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Lecture No - 29

### **Earlier Lecture**

- For an optimum design of a Stirling cryocooler, a compromise between the operating and the design parameters may be sought.
- Based on Schmidt's analysis, the variation of O<sub>E</sub> / (p<sub>max</sub>V<sub>T</sub>) and W<sub>T</sub> / (p<sub>max</sub>V<sub>T</sub>) for a few non – dimensional numbers was presented.
- A combined effect of parameters on performance of system as a whole, is given in Walker's optimization charts.

### **Earlier Lecture**

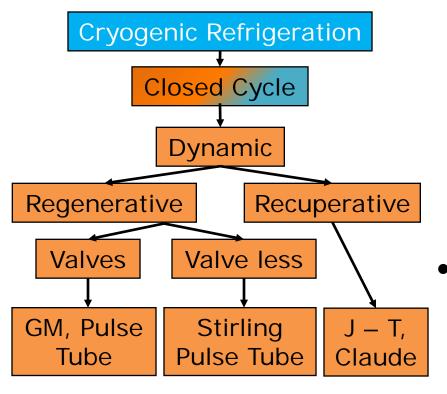
- In order to account for the various losses and to make the analysis more realistic, we have
  - $Q_{E, Design} = 3 X Q_{E, Reqd}$
- In the earlier lecture, a tutorial problem was solved on Stirling cryocooler design using the Walker's Optimization Charts.
- For a given Q<sub>E, Design</sub>, if the dimensions of the piston and expander displacer are very large, the system is designed for two cylinders or more.

### **Outline of the Lecture**

#### **Topic : Cryocoolers**

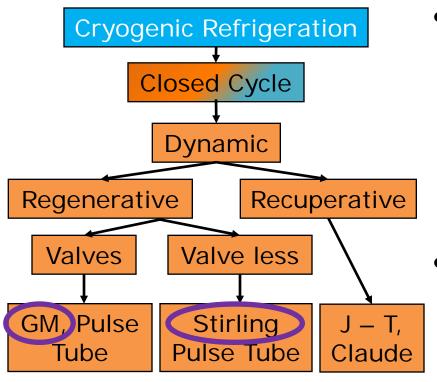
- Gifford McMahon (GM) Cryocooler
- GM and Stirling Cryocooler A comparison
- Working of a GM Cryocooler
- Regenerators, Valve mechanism
- Applications

### Introduction



- In the earlier lecture, we have seen the classification of cryogenic refrigeration.
- The closed cycle division of the same is as shown.

### Introduction



- The working of a valve less, closed cycle, regenerative type, Stirling Cryocooler was discussed.
- On the other hand, the valved system under the regenerative type is the Gifford – McMahon (GM) Cryocooler.

W

V₁

 $V_2$ 

 $Q_c, T_c$ 

G – M

 $\dot{Q}_{0}, T_{0}$ 

## Gifford – McMahon System

- The schematic of a Gifford McMahon (GM) system is as shown in the figure.
- W. E. Gifford and H. O. Mc Mahon were the first to present this idea of introduction of valves in the year 1950.
  - This valve mechanism is used to generate the pressure variation or the pressure pulse.
  - This working cycle was later named as Gifford – McMahon cycle.

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 $V_2$ 

### Gifford – McMahon System

- The sequential opening and closing of these valves generate the required pressure variation or the pressure pulse.
- The timing of the valves in relation to the position of the displacer is vital for optimum operation.
  - Therefore in a GM system, there is a relation between the pressure pulse generated by the valve mechanism and the expander displacer motion.

V₁

 $V_2$ 

 $Q_c, T_c$ 

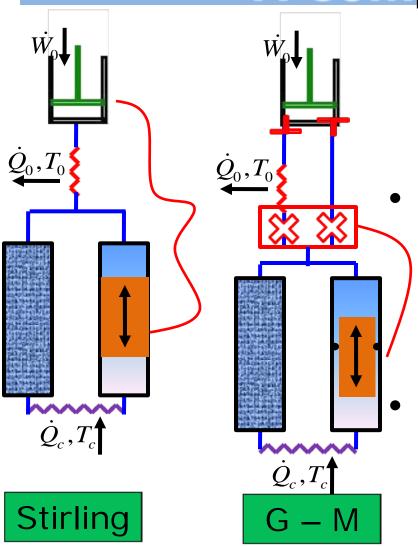
G – M

### Gifford – McMahon System

- Different variations in the valve design for a GM Cryocooler are possible.
- Some of the systems may have one valve each on the high and the low pressure lines.
  - Also, some of the systems may have poppet valves, solenoid valves.
  - Commercially available cryocoolers have rotary valves to control or regulate the flow of the working medium.

