

$W^\perp$ : orthogonal complement  
of a subspace  $W$  of  $\mathbb{R}^k$

Matrix Situation:

$$A \in \mathbb{R}^{m \times n}$$

For  $\mathbb{R}^n$  :  $\mathcal{R}_{A^T}$  and  $\mathcal{N}_A$

For  $\mathbb{R}^m$  :  $\mathcal{R}_A$  and  $\mathcal{N}_{A^T}$

We had  $\begin{cases} \mathcal{N}_A = \mathcal{R}_{A^T}^\perp \\ \mathcal{N}_A^\perp = \mathcal{R}_{A^T} \end{cases}$  & hence

and

$$\begin{cases} \mathcal{N}_{A^T} = \mathcal{R}_A^\perp \\ \mathcal{N}_A = \mathcal{R}_{A^T}^\perp \end{cases}$$

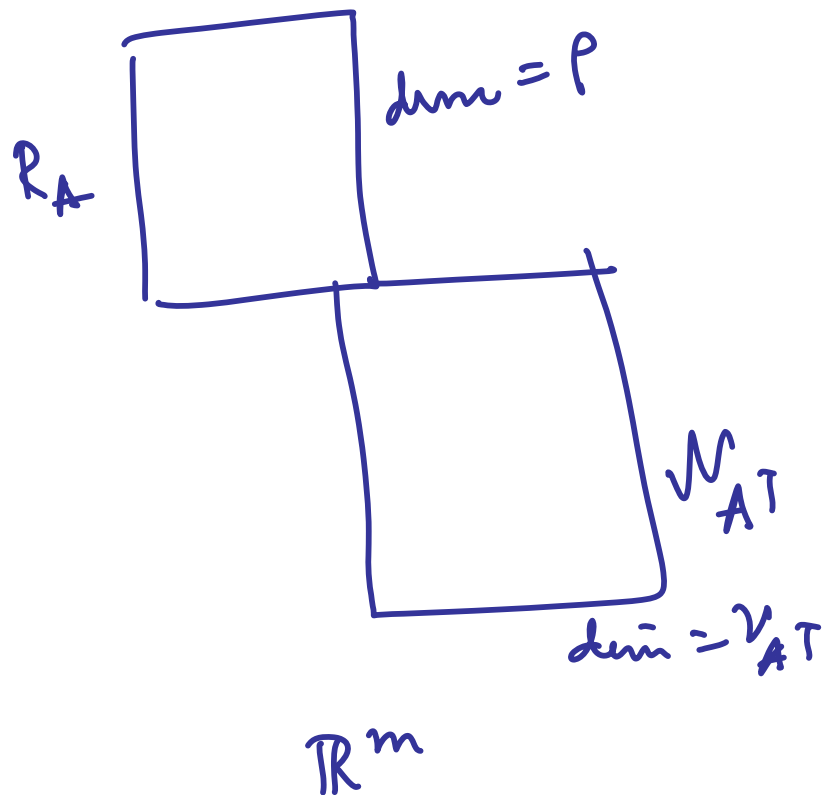
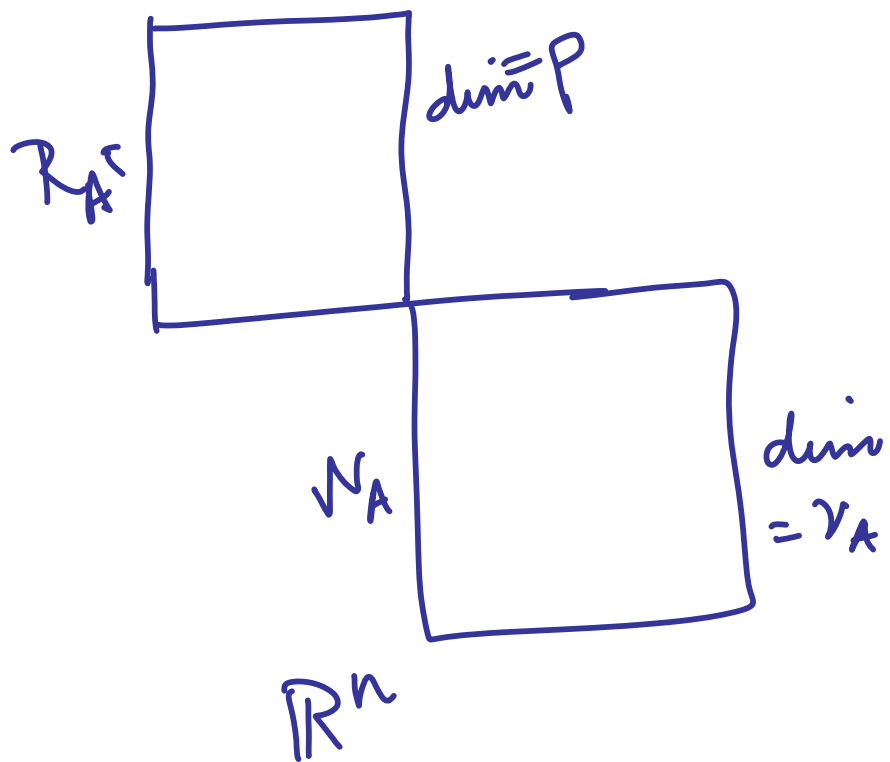
$$\dim \mathcal{R}_{A^T} + \dim \mathcal{R}_{A^T}^\perp = \dim \mathbb{R}^n$$

