

# Homog System

Plays an imp role

- 1) in deciding the uniqueness  
of the sol of N.H.S
- & 2) finding all sol of N.H.S  
knowing one particular  
sol of the N.H.S

## MAIN TOOL

Elementary Row Operations  
(ERO)

## ERO of Type 1

### Row Exchange

Keeps all but two rows unaltered  
& Interchanges the position of  
these two rows

If we interchange  $i^{\text{th}}$  row &  $j^{\text{th}}$  row  
positions we shall denote this by  $R_{ij}$

### Example

$$A = \begin{pmatrix} 0 & 1 & 2 \\ 3 & 2 & 1 \end{pmatrix} \xrightarrow{R_{12}} \begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} = A_1$$

$$A \in \mathbb{F}^{m \times n} \xrightarrow{R_{ij}} A_1$$

## Some Simple Properties of ERO of Type I

i) ERO of Type I is "invertible"

$$\& (R_{ij})^{-1} = R_{ij} \text{ an ERO of Type I}$$

$$A \xrightarrow{R_{ij}} A_1$$

$\swarrow R_{ij}$

ii) Let us look at the ex

$$A = \begin{pmatrix} 0 & 1 & 2 \\ 3 & 2 & 1 \end{pmatrix}_{2 \times 3} \xrightarrow{R_{12}} \begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} = A_1$$

Look at the HS corresponding to  $A$  &  $A_1$ .

$$\left. \begin{array}{l} Ax = \theta_2 \\ x_2 + 2x_3 = 0 \\ 3x_1 + 2x_2 + x_3 = 0 \end{array} \right| \quad \left. \begin{array}{l} A_1 x = \theta_2 \\ 3x_1 + 2x_2 + x_3 = 0 \\ x_2 + 2x_3 = 0 \end{array} \right.$$

So both systems are same  
only the order of the eqns. is changed

Conclusion: The HS  $Ax = \theta_2$  &  $A_1 x = \theta_2$   
have the same set of  
sols

In general if  $A \in \mathbb{F}^{m \times n}$

$$A \xrightarrow{R_{ij}} A_1$$

then the HS  $Ax = \theta_m$  and  $A_1x = \theta_m$   
 have the same set of sols

iii) Ex:  $A = \begin{pmatrix} 0 & 1 & 2 \\ 3 & 2 & 1 \end{pmatrix}_{2 \times 3} \xrightarrow{R_{12}} \begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} = A_1$

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \xrightarrow{R_{12}} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = E$$

Look at

$$\begin{aligned} EA &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 2 \\ 3 & 2 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 3 & 2 & 1 \\ 0 & 1 & 2 \end{pmatrix} = A_1 \end{aligned}$$

$\therefore$  Premultiplication of  $A$  by  $E$   
produced the same effect  
as the ERO

CONCLUSION  $A \in \mathbb{F}^{m \times n}$

$$A \xrightarrow{R_{ij}} A_1$$

Then look at  $I_m \xrightarrow{R_{ij}} E$

Then  $EA = A_1$

ERO of Type 2

Keep all rows except one row unchanged  
(let us say all rows except  $j^{\text{th}}$  row)

are kept unchanged)

To the  $j^{\text{th}}$  row add  $\alpha$  times the  $i^{\text{th}}$  Row

We write this as

$$A \xrightarrow{R_j + \alpha R_i} A_1 \quad \alpha \in \mathbb{F}$$

Example

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 3 & 1 & 2 \end{pmatrix}_{3 \times 3} \xrightarrow{R_3 + 2R_1} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 5 & 3 & 2 \end{pmatrix} = A_1$$

Simple Properties of ERO type 2

i) ERO of Type 2 is invertible

$$(R_j + \alpha R_i)^{-1} = R_j + (-\alpha) R_i$$

Ex

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 3 & 1 & 2 \end{pmatrix} \xrightarrow{R_3 + 2R_1} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 5 & 3 & 2 \end{pmatrix} = A_1$$

$R_3 - 2R_1$

The inverse of an ERO  
of Type 2 is again an ERO  
of Type 2

ii) Ex:

