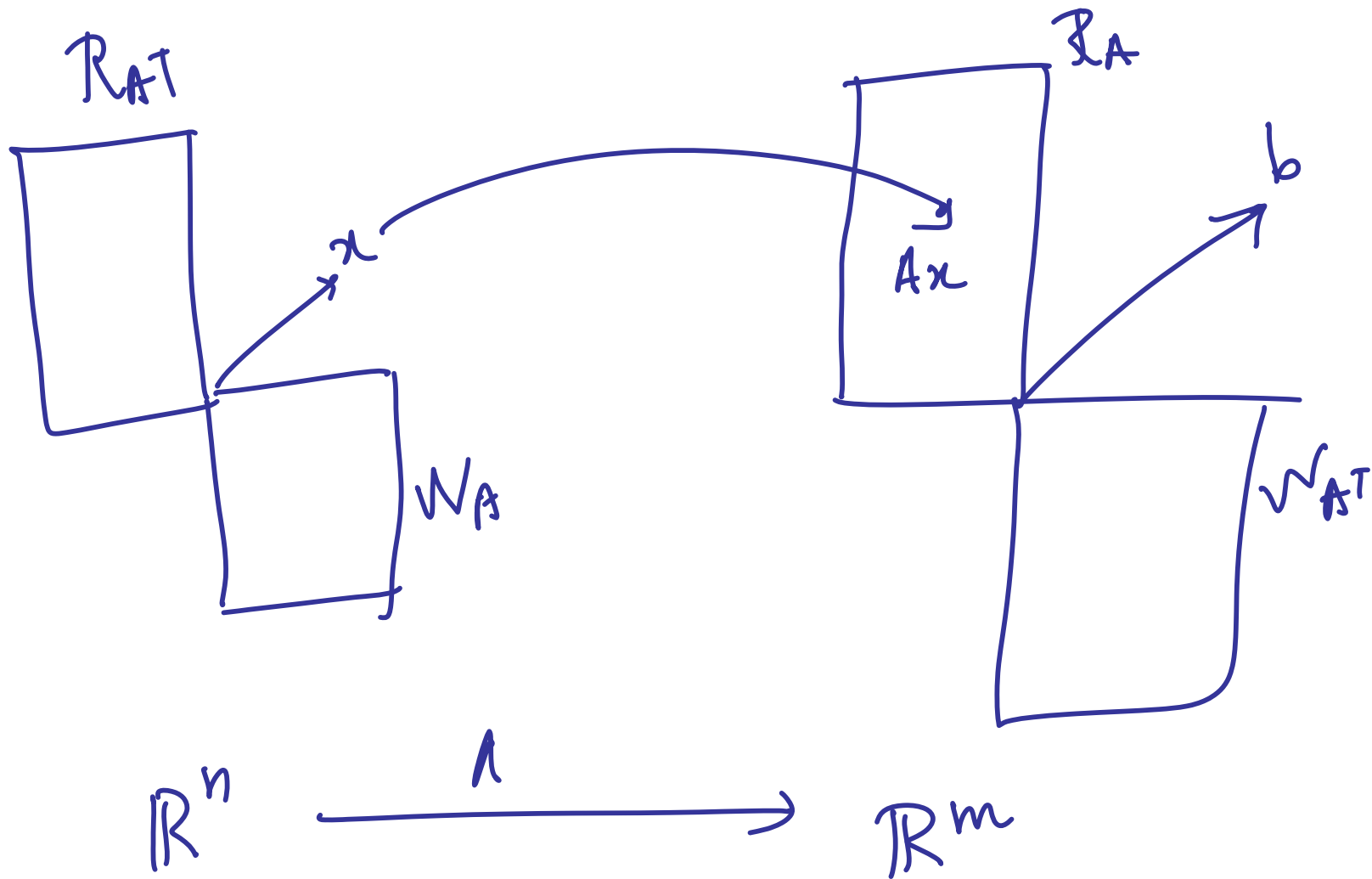
when  $b \in \mathbb{R}^m$  DOES NOT satisfy

the consistency condition.

What does it mean to say  
that  $b$  does not satisfy  
consistency condn.

$b$  satisfies  $(C)$  means  $b \in \mathcal{P}_A$

$b$  does not satisfy  $(C)$  means  $b \notin \mathcal{P}_A$





$b \notin \mathcal{R}_A$  means

for any  $x \in \mathbb{R}^n$  we cannot get  $Ax = b$

Therefore

$$b - Ax \neq 0_m \text{ for any } x \in \mathbb{R}^n$$

This means

$$\|b - Ax\|^2 > 0$$

$$e_b(x) = \|b - Ax\|^2$$

Square error  
of taking  $x$   
as a possible  
sol for  $Ax = b$ .

We would like this error to be minimum.

If  $x_l \in \mathbb{R}^n$  is s.t. this error is min we call it Least Square sol for  $Ax = b$

Def  $x_l \in \mathbb{R}^n$  is called Least Square sol for  $Ax = b$  if

$$\|b - Ax_l\|^2 \leq \|b - Ax\|^2 \quad \forall x \in \mathbb{R}^n$$

$$\lambda \in \quad e_b(x_\lambda) \leq e_b(x) \quad \forall x \in \mathbb{R}^n$$