$$\Rightarrow \rho_{A^T} + \nu_A = n$$

$$\rho_A + \nu_A = n \quad (\text{Rank-Nullity})$$

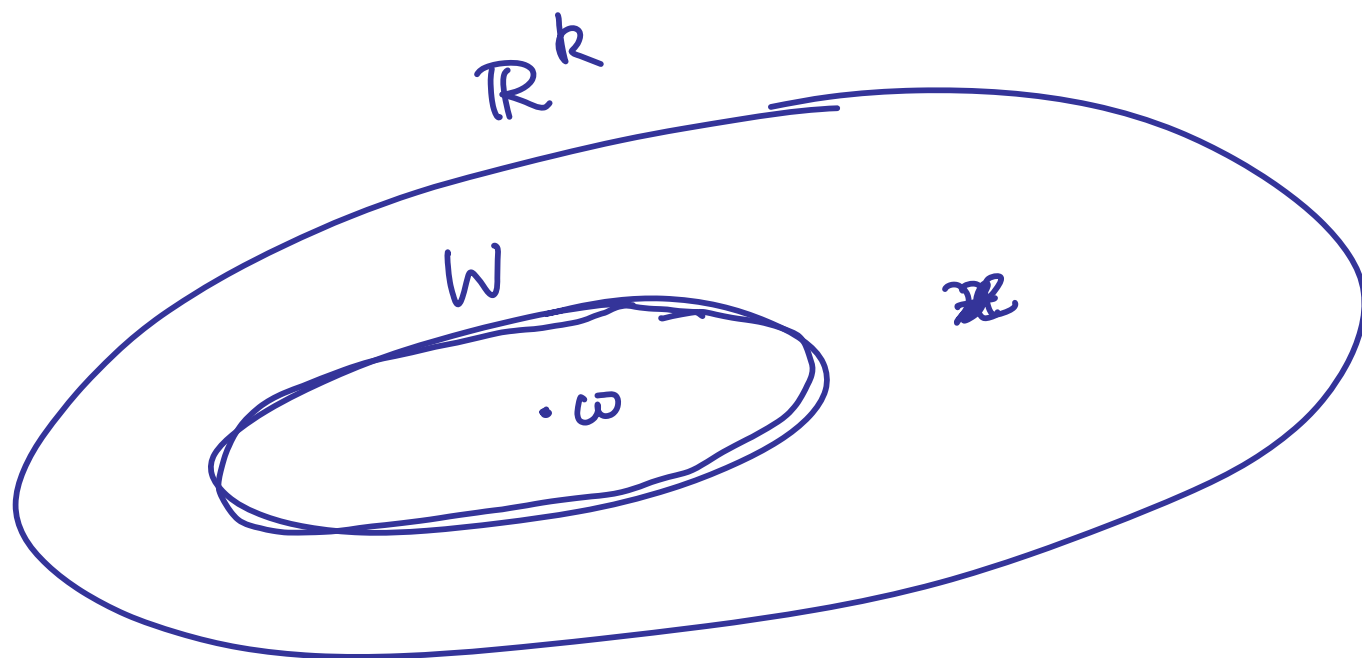
$$\Rightarrow \rho_A = \rho_{A^T}$$

$\Rightarrow$  Rank of a matrix  
= Rank of its transpose



$p = \text{Rank of } A$

# Best Approximation from a subspace



$W$  is a subspace of  $\dim d$  in  $\mathbb{R}^k$

$$x \in \mathbb{R}^k$$

If we take any  $w \in W$  and consider it as an approximation of  $x$

then the <sup>square</sup> error  
 $= \|x - w\|^2$

We would like to minimize this error

This means: We want a  $w_0 \in W$  s.t.

$$\|x - w_0\|^2 < \|x - \underline{w}\|^2 \quad \forall w \in W, w \neq w_0$$

Does there exist such a  $w_0$ ?

$W$  is of dim  $d$

Let  $\varphi_1, \varphi_2, \dots, \varphi_d$  be an o.n.b. for  $W$

Any  $w \in W$  can be expressed as a l.c.

of  $\varphi_1, \varphi_2, \dots, \varphi_d$  as

$$w = \alpha_1 \varphi_1 + \alpha_2 \varphi_2 + \dots + \alpha_d \varphi_d$$

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Square  
Error

$$\|x - w\|^2 = (x - w, x - w)$$

$$= (x - (\alpha_1 \varphi_1 + \dots + \alpha_d \varphi_d), x - (\alpha_1 \varphi_1 + \dots + \alpha_d \varphi_d))$$

$$= (x, x) - \alpha_1 (x, \varphi_1) - \alpha_2 (x, \varphi_2) \dots - \alpha_d (x, \varphi_d) \\ - \alpha_1 (x, \varphi_1) - \alpha_2 (x, \varphi_2) \dots - \alpha_d (x, \varphi_d) \\ + \alpha_1^2 + \alpha_2^2 + \dots + \alpha_d^2$$