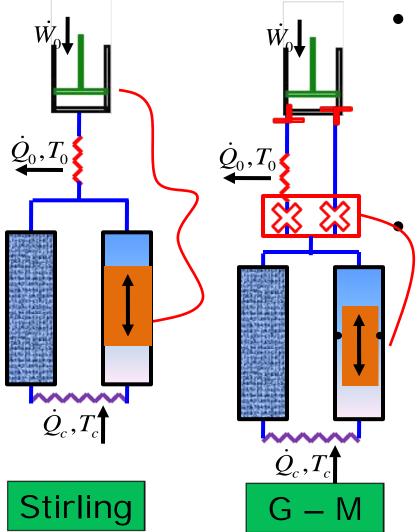
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### **A** Comparison



- At low frequencies, the rubbing seal between the displacer and the cylinder is perfect.
  - The valves facilitates production of any kind of pressure wave as per the requirement of system.

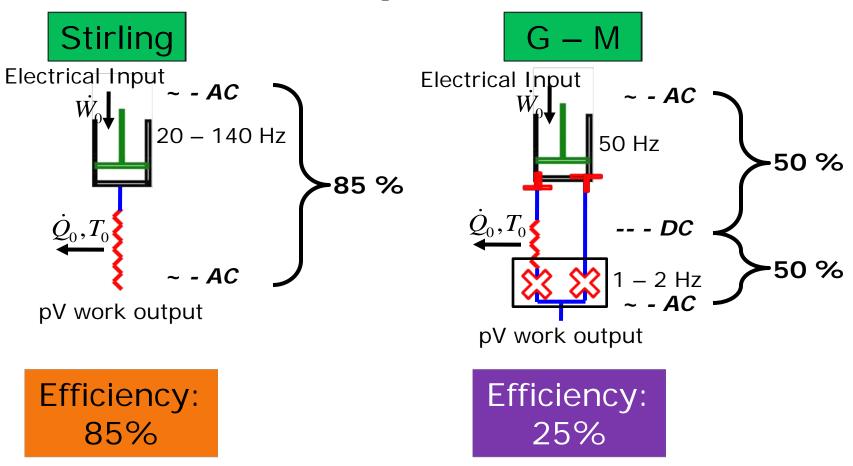
### **A** Comparison



Stirling cryocooler is a high frequency machine where as, a GM Cryocooler is a low frequency machine.

Although, presence of valves deteriorates the system performance, but it is possible to reach much lower temperatures using a GM system as compared to a Stirling system.

### **A** Comparison



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# A Comparison

#### Stirling

- 20 150 Hz frequency.
- Direct connection (Compressor – expander).
- Dry compressor.
- High COP (10 W at 80 K, 350 W).
- Low pressure ratios.
- 20 K using two stages.
- Low power compressors and compact.

#### Gifford - McMahon

- 1 5 Hz frequency.
- Valved connection (Compressor – expander).
- Lubricated compressor.
- Low COP (100 W at 80 K, 4000 W+Q<sub>chill</sub>).
- High pressure ratios.
- 4 K using two stages.
- High power compressors and bulky.

# A Comparison

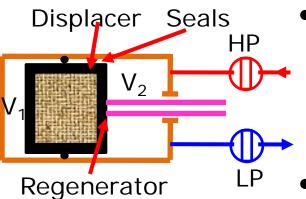
### Stirling

- Miniaturization is possible due to fewer moving parts.
- Suitable for space application.

#### Gifford - McMahon

- Miniaturization is not possible due to the valves.
- Mostly, land based applications.

## Working of GM Cryocooler

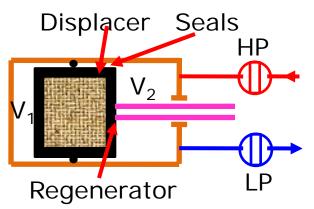


- Consider a displacer housing the regenerator, at BDC position as shown in the figure.
- The cold space (V<sub>1</sub>) and the warm space (V<sub>2</sub>) are as shown.
- In this schematic, both the high (HP) and low (LP) valves are in closed position.
- The seals are provided to reduce the leakage across the displacer.