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 3 & 1 & 2 \end{pmatrix} \xrightarrow{R_3 + 2R_1} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 5 & 3 & 2 \end{pmatrix} = A_1$$

HS corr. to  $A$  &  $A_1$

$$\underline{Ax = 0}$$

$$\begin{aligned} x_1 + x_2 &= 0 \\ 2x_1 + x_3 &= 0 \\ 3x_1 + x_2 + 2x_3 &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\}$$

$$\underline{A_1 x = 0}$$

$$\begin{aligned} x_1 + x_2 &= 0 \\ 2x_1 + x_3 &= 0 \\ 5x_1 + 3x_2 + 2x_3 &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\}$$

The two HS  $Ax = 0$  &  $A_1 x = 0$   
have the same set of solution

In general

$A \in F^{m \times n}$

$$A \xrightarrow{R_3 + \alpha R_1} A_1$$

Then the HS  $Ax = \theta_m \wedge A_1x = \theta_m$   
have the same set of solns.

iii) Example

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 3 & 1 & 2 \end{pmatrix}_{3 \times 3} \xrightarrow{R_3 + 2R_1} \begin{pmatrix} 1 & 1 & 0 \\ 2 & 0 & 1 \\ 5 & 3 & 2 \end{pmatrix} = A_1$$

$$I_3 \xrightarrow{R_3 + 2R_F} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix} = E$$

Verify

$$EA = A_1$$

The ERO of Type 2 can be

effected by EA when

$$Im \xrightarrow{R_j + \alpha R_i} E$$

### SUMMARIZE

Three Types of EROS

Type 1  $R_{ij}$

Type 2  $R_j + \alpha R_i$

They are invertible  
Inverse is again  
same type ERO

They do not change  
the sol of HS

The effect can be achieved  
by pre multiplying by an "E"

### Third Type ERO

All but one row remain unaltered  
(say except the  $i^{\text{th}}$  row)

Multiply every entry in the  $i^{\text{th}}$   
row by  $\alpha \neq 0$  (where  $\alpha \neq 0$ )

Ex:  $A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & 2 \end{pmatrix}_{2 \times 3} \xrightarrow{(-3)R_2} \begin{pmatrix} 1 & 0 & -1 \\ -6 & -3 & -6 \end{pmatrix} = A_1$

In general  $\alpha R_i$  — (Multiply  $i^{\text{th}}$   
row by  $\alpha$ )

i) Look at the systems

$$Ax = \theta_2$$

$$x_1 - x_3 = 0$$

$$2x_1 + x_2 + 2x_3 = 0$$

$$\left| \begin{array}{l} A_1 x = \theta_2 \\ x_1 - x_3 = 0 \\ -6x_1 - 3x_2 - 6x_3 = 0 \end{array} \right.$$

Both have same set of sol

In general

$$A \in \mathbb{F}^{m \times n}$$

$$A \xrightarrow{\alpha R_i} A_1 \quad (\alpha \neq 0)$$

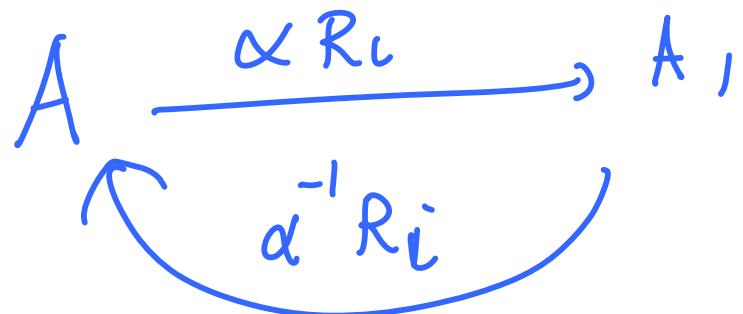
$$\Rightarrow \text{The HS } Ax = \theta_m \quad \& \quad A_1 x = \theta_m$$

both have the same  
set of sol

ii) ERO of Type 3 is  
invertible

$$(\alpha R_i)^{-1} = \alpha^{-1} R_i$$

This is again an ERO of Type 3



iii) Ex:

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & 2 \end{pmatrix} \xrightarrow{(-3)R_2} \begin{pmatrix} 1 & 0 & -1 \\ -6 & -3 & -6 \end{pmatrix} = A_1$$

$2 \times 3$

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \xrightarrow{(-3)R_2} \begin{pmatrix} 1 & 0 \\ 0 & -3 \end{pmatrix} = E$$

$$EA = \begin{pmatrix} 1 & 0 \\ 0 & -3 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 2 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -1 \\ -6 & -3 & -6 \end{pmatrix} \\ = A I$$

The ERO of type 3 can be implemented by premultiplying A by "an E"

All ERO's have

i) They are invertible

Inverse is of the same  
type.

2) They do not alter  
the sol of the HS

3) They can be effected  
by premultiplication of A  
by an E

$$A \in F^{m \times n}$$

$\mathcal{E}$ : The set of all EROs  
on  $m \times n$  matrices

$I_m$ : The  $m \times m$  identity matr.

$$E_0 \in \mathcal{E}$$

$$I_m \xrightarrow{E_0} E \rightarrow \text{elementary matrices}$$

An  $m \times m$  elementary matrix  
is a matrix obtained by

applying an ERO on  $\mathbf{Im}$ .

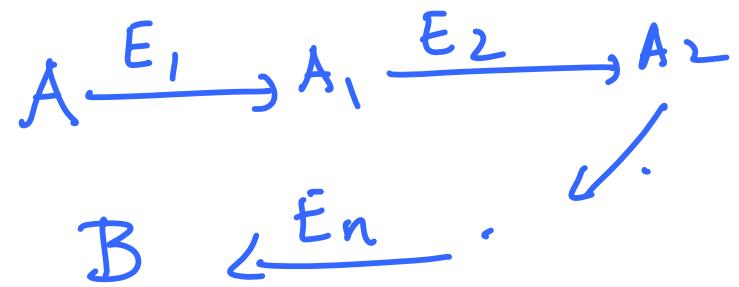
ERO's are effected by  
premultiplying  $A$  by  
elementary matrices

Look at  $\underline{\mathbb{F}^{m \times n}}$

$A, B \in \underline{\mathbb{F}^{m \times n}}$

Suppose there are ERO's  
 $E_1, E_2, \dots, E_k \in \mathcal{E}$

s.t



Then we say

A is Row EQUIVALENT To B

and

symbolically we write

$$A \xrightarrow{R} B$$

Observe the following properties

1)  $A \xrightarrow{R} A$  Reflexivity

2) Since each ERO is invertible  
and again an ERO we see

that

$$A \sim^R B \Leftrightarrow B \sim^R A$$

(Symmetry)

3)  $A \sim^R B$  and  $B \sim^R C$

$$\Rightarrow A \xrightarrow{E_1} \dots \xrightarrow{E_k} B$$

and  
 $B \xrightarrow{f_1} \dots \xrightarrow{f_s} C$

$$\Rightarrow A \xrightarrow{\text{Finite No of } E_i \text{ & } f_j} C$$

$$\Rightarrow A \sim^R C$$

$$A \sim^R B \& B \sim^R C \Rightarrow A \sim^R C$$

(TRANSITIVITY)

Hence Row Equivalence is  
an EQUIVALENCE RELATION  
on  $\mathbb{F}^{m \times n}$

Suppose

$$A \xrightarrow{R} B$$

$$Ax = \theta_m$$

$$Bx = \theta_m$$

Since ERO's do not alter the  
set of sol of the HS we see  
that the two systems have  
same set of sol

Conclusion

$A \xrightarrow{R} B \Rightarrow$  The Systems  
Homog  
 $Ax = 0_m \& Bx = 0_m$   
have the same  
set of sol.

How do we exploit this?

Idea Start from A

Apply suitable ERO's

step by step to A

to get a Row equivalent  
matrix B

Then we can solve

$$Bx = \theta_m$$

instead of  $Ax = \theta_m$

Idea Choose  $ERO'$  so that  
easy to solve  $Bx = \theta_m$ ?