$$= \|x\|^2 + \sum_{j=1}^d \left\{ \alpha_j^2 - 2\alpha_j (x, \varphi_j) \right\}$$

$$= \|x\|^2 + \sum_{j=1}^d \left\{ \alpha_j^2 - 2\alpha_j (x, \varphi_j) + (x, \varphi_j)^2 - (x, \varphi_j)^2 \right\}$$

$$= \|x\|^2 + \sum_{j=1}^d (\alpha_j - (x, \varphi_j))^2 - \sum_{j=1}^d (x, \varphi_j)^2$$

For any  $w = \underline{\alpha_1} \varphi_1 + \dots + \underline{\alpha_d} \varphi_d$  in  $W$

the square error is

$$\|x - w\|^2 = \underbrace{\|x\|^2 + \sum_{j=1}^d (\alpha_j - (x, \varphi_j))^2}_{\text{square error}} - \underbrace{\sum_{j=1}^d (x, \varphi_j)^2}_{\text{constant}}$$

The square error is minimum when

$$\underline{\alpha_j = (x, \varphi_j)^2}, \quad 1 \leq j \leq d$$

Hence if we choose

$$w_0 = (x, \varphi_1) \varphi_1 + (x, \varphi_2) \varphi_2 + \dots + (x, \varphi_d) \varphi_d$$

Then we get

$$\|x - w_0\|^2 = \frac{\|x\|^2 - \sum_{j=1}^d (x, \varphi_j)^2}{\|x\|^2 + \sum_{j=1}^d (\alpha_j - (x, \varphi_j))^2 - \sum_{j=1}^d (x, \varphi_j)^2}$$

$\|x - w\|^2$

for any other  $w \in W$

Hence  $w_0 = \frac{\sum_{j=1}^d (x, \varphi_j) \varphi_j}{\|x\|^2 + \sum_{j=1}^d (\alpha_j - (x, \varphi_j))^2 - \sum_{j=1}^d (x, \varphi_j)^2} \in W$

and approximates  $x$  from  $W$  with least square error.