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V₁

### Working of GM Cryocooler



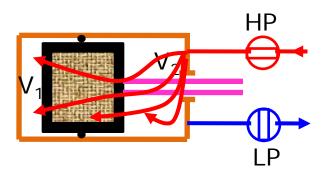
pŧ

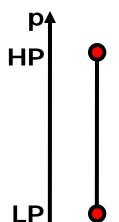
LP

 $\mathbf{V}_{\min}$ 

 The corresponding situation of the cold space (V<sub>1</sub>), when plotted on a pV diagram is as shown in the adjacent figure.

### Working of GM Cryocooler

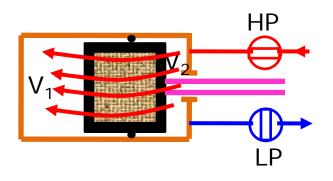


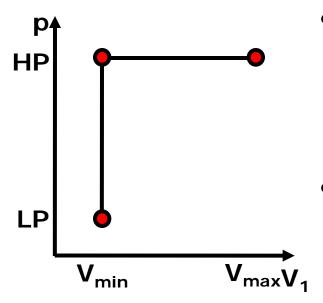


 $\mathbf{V}_{\min}$ 

With the opening of the HP valve, the high pressures gas fills
 V<sub>1</sub> and V<sub>2</sub> spaces at a constant volume as shown in the figure.

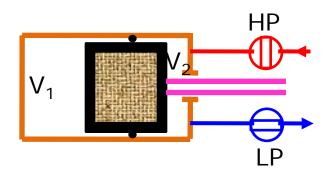
### Working of GM Cryocooler

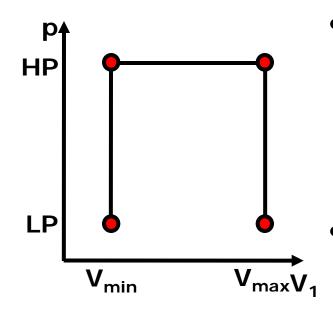




- The displacer moves back displacing the gas from V<sub>2</sub> to V<sub>1</sub> at a constant pressure.
- The cold space volume (V<sub>1</sub>) increases where as, the warm space volume (V<sub>2</sub>) decreases.

### Working of GM Cryocooler

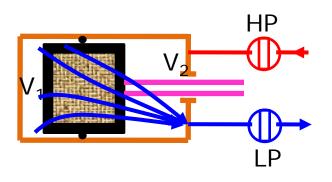


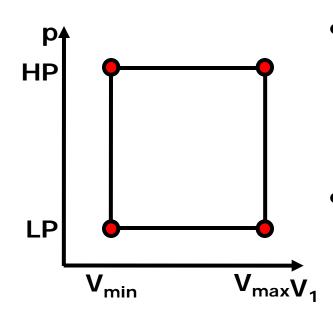


Now, the **HP** valve is closed and **LP** valve is opened. This leads to an expansion of gas, reducing the pressure from **HP** to **LP**.

This expansion produces cold in cold space volume (V<sub>1</sub>).

### Working of GM Cryocooler





- The displacer moves back, reducing the cold space volume (V<sub>1</sub>).
- The cycle continues to produce lower and lower temperatures.

## Multistaging in GM Cryocooler

2<sup>nd</sup> Stage Cold, End



- A single stage GM cryocooler produces a refrigeration effect of 12 W at 80 K, for a 1.2 kW input power.
- In order to reach much lower temperatures, say, in the order of 10 K to 4.2 K, multistaging is done in these systems.

### Multistaging in GM Cryocooler

2<sup>nd</sup> Stage Cold, End



Commercially available two stage GM cryocoolers are capable of reaching temperatures lower than 4.2 K.

### **Components of GM Cryocooler**

- Video of GM cryocooler.
- For the sake of understanding, a demo video of a GM cryocooler at IIT Bombay is shown.
- It is a two stage machine capable of reaching a temperature of 10 K.

## **Components of GM Cryocooler**

- The basic components of any GM cryocooler are as listed below.
  - Helium compressor scroll/reciprocating type.
  - Flex lines HP line, LP line.
  - Regenerator(s) and Displacer(s).
  - Valve mechanism rotary, solenoid, poppet.
  - Cooling arrangements Air or water cooled.