This is called the best approximation of



$x$  from  $W$

OBSERVATION

1) Note  $w_0 = \sum_{j=1}^d (x, \phi_j) \phi_j$

$= x_W$  the orthogonal projection  
of  $x$  onto  $W$

$\therefore$  The best approximation of  $x$  from  $W$   
is the orthogonal projection  $x_W$  of  $x$  onto  $W$

2) Similarly  $x_{W^\perp}$  is the best approximant  
of  $x$  from  $W^\perp$

3) The least <sup>square</sup> error

We have  $x = x_w + x_{w^\perp}$

Best approximant from  $W$  is  $x_w$ .

$$\begin{aligned}\therefore \text{least sq- error} &= \|x - x_w\|^2 \\ &= \|x_{w^\perp}\|^2\end{aligned}$$



$$\|x_{w^\perp}\|^2$$

## Example:

In  $\mathbb{R}^3$  consider  $W = \left\{ x = \begin{pmatrix} a \\ a \\ a \end{pmatrix} : a \in \mathbb{R} \right\}$

Let  $x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3$

Want to find best approximation of  $x$  from  $W$

We know this is given by the orthogonal projection of  $x$  onto  $W$

We have seen (earlier lecture)

$$x_W = \begin{pmatrix} (x_1 + x_2 + x_3)/3 \\ (x_1 + x_2 + x_3)/3 \\ (x_1 + x_2 + x_3)/3 \end{pmatrix}$$

Let us verify this directly

Take any  $w \in W$

$$\text{Let } w = \begin{pmatrix} t \\ t \\ t \end{pmatrix}; t \in \mathbb{R}$$

Square error

$$= \|x - w\|^2 = \left\| \begin{pmatrix} x_1 - t \\ x_2 - t \\ x_3 - t \end{pmatrix} \right\|^2$$

$$= (x_1 - t)^2 + (x_2 - t)^2 + (x_3 - t)^2$$

We want to find  $w$  s.t. this square error is minimum i.e. We want

to find  $t \in \mathbb{R}$  s.t

$(x_1 - t)^2 + (x_2 - t)^2 + (x_3 - t)^2$   
is minimum.

$$E(t) = (x_1 - t)^2 + (x_2 - t)^2 + (x_3 - t)^2$$

$$\begin{aligned} \frac{dE}{dt} &= -2(x_1 - t) - (2)(x_2 - t) - 2(x_3 - t) \\ &= \underline{6t - 2(x_1 + x_2 + x_3)} \end{aligned}$$

$$\frac{dE}{dt} = 0 \text{ when } t = \frac{x_1 + x_2 + x_3}{3}$$

$$\frac{d^2 E}{dt^2} = 6 > 0$$

$$\left. \frac{d^2 E}{dt^2} \right|_{t = \frac{x_1 + x_2 + x_3}{3}} = 6 > 0$$

...  $t = \frac{x_1 + x_2 + x_3}{3}$  is the pt. at which  $E(t)$  is min.

The vector  $w \in W$  corresp to this  $t$  is

$$\begin{pmatrix} (x_1 + x_2 + x_3)/3 \\ (x_1 + x_2 + x_3)/3 \\ (x_1 + x_2 + x_3)/3 \end{pmatrix} = x_w \text{ as found earlier}$$

Note: If  $x \in W$  then  $x_W = x$   
and hence  $x$  is itself its  
best approximant from  $W$