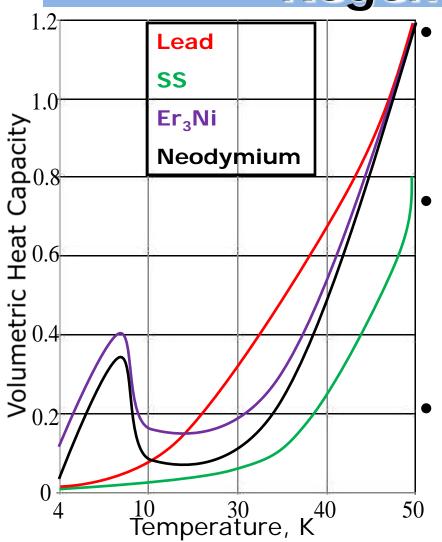
### Regenerators

- The regenerator is the most vital component and is often called as a heart of a cryocooler.
- The major aspects of a regenerator are
  - Dimensions length, diameter.
  - Material Heat capacity, thermal conductivity.
  - Porosity.
  - Working temperature.
  - Heat transfer and minimum pressure drop.

### Regenerators

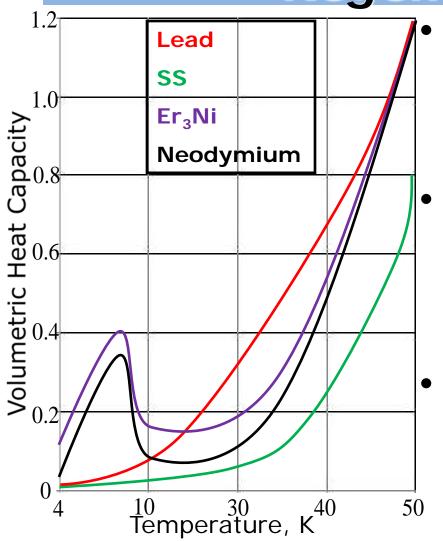
- In general, a material with high heat capacity is chosen as a regenerator material.
- This is because, the energy exchanged between the working gas and the matrix is directly dependent on the relative heat capacity.
- As seen in the earlier lectures, it is important to note that the C<sub>P</sub> of a material decreases with the decrease in the temperature.
- Very often, a combination of various rare earth materials is used as a regenerator material.
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### Regenerators



- The variation of volumetric heat capacity with temperature is as shown.
- Materials like **SS** are not preferred at lower temperatures (~ **30 K**) due to low heat capacity.
  - Materials like **Lead**, **Er<sub>3</sub>Ni** and **Neodymium** exhibit high heat capacities at lower temperatures.

### Regenerators

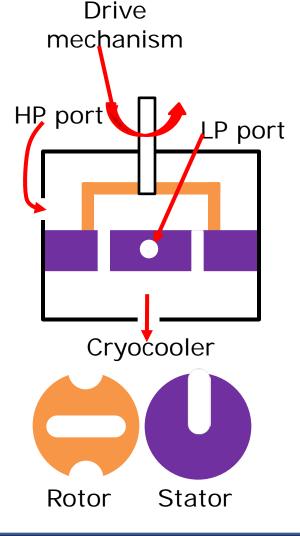


- In single stage GM systems (~ 30 K), SS meshes are used.
- Two stage (~ **10 K**)
  - 1<sup>st</sup> stage: **SS** mesh
  - 2<sup>nd</sup> stage: Lead balls
- Two stage (~ 4.2 K)
  - 1<sup>st</sup> stage: **SS + Lead**
  - 2<sup>nd</sup> stage: Lead + Er<sub>3</sub>Ni.

### **Valve Mechanism**

- As mentioned earlier, the sequential opening and closing of the valve mechanism, generates the required pressure variation or the pressure pulse.
- The rotary valve should operate at an optimum frequency.
- The schematic and the working of a most commonly used rotary valve is explained in the next slide.

## **Valve Mechanism**

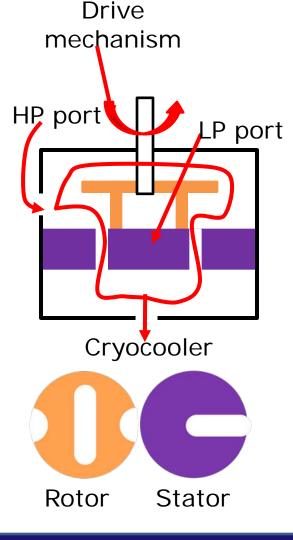


The various parts of a rotary valve are as listed below.