$\mathbb{R}^k$

Matrix Context  $A \in \mathbb{R}^{m \times n}$

1. General Space  $\mathbb{R}^k$

1. We look at  
 $\mathbb{R}^n$  and  $\mathbb{R}^m$

2. Subspace in  $\mathbb{R}^k$

2.  
a) Two subspaces  
 $\mathcal{R}_A$  &  $\mathcal{N}_A$  in  $\mathbb{R}^n$

b) Two subspaces

$R_A$  &  $N_{A^T}$  in  $\mathbb{R}^n$

3. Orthogonal complement  
 $W^\perp$  of a subspace  $W$

3.  $R_{A^T}^\perp, N_A^\perp$  in  $\mathbb{R}^n$

$R_A^\perp, N_{A^T}^\perp$  in  $\mathbb{R}^m$

$N_A = R_{A^T}^\perp, N_{A^T} = R_A^\perp$  Had this

4.  $(W^\perp)^\perp = W$

4.  $R_{A^T} = N_A^\perp$

$R_A = N_{A^T}^\perp$

5.  $\dim W + \dim W^\perp = n$

5.  $\rho_{A^T} + \nu_A = n$

Using together with Rank-Nullity Theorem gave us

$$\rho_A = \rho_{A^T}$$



6. If  $B_W$  is a basis for  $W$   
 and  $B_{W^\perp}$  is a basis for  $W^\perp$   
 then  $B = B_W \cup B_{W^\perp}$  is  
 a basis for  $\mathbb{R}^k$

6. If  $B_{R^T}$  is a basis  
 for  $R^T$  and  
 $B_{R^T}^\perp$  i.e.  $B_{N_A}$  is a  
 basis for  $R^T^\perp = N_A$

then  
 $B_n = B_{R^T} \cup B_{N_A}$   
 is a basis for  $\mathbb{R}^n$

& similarly

$B_{R_A} \cup B_{N_A^T} = B_m$  a basis  
 for  $\mathbb{R}^m$

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7.  $\left( \text{ONB for } W \right) \cup \left( \text{ONB for } W^\perp \right)$   
 $= \text{ONB for } \mathbb{R}^k$

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a)  $\left( \text{ONB for } R^T \right) \cup \left( \text{ONB for } N_A \right)$   
 $= \text{ONB for } \mathbb{R}^n$

$$\begin{aligned} \S \quad x \in \mathbb{R}^k &\Rightarrow x = x_W + x_{W^\perp} \\ &x_W \in W, x_{W^\perp} \in W^\perp \\ &\text{(unique)} \end{aligned}$$

9 Best approximation of  $x$  from  $W$  is  $x_W$

$$\begin{aligned} \text{b) } (\text{ONB for } \mathbb{R}_A) \cup (\text{ONB for } \mathbb{R}_{A^\perp}) \\ = \text{ONB for } \mathbb{R}^m \end{aligned}$$

$$\begin{aligned} \S \quad x \in \mathbb{R}^n \\ \Rightarrow x = x_{\mathbb{R}_A} + x_{\mathbb{R}_{A^\perp}} \\ \text{(unique)} \end{aligned}$$

$$\begin{aligned} b \in \mathbb{R}^m &\Rightarrow \\ b &= b_{\mathbb{R}_A} + b_{\mathbb{R}_{A^\perp}} \\ &\text{(unique)} \end{aligned}$$

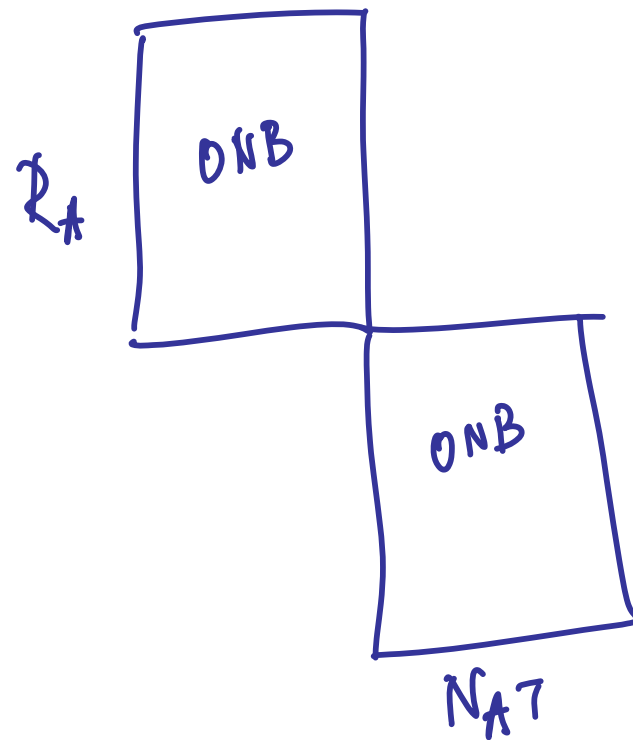
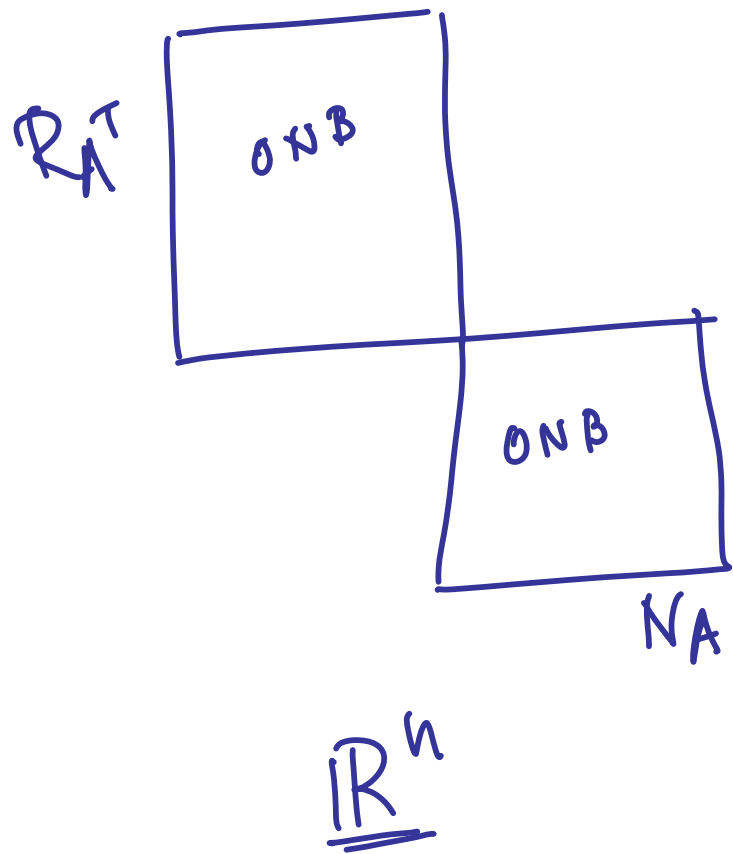
9. Best approximation of  $x$  from  $\mathbb{R}_A$  is  $x_{\mathbb{R}_A}$   
a)  $x \in \mathbb{R}^n$

b) Best app of  $x$  from  $R_A$   
in  $\mathcal{R}_A$   
 $\in \mathcal{R}_A$

10. Least sq. error  
 $\|x_{N^+}\|^2$

10 a) least sq. error  
 $\|x_{N^+}\|^2$

b) least sq error  
 $\|x_{N^+}\|^2$



The hunt for "suitable" bases for these four subspaces leads us to the notion of eigenvalues

and eigenvectors

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Another Problem where  
eigenvalues and eigenvector  
notions appear

System

$$Ax = b$$

$$A \in \mathbb{R}^{n \times n}$$

$$b \in \mathbb{R}^n$$

To find  $x \in \mathbb{R}^n$

Change of Variables:

$$y = Cx \quad C \in \mathbb{R}^{n \times n} \text{ invertible}$$

$$z = Cb$$

$$x = C^{-1}y = Py$$

$$b = C^{-1}z = Pz$$

System

$Ax = b$  becomes

$$APy = Pz$$

$$\Rightarrow P^{-1}APy = z$$

If we can choose  $P$  such that  $P^{-1}AP$  is diagonal then we have

an easy system for  $y$

Can we find  $P$  s.t

$P^{-1}AP$  is diagonal