- Drive mechanism
- HP, LP ports
- Rotor, Stator
- The rotor is driven by a drive mechanism, maintaining a perfect seal on the stator.
- The slotted rotor and stator discs, connect the cryocooler to HP and LP lines respectively.

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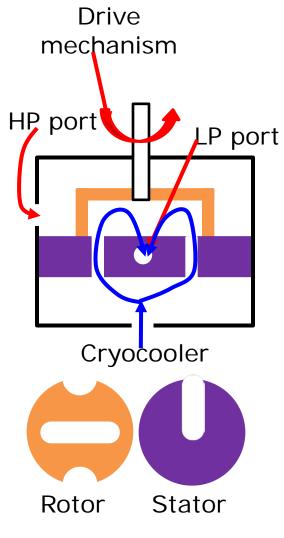
### **Valve Mechanism**



#### **High Pressure Position**

- When the slots on the rotor disc match with the stator as shown, the high pressure gas from the compressor flows to the cryocooler.
- In this position, the LP port is masked/closed.

### **Valve Mechanism**



#### Low Pressure Position

- With the rotation of the rotor disc, at a particular instant, the slots on the rotor disc are masked/closed.
- In this position, the hole in the stator is unmasked/opened, connecting the cryocooler to the LP port, as shown in the figure.

### **Applications**

- GM cryocoolers find applications in the following areas.
  - MRI machines
  - Cryo pumps
  - N<sub>2</sub> liquefiers
  - Cryoprobes
- These machines also find applications in areas like low temperature physics and scientific applications.

### Summary

- W. E. Gifford and H. O. Mc Mahon were the first to present this idea of introduction of valves in the year 1950.
- A GM system has a valve mechanism to control/regulate the flow between the compressor and the regenerator – displacer assembly.
- For an optimum performance, the relation between the pressure pulse generated by the valve mechanism and the expander – displacer motion is vital.

### Summary

- A GM system can reach much lower temperatures as compared to a Stirling system, but may require a high powered compressor due to the inefficiency of the valves.
- Multistaging is done to reach lower temperatures (4.2 K to 10 K).
- The basic components are Helium compressor, Flex lines, Regenerator(s), Displacer(s) and Valve mechanism.

### Summary

- The choice of the regenerator material is dependent on the lowest working temperature of the cryocooler.
- Single stage (~ 30 K), SS mesh.
- 2 stage (~ 10 K), 1<sup>st</sup> stage: SS mesh, 2<sup>nd</sup> stage: Lead balls.
- 2 stage (~ 4.2 K), 1<sup>st</sup> stage: SS mesh + Lead balls, 2<sup>nd</sup> stage: Lead balls + Er<sub>3</sub>Ni balls.
- Commercially available cryocoolers have rotary valves to control/regulate the flow.

- A self assessment exercise is given after this slide.
- Kindly asses yourself for this lecture.

## Self Assessment

- 1. \_\_\_\_ is used to generate the pressure variation in a GM system.
- 2. In a GM cycle, the relation between the pressure pulse and the \_\_\_\_\_ is vital.
- 3. Rubbing seals between the displacer and the cylinder is perfect at \_\_\_\_\_ frequencies.
- In a \_\_\_\_\_ system, miniaturization is not possible due to the valves.
- 5. In GM systems, \_\_\_\_is done in order to reach lower temperatures.
- 6. \_\_\_\_ is the most vital component and is often called as a heart of a cryocooler.
- 7. \_\_\_\_ decreases with the decrease in temperature.

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### Self Assessment

- 8. Materials like \_\_\_\_, \_\_\_\_ and \_\_\_\_\_ exhibit high heat capacities at lower temperatures.
- 9. Rotary valve should operate at an \_\_\_\_\_ frequency.
- 10. Commercially available cryocoolers have \_\_\_\_\_ types of valves to control/regulate the flow.

### Answers

- 1. Valve mechanism
- 2. Expander displacer piston.
- 3. Low
- 4. GM
- 5. Multistaging
- 6. Regenerator
- 7. C<sub>P</sub>
- 8. Lead, Er<sub>3</sub>Ni and Neodymium
- 9. Optimum
- 10.Rotary

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### **Thank You!**

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